

UNILATERAL BOUNDARY VALUE PROBLEMS WITH JUMP DISCONTINUITIES

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Using the critical point theory of Szulkin (1986), we study elliptic problems with unilateral boundary conditions and discontinuous nonlinearities. We do not use the method of upper and lower solutions. We prove two existence theorems: one when the right-hand side is nondecreasing and the other when it is nonincreasing.

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1. Introduction. In this paper, using the critical-point theory of Szulkin [10] for lower semicontinuous functionals, we study nonlinear elliptic problems with unilateral boundary conditions and jump discontinuities. Let $Z \subseteq \mathbb{R}^N$ be a bounded domain with a C^1 -boundary Γ . The problem under consideration is

$$\begin{aligned} -\operatorname{div} \left(\|Dx(z)\|^{p-2} Dx(z) \right) &= f(z, x(z)) \quad \text{a.e. on } Z, \\ \frac{\partial x}{\partial n_p}(z) &\geq 0 \quad \text{a.e. on } \Gamma, \quad 2 \leq p < \infty, \\ \left\langle \frac{\partial x}{\partial n_p}, x \right\rangle_{\Gamma} &= 0, \\ x &\geq 0 \quad \text{a.e. on } \Gamma. \end{aligned} \tag{1.1}$$

Here, $D = \operatorname{grad}$, $(\partial x / \partial n_p)(z) = \|Dx(z)\|^{p-2} (Dx(z), n(z))_{\mathbb{R}^N}$, where $n(z)$ denotes the exterior normal vector to Γ at z . By $\langle \cdot, \cdot \rangle_{\Gamma}$, we denote the natural pairing between $((W^{1/q,p}(\Gamma))^*, W^{1/q,p}(\Gamma))$. By $\langle \partial x / \partial n_p, x \rangle_{\Gamma} = 0$, we mean formally that $\|Dx(z)\|^{p-2} (Dx(z), \eta(z))_{\mathbb{R}^N} x(z) = 0$ on Γ (see Kenmochi [8, Remark 1, pages 137–138]). One can also see Barbu [3, Chapter IV].

Our approach is variational and we minimize nonsmooth energy functionals. Dirichlet problems with discontinuities were studied by Ambrosetti and Badiale [1], Arcoya and Calahorrano [2], and Stuart and Toland [9]. All of these works need the right-hand side to be nondecreasing. Moreover, we study an elliptic problem with unilateral boundary conditions. Our energy functional is convex and lower semicontinuous and is not defined everywhere. Thus, we cannot apply the critical-point theory of Chang [4], which is for locally Lipschitz functionals defined everywhere.

On the other hand, Heikkilä and Lakshmikantham [6] used the method of upper and lower solutions and obtained existence theorems with a pseudomonotone differential operator and a nondecreasing right-hand side. They proved existence results for Dirichlet, Neumann, and other types of problems. Our goal here is to have an existence result without assuming the existence of upper and lower solutions. It seems that this is the first such result for unilateral problems. For another type of boundary conditions, one can see also [5].

2. Preliminaries. As we already mentioned, our approach is variational and is based on the critical-point theory of Szulkin [10], which applies to a certain broad class of nonsmooth energy functionals. For the convenience of the reader, in this section, we recall some basic definitions and facts from this theory, which we will need in the sequel.

So, let X be a Banach space and $R : X \rightarrow \bar{R} = R \cup \{+\infty\}$ be a function satisfying the following hypothesis:

(H) $R = \Phi + \psi$, where $\Phi \in C^1(X, R)$ and $\psi : X \rightarrow (-\infty, +\infty]$ is convex, proper (i.e., $\psi \not\equiv +\infty$), and lower semicontinuous.

Following Szulkin [10], a point $x \in X$ is said to be a critical point of R if $x \in \text{dom } \psi = \{x \in X : \psi(x) < +\infty\}$ and satisfies the inequality

$$\langle \Phi'(x), y - x \rangle + \psi(y) - \psi(x) \geq 0 \quad \forall y \in X. \quad (2.1)$$

Here, by $\langle \cdot, \cdot \rangle$ we denote the duality brackets for the pair (X, X^*) . If $x \in X$ is a critical point, then $c = R(x)$ is called “critical value.” It is clear from the above definition that $x \in X$ is a critical point if and only if $-\Phi'(x) \in \partial\psi(x)$, where $\partial\psi(\cdot)$ denotes the subdifferential in the sense of convex analysis of ψ . Exploiting the convexity of ψ , we can easily prove the following proposition (see Szulkin [10]).

