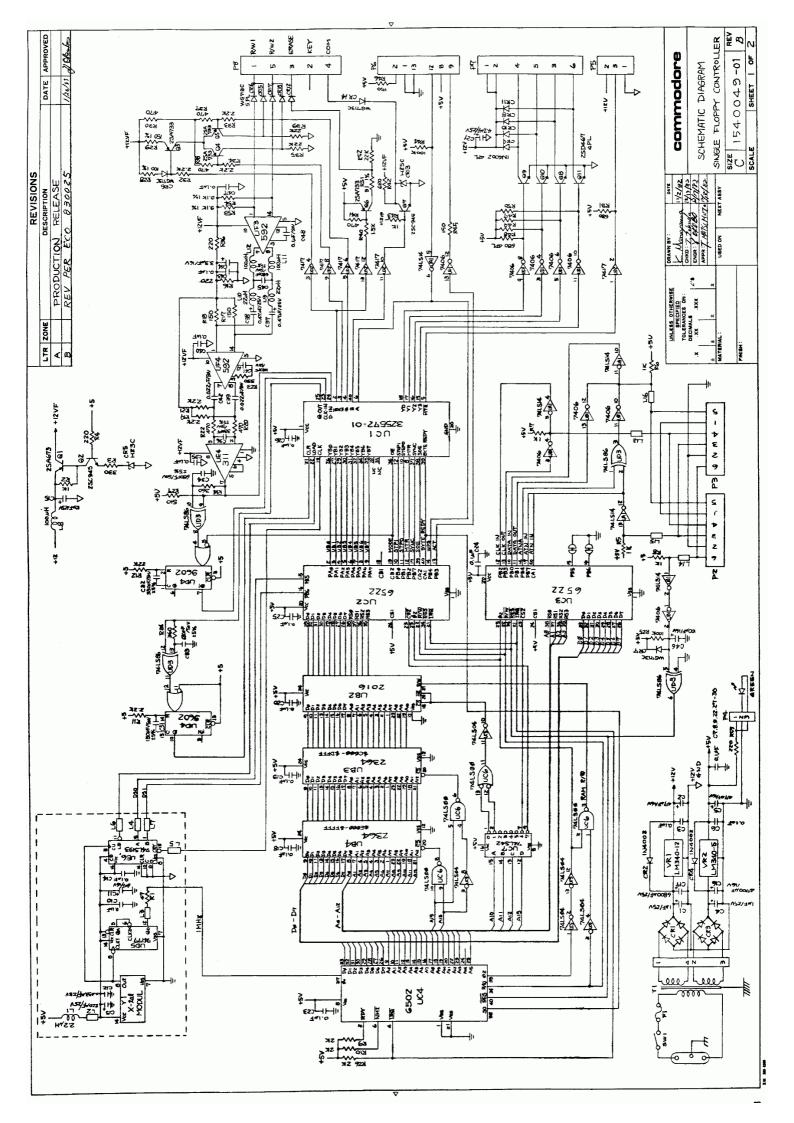
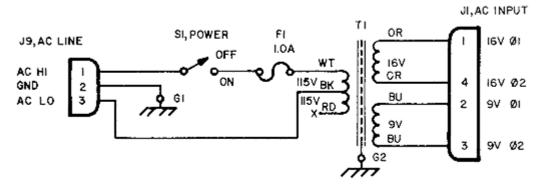
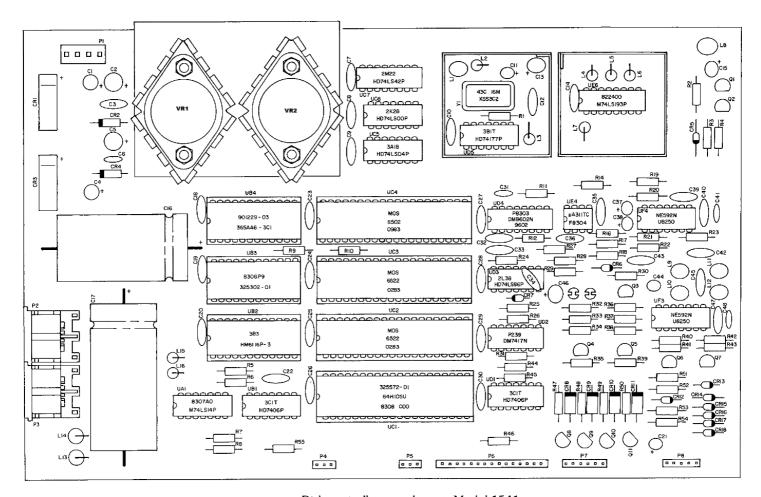
		CBM	FLOPPY	DRIVE	1541	
Model	System	Board-D	Description			
VIC 1541		Very early version, long board.  As above, only the ROMs are different.  Shorter board with a 40 pin gate array, Alps mech.  As above, but Newtronics mech. Similar to above Similar to above, Alps mechanism.				
1541						
SX 64	250410-01	Design most similar to 1540048-01, Alps mechanism.				
1541	251777 251830	Function of bridge rects. reversed, Newtronics mech. Same as above				mech.
1541 A 1541 A2 1541 B 1541 C	250442-01 250446-01 250448-01 250448-01	A 74LS Same a Short bo R/W hyl	Newtronics driv 123 replaces th is the 1541C, b oard, new 40/42 brid chip replac Newtronics driv	e 9602 at UD ut in a case lik 2 pin gate arra e many comp	4. xe the 1541 ay, 20 pin g onents.	ate arra
1541C 251854 As above, s			re, single DOS stepper motor of	ROM IC, trk 0	sensor, 30	
1541-II			using the 40 pi t not the 20 pin			
NOTE:		ese system boards are the 60 Hz versions. The -02 and -04 boate probably the 50 Hz versions.				

