

ON AN ACCELERATED PROCEDURE OF EXTRAPOLATION

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ABSTRACT. This paper presents some theoretical results concerning an extrapolation method, based on a completely consistent linear stationary iterative method of first degree, for the numerical solution of the linear system $Au=b$. The main purpose of the paper is to find ranges for the extrapolation parameter, such that the extrapolation method converges independently of whether the original iterative method is convergent or not.

KEY WORDS AND PHRASES. *Linear stationary iterative method of first degree, Extrapolation method.*

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1. INTRODUCTION.

For the numerical solution of the linear system of equations

$$Au = b, \quad (1.1)$$

where A is a given nonsingular real $n \times n$ matrix, b is a given real vector and u is the solution - vector, which is to be determined, various iterative methods can be applied. Among them, we consider a completely consistent linear stationary iterative method of first degree (see e.g. [1]) defined by

$$u^{(m+1)} = Gu^{(m)} + k, \quad m = 0, 1, 2, \dots, \quad (1.2)$$

where G is some real matrix, which is called the iteration matrix of the method (1.2), k is some real vector and $u^{(0)}$ is an arbitrary initial approxi-

mation to the solution u of (1.1). Moreover, we have

$$k = (I-G)A^{-1}b \quad \text{and} \quad \det(I-G) \neq 0. \quad (1.3)$$

In order to accelerate the rates of convergence of methods like (1.2), various procedures and modifications are used. One of them is the extrapolation method based on (1.2). This is defined by

$$u^{(m+1)} = \omega(Gu^{(m)} + k) + (1-\omega)u^{(m)}, \quad m = 0, 1, 2, \dots, \quad (1.4)$$

where ω is a real parameter ($\neq 0$) called the extrapolation parameter. We note here, that the idea of using an extrapolation parameter, $\omega \neq 0$, appeared long ago in the stationary Richardson method [2], based on (1.1), defined by

$$u^{(m+1)} = u^{(m)} + \omega(Au^{(m)} - b) = (I + \omega A)u^{(m)} - \omega b, \quad m = 0, 1, 2, \dots,$$

which follows from (1.4) as a special case if $G = I + A$.

For $\omega=1$, method (1.4) coincides with (1.2). The iteration matrix of method (1.4) is

$$G_\omega = \omega G + (1-\omega)I, \quad (1.5)$$

where I is the identity matrix of order n . Thus, (1.4) takes the form

$$u^{(m+1)} = G_\omega u^{(m)} + k', \quad m = 0, 1, 2, \dots, \quad (1.6)$$

where $k' = \omega k$. Since

$$(I - G_\omega)A^{-1}b = \omega(I - G)A^{-1}b = \omega k = k'$$

and

$$\det(I - G_\omega) = \det(\omega(I - G)) = \omega^n \det(I - G) \neq 0,$$

it follows that the extrapolation method is completely consistent with the system (1.1).

The problem which now arises is how the parameter ω must be chosen in order to have $\rho(G_\omega) < \rho(G)$ with $\rho(G_\omega) < 1$, where $\rho(G)$, $\rho(G_\omega)$ are the spectral radii of the matrices G and G_ω respectively.

As is known, the problem of finding a theoretical optimum value for ω , say ω_{opt} , such that

$$\rho(G_{\omega_{\text{opt}}}) = \min_{\omega} \rho(G_\omega) \leq \rho(G) \quad \text{and} \quad \rho(G_{\omega_{\text{opt}}}) < 1,$$

has been solved in some special cases, but not in the general case. It is

easy to show (see e.g. [3]) that, if the matrix G has real eigenvalues μ_j such that

$$\mu_m \leq \mu_j \leq \mu_M < 1, \quad (1.7)$$

then $\rho(G_\omega) < 1$ iff $0 < \omega < 2/(1-\mu_m)$ and the spectral radius $\rho(G_\omega)$ is minimized if we take $\omega = \omega_{\text{opt}} = 2/(2-(\mu_m + \mu_M))$. Moreover, we have

$$\rho(G_{\omega_{\text{opt}}}) = (\mu_M - \mu_m) / (2 - (\mu_m + \mu_M)) < 1.$$

Therefore, in this case, the optimum extrapolation method is always convergent, although $\rho(G)$ is not necessarily less than one. It must be noted that (1.7) holds if G is the matrix B of the Jacobi method, corresponding to a positive definite matrix A of the original system. Then, the optimum JOR method [1] converges. We also note, that if G has real eigenvalues such that $1 < \mu_m \leq \mu_j \leq \mu_M$, then $\rho(G_\omega) < 1$ iff $2/(1-\mu_M) < \omega < 0$. Moreover, $\omega_{\text{opt}} = 2/(2-(\mu_m + \mu_M))$ and $\rho(G_{\omega_{\text{opt}}}) = (\mu_M - \mu_m) / (\mu_m + \mu_M - 2) < 1$.