PROPOSITION 2.1. *If R satisfies (H), then each local minimum is necessarily a critical point of R .*

It is well known that variational methods require some kind of compactness condition, known as “Palais-Smale condition” ((PS)-condition). In the present nonsmooth setting, this condition was formulated by Szulkin [10] as follows.

(PS) If $\{x_n\}_{n \geq 1}$ is a sequence such that $R(x_n) \rightarrow c \in R$ and

$$\langle \Phi'(x_n), y - x_n \rangle + \psi(y) - \psi(x_n) \geq -\varepsilon_n \|y - x_n\| \quad \forall y \in X, \quad (2.2)$$

where $\varepsilon_n \rightarrow 0$, then $\{x_n\}_{n \geq 1}$ possesses a convergent subsequence.

An alternative formulation of the compactness condition is the following.

(PS') If $\{x_n\}_{n \geq 1}$ is a sequence such that $R(x_n) \rightarrow c \in R$ and

$$\langle \Phi'(x_n), y - x_n \rangle + \psi(y) - \psi(x_n) \geq \langle z_n, y - x_n \rangle \quad \forall y \in X, \quad (2.3)$$

where $z_n \rightarrow 0$, then $\{x_n\}_{n \geq 1}$ possesses a convergent subsequence.

Szulkin (see [10, Proposition 1.2]) proved that the above two formulations are in fact equivalent.

The following theorem of Szulkin (see [10, Theorem 1.7]) will be used in our main existence theorem.

THEOREM 2.2. *If R is bounded from below and satisfies (H) and (PS), then $c = \inf_{x \in X} R(x)$ is a critical value.*

In what follows, we will use the well-known inequality

$$\sum_{j=1}^N (a_j(\eta) - a_j(\eta')) (\eta_j - \eta'_j) \geq C |\eta - \eta'|^p \quad (2.4)$$

for $\eta, \eta' \in R^N$, with $a_j(\eta) = |\eta|^{p-2} \eta_j$.

3. Existence theory. We state our hypotheses for the functions f of problem (1.1).

(H(f)₁) We suppose that $f : Z \times R \rightarrow R$ is a function such that

- (i) it is N -measurable (i.e., for every $x : Z \rightarrow R$ measurable, $z \rightarrow f_{1,2}(z, x(z))$ is measurable too) with

$$f_1(z, x) = \liminf_{x' \rightarrow x} f(z, x'), \quad f_2(z, x) = \limsup_{x' \rightarrow x} f(z, x'), \quad (3.1)$$

- (ii) there exists $h : Z \times R \rightarrow R$ with $|h(z, x)| \leq c_1 + c_2 |x|^{p^*}$ for all $x \in R$ almost all $z \in Z$ and for some $c_1, c_2 > 0$, such that $h(z, x) \rightarrow \infty$ as $x \rightarrow +\infty$ and there exists $M > 0$ such that for almost all $z \in Z$, $-F(z, x) \geq h(z, |x|)$ for $|x| \geq M$ with $F(z, x) = \int_0^x f(z, r) dr$,

- (iii) for almost all $z \in Z$ and for all $x \in R$, $|f(z, x)| \leq c_1 + c_2 |x|^{\mu-1}$, $\mu < p$, $c_1, c_2 > 0$, $(1/\mu + 1/\mu' = 1)$, and there exists $g : Z \times R \rightarrow R$ Carathéodory such that $|g(z, x)| \leq c_3 + c_4 |x|^{p^*}$ with $p^* = Np/(N-p)$ and $x \rightarrow g(z, x) - f(z, x)$ is nondecreasing for all $x \in R$ and for almost all $z \in Z$.

Let $x \in W^{1,p}(Z)$ satisfy the boundary conditions.

