

S. Topa

### The determination of the homomorphisms of some representation of the group $L_2^2$

Let us consider a group  $G$  and its two arbitrary representations

$$(1) \quad \bar{x} = f(x, a), \quad x, \bar{x} \in X, \quad a \in G,$$

$$(2) \quad \bar{y} = g(y, a), \quad y, \bar{y} \in Y, \quad a \in G.$$

A function  $\varphi: X \rightarrow Y$  of the property that

$$(3) \quad \varphi(f(x, a)) = g(\varphi(x), a), \quad x \in X, \quad a \in G$$

is named the homomorphism of the algebraic structure  $(X, f)$  to the structure  $(Y, g)$ .

The problem is to solve equation (3) with the following representation  $(a, \beta, \gamma, \delta, \dots, k = 1, 2)$

$$a \in G \Leftrightarrow a = (L_\beta^\alpha, L_{\beta\gamma}^\alpha) \in L_2^2,$$

$$x \in X \Leftrightarrow x = (x_\alpha, x_{\alpha\beta}) \in R^{12} \text{ and } \det \|x_\alpha\| \neq 0$$

$$(4) \quad \bar{x} = f(x, a) \Leftrightarrow \begin{cases} \bar{x}_\alpha = L_\alpha^\gamma x_\gamma \\ \bar{x}_{\alpha\beta} = L_{\alpha\beta}^\gamma x_\gamma + L_\alpha^\gamma L_{\beta\gamma}^\delta x_{\gamma\delta} \end{cases} \quad x, \bar{x} \in X, \quad L \in L_2^2.$$

$L_2^2$  denotes the differential group of order 2 in two dimensional space.

The function  $g$  may be arbitrary.

By the above assumptions equation (3) takes the form

$$(5) \quad \varphi(\bar{x}_\alpha, \bar{x}_{\alpha\beta}) = g(\varphi(x_\alpha, x_{\alpha\beta}), L_\beta^\alpha, L_{\beta\gamma}^\alpha).$$

A function  $\varphi$ , which satisfies (3), may be also called the „generalized homogeneous function” with respect to the functions  $f$  and  $g$  (see [1]). In [1] there is given a method of solving the functional equations of the type (3). The equation (5) will be solved here by using this method (see also [2]).

The domains of transitivity of points  $x \in X$  with respect to the representation (4) are 10-dimensional surfaces in 12-dimensional space  $R^{12} \supset X$ . One of the „generators” of the family of these surfaces is of the form

$$(6) \quad \begin{cases} x_{\gamma} = \delta_{\gamma}^k, \\ x_{\gamma\delta} = \delta_{\gamma}^1 \delta_{\delta}^2 \delta_k^{\alpha} T_{\alpha}, \end{cases} \quad T = (T_1, T_2) \in R^2.$$

If we put the right-hand-side expressions of (6) in the formulae (4) instead of  $x$ , then we obtain the one-to-one transformation of the form

$$(7) \quad \begin{cases} \bar{x}_{\alpha} = L_{\alpha}^{\gamma} \delta_{\gamma}^k, \\ \bar{x}_{\alpha\beta} = L_{\alpha\beta}^{\gamma} \delta_{\gamma}^k + L_{\alpha}^{\gamma} L_{\beta}^{\delta} \delta_{\gamma}^1 \delta_{\delta}^2 \delta_k^{\alpha} T_{\alpha}, \end{cases} \quad L \in L_2^2, \quad T \in R^2, \quad \bar{x} \in X.$$

The inverse transformation of (7) is the following

$$(8) \quad \begin{cases} T_{\alpha} = \frac{1}{\Delta} [(\bar{x}_{12} - \bar{x}_{21}) \delta_{\alpha}^2 - (\bar{x}_{12} - \bar{x}_{21}) \delta_{\alpha}^1], & \Delta = \det \|\bar{x}_{\alpha}^k\|, \\ L_{\beta}^{\alpha} = \delta_{\beta}^k \bar{x}_{\alpha}^k, \\ L_{\beta\gamma}^{\alpha} = (\bar{x}_{\beta\gamma} - \bar{x}_{\beta\gamma} \bar{x}_{\beta\gamma} T_k) \delta^{k\alpha}. \end{cases}$$

Now we put the right-hand-side expressions of (6) in (5) instead of  $x$  and we obtain

$$(9) \quad \varphi(\bar{x}_{\alpha}^k, \bar{x}_{\alpha\beta}^k) = g(\Phi(T_{\alpha}), L_{\beta}^{\alpha}, L_{\beta\gamma}^{\alpha})$$

where

$$\Phi(T_{\alpha}) \stackrel{\text{def}}{=} \varphi(\delta_{\alpha}^k, \delta_{\gamma}^1 \delta_{\delta}^2 \delta_k^{\alpha} T_{\alpha}).$$

If we were to put the right-hand-side expressions of (8) in (9) instead of  $T_{\alpha}, L_{\beta}^{\alpha}, L_{\beta\gamma}^{\alpha}$ , then the formula for the general solution of the equation (5) would be obtained. The function  $\Phi: R^2 \rightarrow Y$  may be arbitrary.

#### REFERENCES

- [1] S. Topa, *On a generalization of homogeneous functions*, Publ. Math. Debrecen, 13 (1966), 1-4, 289-300.
- [2] S. Topa, *Determination of differential concomitants of the first class of a pair of covariant vectors in a two-dimensional space*, Ann. Polon. Math. XIX (1967), 337-341.