

S. Topa

The determination of the homomorphisms of some representation of the group L_2^2

Let us consider a group G and its two arbitrary representations

$$(1) \quad \bar{x} = f(x, a), \quad x, \bar{x} \in X, \quad a \in G,$$

$$(2) \quad \bar{y} = g(y, a), \quad y, \bar{y} \in Y, \quad a \in G.$$

A function $\varphi: X \rightarrow Y$ of the property that

$$(3) \quad \varphi(f(x, a)) = g(\varphi(x), a), \quad x \in X, \quad a \in G$$

is named the homomorphism of the algebraic structure (X, f) to the structure (Y, g) .

The problem is to solve equation (3) with the following representation $(a, \beta, \gamma, \delta, \dots, k = 1, 2)$

$$a \in G \Leftrightarrow a = (L_\beta^\alpha, L_{\beta\gamma}^\alpha) \in L_2^2,$$

$$x \in X \Leftrightarrow x = \begin{pmatrix} x_\alpha \\ x_{\alpha\beta} \end{pmatrix} \in R^{12} \text{ and } \det_k x_\alpha \neq 0$$

$$(4) \quad \bar{x} = f(x, a) \Leftrightarrow \begin{cases} \bar{x}_\alpha = L_\alpha^\gamma x_\gamma \\ \bar{x}_{\alpha\beta} = L_{\alpha\beta}^\gamma x_\gamma + L_\alpha^\delta L_{\beta\gamma}^\delta x_{\gamma\delta} \end{cases} \quad x, \bar{x} \in X, \quad L \in L_2^2.$$

L_2^2 denotes the differential group of order 2 in two dimensional space.

The function g may be arbitrary.

By the above assumptions equation (3) takes the form

$$(5) \quad \varphi(\bar{x}_\alpha, \bar{x}_{\alpha\beta}) = g(\varphi(x_\alpha, x_{\alpha\beta}), L_\beta^\alpha, L_{\beta\gamma}^\alpha).$$

A function φ , which satisfies (3), may be also called the „generalized homogeneous function” with respect to the functions f and g (see [1]). In [1] there is given a method of solving the functional equations of the type (3). The equation (5) will be solved here by using this method (see also [2]).

The domains of transitivity of points $x \in X$ with respect to the representation (4) are 10-dimensional surfaces in 12-dimensional space $R^{12} \supset X$. One of the „generators” of the family of these surfaces is of the form

$$(6) \quad \begin{cases} x_\gamma = \delta_\gamma, \\ x_{\gamma\delta} = \delta_\gamma^1 \delta_\delta^2 \delta^* T_\kappa, \end{cases} \quad T = (T_1, T_2) \in R^2.$$

If we put the right-hand-side expressions of (6) in the formulae (4) instead of x , then we obtain the one-to-one transformation of the form

$$(7) \quad \begin{cases} \bar{x}_a = L_a^\gamma \delta_\gamma, \\ \bar{x}_{a\beta} = L_{a\beta}^\gamma \delta_\gamma + L_a^\kappa L_\beta^\delta \delta_\gamma^1 \delta_\delta^2 \delta^* T_\kappa, \end{cases} \quad L \in L_2^2, \quad T \in R^2, \quad \bar{x} \in X.$$

The inverse transformation of (7) is the following

$$(8) \quad \begin{cases} T_a = \frac{1}{\Delta} [(\bar{x}_{12} - \bar{x}_{21}) \delta_a^2 - (\bar{x}_{12} - \bar{x}_{21}) \delta_a^1], \quad \Delta = \det \|\bar{x}_a\|, \\ L_\beta^\kappa = \delta_\beta^k \bar{x}_a, \\ L_{\beta\gamma}^\kappa = (\bar{x}_{\beta\gamma} - \bar{x}_{\beta\gamma} \bar{x}_{\beta\gamma} T_k) \delta^{ka}. \end{cases}$$

Now we put the right-hand-side expressions of (6) in (5) instead of x and we obtain

$$(9) \quad \varphi(\bar{x}_a, \bar{x}_{a\beta}) = g(\Phi(T_a), L_\beta^\kappa, L_{\beta\gamma}^\kappa)$$

where

$$\Phi(T_a) \stackrel{df}{=} \varphi(\delta_a, \delta_\gamma^1 \delta_\delta^2 \delta^* T_\kappa).$$

If we were to put the right-hand-side expressions of (8) in (9) instead of $T_a, L_\beta^\kappa, L_{\beta\gamma}^\kappa$, then the formula for the general solution of the equation (5) would be obtained. The function $\Phi: R^2 \rightarrow Y$ may be arbitrary.

REFERENCES

- [1] S. Topa, *On a generalization of homogeneous functions*, Publ. Math. Debrecen, 13 (1966), 1-4, 289-300.
- [2] S. Topa, *Determination of differential concomitants of the first class of a pair of covariant vectors in a two-dimensional space*, Ann. Polon. Math. XIX (1967), 337-341.