DEFINITION 3.1. We say that x is a solution of type I for problem (1.1) if there exists some $w(z) \in L^{\mu'}(Z)$ with $w(z) \in [f_1(z, x(z)), f_2(z, x(z))]$ a.e. on Z such that

$$-\operatorname{div} \left(\|Dx(z)\|^{p-2} Dx(z) \right) = w(z) \quad \text{a.e. on } Z. \quad (3.2)$$

DEFINITION 3.2. We say that x is a solution of type II for problem (1.1) if

$$-\operatorname{div} \left(\|Dx(z)\|^{p-2} Dx(z) \right) = f(z, x(z)) \quad \text{a.e. on } Z. \quad (3.3)$$

THEOREM 3.3. *If hypotheses (H(f)₁) hold, then problem (1.1) has a solution of type I.*

PROOF. Let $\Phi_1, \Phi_2, \psi : W^{1,p}(Z) \rightarrow R$ be defined as follows:

$$\Phi_1(x) = - \int_Z F(z, x(z)) dz + \int_Z G(z, x(z)) dz \quad (3.4)$$

with

$$\begin{aligned} G(z, x) &= \int_0^x g(z, r) dr, \\ \psi(x) &= \frac{1}{p} \|Dx\|_p^p + I_K(x), \\ \Phi_2(x) &= - \int_Z \int_0^{x(z)} g(z, r) dr dz. \end{aligned} \quad (3.5)$$

Here, $K = \{x \in W^{1,p}(Z) : x \geq 0 \text{ on } \Gamma \text{ in the sense of } W^{1/p',p}\}$ (see Kenmochi [8]) and I_K is the indicator function of the closed, convex set K . Then the energy functional is $R(x) = \Phi_1(x) + \Phi_2(x) + \psi(x)$.

It is clear that $\Phi_2 \in C^1(W^{1,p}(Z), R)$. It is easy to prove that ψ is lower semicontinuous, convex, and proper. It remains to show that Φ_1 is convex and lower semicontinuous. Let $x_n \rightarrow x$ in $W^{1,p}(Z)$. Then $x_n \rightarrow x$ in $L^{p^*}(Z)$ and $x_n(z) \rightarrow x(z)$ a.e. on Z .

From Chang (see [4, (2.3), page 107]), we know that $x \rightarrow F(z, x)$ is locally Lipschitz. It is easy to see that $x \rightarrow G(z, x)$ is locally Lipschitz too. So, $G(z, x_n(z)) - F(z, x_n(z)) \rightarrow G(z, x(z)) - F(z, x(z))$ a.e. on Z . Now using (H(f)₁)(iii) and the dominated convergence theorem, we have that $\Phi_1(x_n) \rightarrow \Phi_1(x)$ as $n \rightarrow \infty$.

Moreover, by virtue of monotonicity of $x \rightarrow g(z, x) - f(z, x)$, we have that $x \rightarrow G(z, x) - F(z, x)$ is convex.

CLAIM 3.4. *We claim that $R(\cdot)$ satisfies the (PS)-condition of Szulkin [10].*

Indeed, let $\{x_n\}_{n \geq 1} \subseteq W^{1,p}$ such that $R(x_n) \rightarrow c$ as $n \rightarrow \infty$. Note that if $x_n \notin K$, then $\psi(x_n) = +\infty$, thus, $R(x_n) = +\infty$. Since, $R(x_n) \rightarrow c$, we obtain that $x_n \in K$ for large enough n .

We will prove that this sequence is bounded in $W^{1,p}(Z)$. Suppose not. Then $\|x_n\| \rightarrow \infty$. Let $y_n(z) = x_n(z)/\|x_n\|$. Then clearly, at least for a subsequence, we have $y_n \xrightarrow{w} y$ in $W^{1,p}(Z)$. From the choice of the sequence, we have

$$\Phi_1(x_n) + \Phi_2(x_n) + \frac{1}{p} \|Dx_n\|_p^p \leq M. \quad (3.6)$$

Dividing the last inequality by $\|x_n\|$, we have

$$- \int_Z \frac{F(z, x_n(z))}{\|x_n\|^p} dz + \frac{1}{p} \|Dy_n\|_p^p \leq \frac{M}{\|x_n\|^p}. \quad (3.7)$$