The ROMs appear to be completely interchangeable. For instance, the first version of ROM for the 1541-II contained the same code as the last version of the 1541. I copy the last version of the 1541-II ROM into two 68764 EPROMs and use them in my original 1541 (long board). Not only do they work, but they work better than the originals.

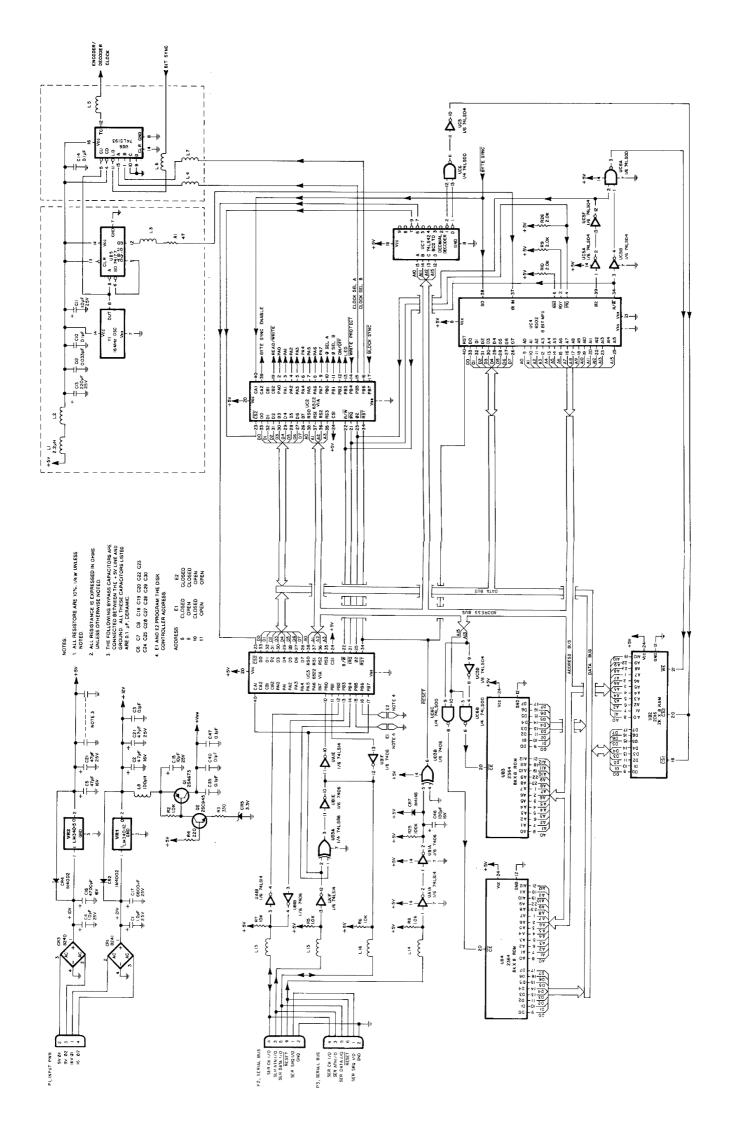


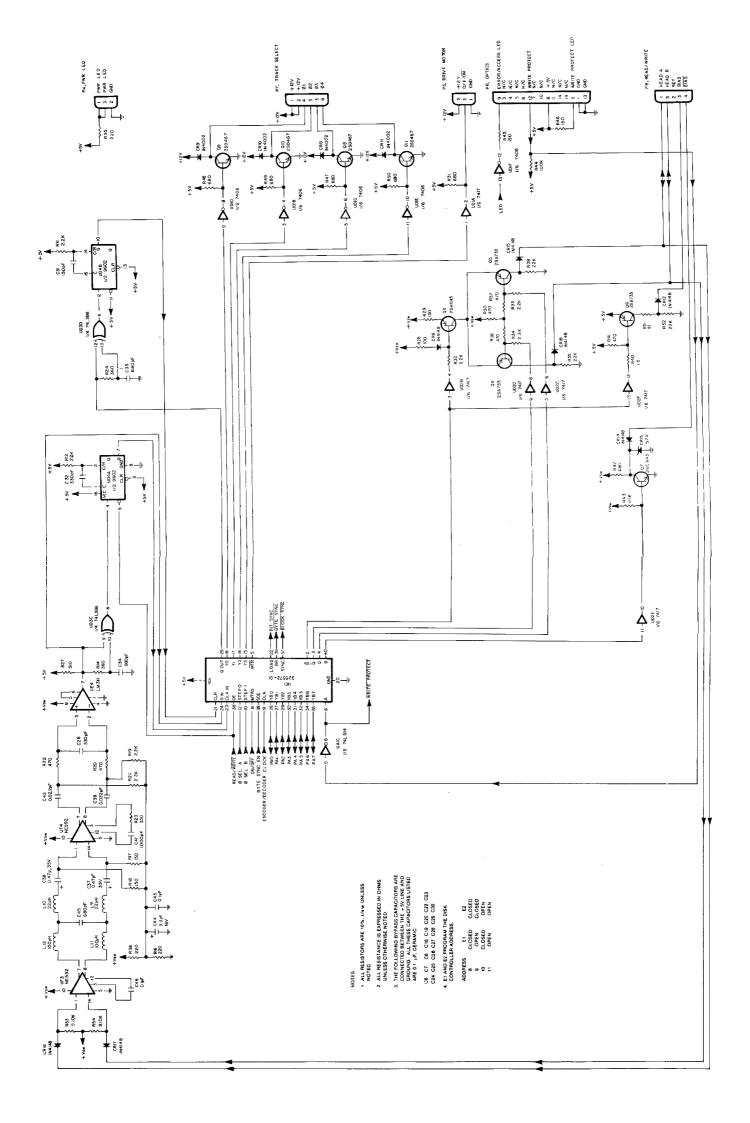


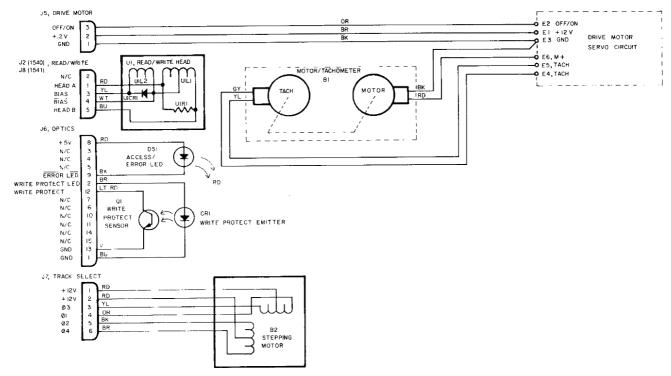
115VAC, 50-60Hz



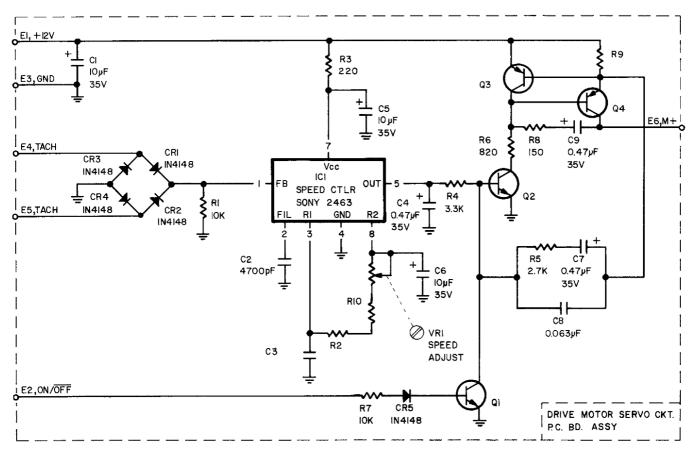
Disk controller parts layout, Model 1541.