By virtue of hypothesis $(H(f)_1)(iii)$, we have that $\int_Z (F(z, x_n(z)) / \|x_n\|^p) dz \rightarrow 0$. Indeed, from $(H(f)_1)(iii)$, we have that $|F(z, x)| \leq c_1 |x| + c_2 |x|^\mu$. So,

$$\begin{aligned} \int_Z \frac{|F(z, x_n(z))|}{\|x_n\|^p} dz &\leq \int_Z c_1 \frac{|x_n(z)|}{\|x_n\|^p} dz + c_2 \int_Z \frac{|x_n(z)|^\mu}{\|x_n\|^p} dz \\ &\leq c_3 \frac{\|x_n\|}{\|x_n\|^p} + c_4 \frac{\|x_n\|^\mu}{\|x_n\|^p}; \end{aligned} \quad (3.8)$$

here we have used the fact that $W^{1,p}(Z)$ embeds continuously in $L^1(Z)$ and in $L^p(Z)$.

So, $\liminf \|Dy_n\|_p \leq \limsup \|Dy_n\|_p^p \rightarrow 0$. From the weak lower semicontinuity of the norm functional, we have that $\|Dy\|_p \leq \liminf \|Dy_n\|_p$. Thus, $\|Dy\|_p = 0$. So, we infer that $y = c \in R$. Since $\|y_n\| = 1$, $c \neq 0$. So, we have that $|x_n(z)| \rightarrow \infty$.

From $(H(f)_1)(ii)$, we have that there exists some $M > 0$ such that for all $x \in R$ with $|x| > M$, we have that $-F(z, x) \geq h(z, |x|)$. Using the continuity of $x \rightarrow F(z, x)$ and that for $|x| \leq M$ we have that $|h(z, x)| \leq L$, we can say that for all $x \in R$, there exists some $C > 0$ such that $-F(z, x) + C \geq h(z, |x|)$. Therefore, going back to (3.6) and using the fact that $|x_n(z)| \rightarrow \infty$, we have a contradiction. So, $\|x_n\|$ is bounded, that is, $x_n \xrightarrow{w} x$ in $W^{1,p}(Z)$ at least for a subsequence. It remains to show that $x_n \rightarrow x$ in $W^{1,p}(Z)$ for a subsequence. Recall that $x_n \rightarrow x$ in $L^p(Z)$ and $x_n(z) \rightarrow x(z)$ a.e. on Z . Because K , closed and convex, is weakly closed, so $x \in K$.

Recall that from the choice of the sequence, we have that

$$\langle \Phi'_2(x_n), y - x_n \rangle + \Phi_1(y) - \Phi_1(x_n) + \psi(y) - \psi(x_n) \geq -\varepsilon_n \|y - x_n\| \quad (3.9)$$

for all $y \in W^{1,p}(Z)$.

Choose $y = x$. Then we have

$$\begin{aligned} \langle \Phi'_2(x_n), x - x_n \rangle + \Phi_1(x) - \Phi_1(x_n) + \psi(x) - \psi(x_n) \\ \geq -\varepsilon_n \|x - x_n\| \implies \langle \Phi'_2(x_n), x - x_n \rangle + \Phi_1(x) - \Phi_1(x_n) \\ + \frac{1}{p} (\|Dx\|_p^p - \|Dx_n\|_p^p) \\ \geq -\varepsilon_n \|x - x_n\|. \end{aligned} \quad (3.10)$$

Note that $I_K(x) = I_K(x_n) = 0$. Thus

$$\begin{aligned} \lim \langle \Phi'_2(x_n), x_n - x \rangle + \lim (\Phi_1(x) - \Phi_1(x_n)) \\ + \underline{\lim} (\|Dx\|_p^p - \|Dx_n\|_p^p) \geq 0. \end{aligned} \quad (3.11)$$

By virtue of hypothesis (H(f)₁)(iii) and the definition of Φ_2 , we have that

$$\lim \langle \Phi'_2(x_n), x_n - x \rangle = 0. \quad (3.12)$$

As before, we can see that

$$\Phi_1(x_n) \rightarrow \Phi_1(x). \quad (3.13)$$

Thus, finally we obtain

$$\limsup \|Dx_n\|_p^p \leq \|Dx\|_p^p. \quad (3.14)$$

On the other hand, since $Dx_n \xrightarrow{w} Dx$ in $L^p(Z, \mathbb{R}^N)$, from the weak lower semicontinuity of the norm, we have

$$\liminf \|Dx_n\|_p \geq \|Dx\|_p \Rightarrow \|Dx_n\|_p \rightarrow \|Dx\|_p. \quad (3.15)$$

The space $L^p(Z, \mathbb{R}^N)$ being uniformly convex has the Kadec-Klee property (see Hu and Papageorgiou [7, Definition I.1.72(d)]) and so $x_n \rightarrow x$ in $W^{1,p}(Z)$.

CLAIM 3.5. *We claim that $R(\cdot)$ is bounded from below.*

Suppose not. Then there exists some sequence $\{x_n\}_{n \geq 1}$ such that $R(x_n) \leq -n$. Then we have

$$\Phi_1(x_n) + \Phi_2(x_n) + \frac{1}{p} \|Dx_n\|_p^p \leq -n. \quad (3.16)$$

By virtue of the continuity of Φ_1 , Φ_2 , and $\|Dx\|_p$, we have that $\|x_n\| \rightarrow \infty$ (because if $\|x_n\|$ is bounded, then $R(x_n)$ is bounded). Dividing by $\|x_n\|^p$ and letting $n \rightarrow \infty$, we have as before a contradiction (by virtue of hypothesis (H(f)₁)(ii)). Therefore, $R(\cdot)$ is bounded from below.

From the above arguments, we know that there exists $x \in W^{1,p}(Z)$ such that $0 \in \partial R(x)$ and $x \in K$. That means that $0 \in \partial(\Phi_1(x) + I_K) + Ax - g$. Here, $A : W^{1,p}(Z) \rightarrow (W^{1,p}(Z))^*$ is such that

$$\langle Ax, y \rangle = \int_Z \|Dx(z)\|^{p-2} (Dx(z), Dy(z))_{\mathbb{R}^N} dz, \quad (3.17)$$

for every $y \in W^{1,p}(Z)$. It is well known that this operator is bounded and pseudomonotone. Also, it is well known that the operator $\psi_1(x) = (1/p)\|Dx\|_p^p$ is differentiable, and then the subdifferential of this operator has only one element.

Recall that Φ_1 is continuous. Therefore, from convex analysis, we know that $\partial(\Phi_1(x) + I_K(x)) = \partial\Phi_1(x) + \partial I_K(x)$. For a more-detailed study of $\partial I_K(x)$, one can see [3, page 54].

From Chang [4], we know that $\partial\Phi_1(x) \subseteq g(z, x(z)) - [f_1(z, x(z)), f_2(z, x(z))]$ (note that Φ_1 is locally Lipschitz, so the subdifferential of convex analysis coincides with this for locally Lipschitz functionals). So, we can say that there exists some $w(z) \in L^{\mu'}$ with $w(z) \in [f_1(z, x(z)), f_2(z, x(z))]$ a.e. on Z such that

$$\langle Ax, y \rangle - \langle w, y \rangle \leq I_K(y) - I_K(x) \quad \forall y \in W^{1,p}(Z). \quad (3.18)$$

We can show that problem (1.1) is equivalent with the above inequality (see Kenmochi [8, Proposition 4.1]). \square

We can have a second existence theorem of type II. We state the following hypotheses.

(H(f)₂) We suppose that $f : R \rightarrow R$ is a function such that

- (i) it is N -measurable (i.e., for every $x : Z \rightarrow R$ measurable, $z \rightarrow f_{1,2}(x(z))$ is measurable too),
- (ii) there exists $h : R \rightarrow R$ with $|h(x)| \leq c_1 + c_2|x|^{p^*}$ for all $x \in R$, almost all $z \in Z$ and for some $c_1, c_2 > 0$, such that $h(x) \rightarrow \infty$ as $x \rightarrow +\infty$ and there exists $M > 0$ such that $-F(x) \geq h(|x|)$ for $|x| \geq M$ with $F(x) = \int_0^x f(r)dr$,
- (iii) for all $x \in R$, $|f(x)| \leq c_1 + c_2|x|^{\mu-1}$, $\mu < p$, $c_1, c_2 > 0$, $(1/\mu + 1/\mu' = 1)$ and there exists $g : R \rightarrow R$ Carathéodory such that $|g(x)| \leq c_3 + c_4|x|^{p^*}$ with $p^* = Np/(N-p)$ and $x \rightarrow g(x) - f(x)$ is nonincreasing.