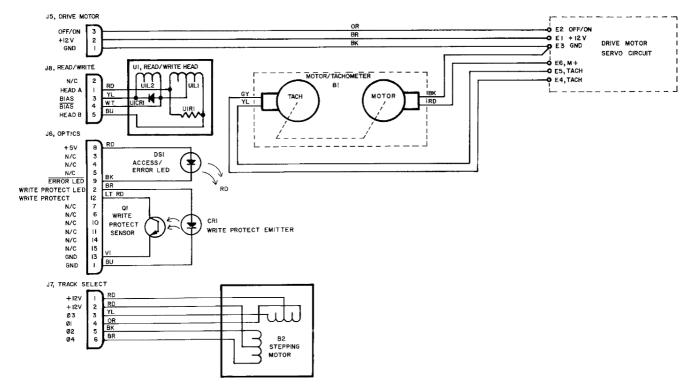




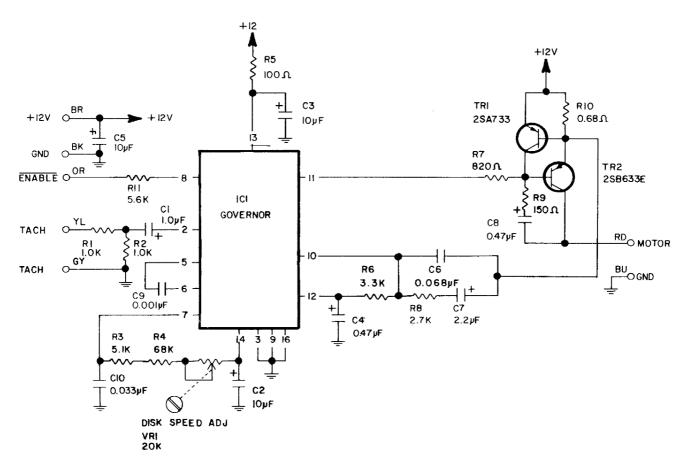
Drive unit schematic, Models 1540 and 1541.



Drive motor servo circuit, Models 1540 and 1541.



Drive unit schematic, Model 1542.



Drive motor servo circuit, Model 1542.