THEOREM 3.6. *If (H(f)₂) hold, then problem (1.1) has a solution of type II.*

PROOF. Take the same functional R as before. We can easily see that $R : W^{1,p}(Z)$ is weakly lower semicontinuous and coercive. The weakly lower semicontinuity is easy, noticing that if $x_n \rightarrow x$ weakly in $W^{1,p}(Z)$, then, at least for a subsequence again denoted by x_n , we have that $x_n \rightarrow x$ strongly in $L^p(Z)$. Indeed, $\psi(x)$ is convex and lower semicontinuous, so is weakly lower semicontinuous. Recall that, $\Phi_1(x) + \Phi_2(x) = -\int_Z F(z, x(z))dz$. So, using (H(f)₂)(iii) and the dominated convergence theorem, we have that $\Phi_1(x_n) + \Phi_2(x_n) \rightarrow -\int_Z F(z, x(z))dz = \Phi_1(x) + \Phi_2(x)$.

For coercivity, we can use the same arguments as in Theorem 3.3.

Take now the ball $M = \{\|x\| \leq C\}$, then from the coercivity of R follows that the infimum is on M for large enough C . So, there exists some $x \in W^{1,p}(Z)$ such that $0 \leq R(y) - R(x)$ for all $y \in W^{1,p}(Z)$ (see Zeidler [11, Proposition 38.12(d), page 154]).

Thus,

$$(-\Phi_1)(y) - (-\Phi_1)(x) \leq \Phi_2(y) + \psi(y) - \Phi_2(x) - \psi(x). \quad (3.19)$$

Since $(-\Phi_1)$ is convex, from the above inequality follows that for all $v_1 \in \partial\Phi_1(x)$, we have

$$v_1 \in \partial(\Phi_2(x) + \psi(x)). \quad (3.20)$$

So, for all $w \in L^{\mu'}(Z)$ with $w(z) \in [f_1(x(z)), f_2(x(z))]$, we have that

$$\langle w, y - x \rangle \leq \langle Ax, y - x \rangle + I_K(y) - I_K(x). \quad (3.21)$$

Choosing now $y = x \pm \phi$ with $\phi \in C_o^\infty(Z)$, we have that for all $w(z) \in [f_1(x(z)), f_2(x(z))]$,

$$\langle w, \phi \rangle = \langle Ax, \phi \rangle. \quad (3.22)$$

We show that $\lambda\{z \in Z : x(z) \in D(f)\} = 0$ with $D(f) = \{x \in R : f(x^+) > f(x^-)\}$, that is, the set of upward-jumps.

So, let $w(z) \in [f_1(x(z)), f_2(x(z))]$ and for any $t \in D(f)$, set

$$\rho^\pm(z) = [1 - \chi_t(x(z))]w(z) + \chi_t(x(z))[f(x(z)^\pm)], \quad (3.23)$$

where

$$\chi_t(s) = \begin{cases} 1, & \text{if } s = t, \\ 0, & \text{otherwise.} \end{cases} \quad (3.24)$$

Then $\rho^\pm \in L^q(Z)$ and $\rho^\pm \in [f_1(x), f_2(x)]$. So

$$\int_Z \rho^\pm(z) y(z) dz = \int_Z \|Dx(z)\|^{p-2} (Dx(z), Dy(z))_{R^N} dz \quad (3.25)$$

for all $y \in C_o^\infty(Z)$.

Thus, $\rho^+ = \rho^-$ for almost all $z \in Z$. From this, it follows that $\chi_t(x(z)) = 0$ for almost all $z \in Z$. Since $D(f)$ is countable and

$$\chi(x(z)) = \sum_{t \in D(f)} \chi_t(x(z)), \quad (3.26)$$

it follows that $\chi(x(z)) = 0$ a.e. (with $\chi(t) = 1$ if $t \in D(f)$ and $\chi(t) = 0$ otherwise).

So, as before, we can show that x is a solution of type II. \square

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Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from “Qualitative Theory of Differential Equations,” allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

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