In a recent work [4], a geometrical approach of the general case with $\rho(G) < 1$ is discussed, where the construction of a capturing circle of the spectrum of G is required.

In the next section we study extrapolation method (1.6) in order to find ranges for ω in which convergence is achieved in the general case.

2. CONVERGENCE THEORY.

First we observe that, if for some norm of G we have $\|G\| < 1$, then for $0 < \omega < 1$ we obtain

$$\|G_\omega\| = \|\omega G + (1-\omega)I\| \leq \omega\|G\| + 1-\omega < \omega + 1-\omega = 1;$$

that is, the extrapolation method converges. We assume now that,

$$\mu_j = \rho_j e^{i\theta_j}, \quad j = 1(1)n, \quad (2.1)$$

are the eigenvalues of G , where $0 \leq \rho_m \leq \rho_j \leq \rho_M = \rho(G)$, $i = (-1)^{\frac{1}{2}}$, $|\mu_j| = \rho_j$ and $\rho_m = \min_j \rho_j$, $\rho_M = \max_j \rho_j$. In the sequel we omit the subscript j in ρ_j , θ_j since no confusion can be made; that is, from now on ρ, θ are used in place of ρ_j, θ_j respectively. Evidently, the eigenvalues of G_ω are given by

$$\lambda_j = \omega \mu_j + 1 - \omega, \quad j = 1(1)n. \quad (2.2)$$

Therefore, for the spectral radius of G_ω , we have that

$$\begin{aligned}\rho(G_\omega) &= \max_j |\omega \mu_j + 1 - \omega| \leq \max_j \{|\omega \mu_j| + |1 - \omega|\} = |1 - \omega| + |\omega| \max_j |\mu_j| = \\ &= |1 - \omega| + |\omega| \rho(G).\end{aligned}\quad (2.3)$$

We examine now the convergence of method (1.6) in relation to that of method (1.2). We discuss four basic cases, the first two of which are rather trivial.

Case I: $\rho \equiv 0$. Here we assume that $\mu_j = 0$ for all j . Then $|\lambda_j| < 1$ iff $0 < \omega < 2$. It is obvious that the optimum value of ω , which minimizes $\rho(G_\omega)$, is $\omega_{\text{opt}} = 1$, since $\rho(G_1) = 0$.

Case II: $\rho \equiv 1$. Now we have that $|\mu_j| = 1$ for all j . Then, $|\lambda_j| < 1$ iff $2\omega(\omega - 1)(1 - \cos\theta) < 0$. If $\cos\theta \neq 1$, that is, if $\mu_j \neq 1$ for all j , then for $0 < \omega < 1$ we have $\rho(G_\omega) < 1$. If $\mu_j = 1$ for some j , then method (1.6) does not converge.

In the case where $\mu_j \neq 1$ for all j , we seek the optimum value of $\omega \in (0, 1)$ which minimizes $\rho(G_\omega)$. Suppose that

$$-1 \leq x_1 \leq x \leq x_2 < 1, \quad (2.4)$$

where $x = \cos\theta = \text{Re } \mu_j$. It is apparent that

$$\max_j |\lambda_j|^2 = 1 - 2\omega(1 - \omega)(1 - x_2)$$

and

$$\min_\omega \{\max_j |\lambda_j|\} = (\min_\omega [1 - 2\omega(1 - \omega)(1 - x_2)])^{\frac{1}{2}}.$$

By letting $f(\omega) = 1 - 2\omega(1 - \omega)(1 - x_2)$, we easily get that $\min_\omega f(\omega) = f(\frac{1}{2}) = (1 + x_2)/2$, which implies that

$$\min_\omega \rho(G_\omega) = \rho(G_{\omega_{\text{opt}}}) = \rho(G_{\frac{1}{2}}) = ((1 + \max_j \text{Re } \mu_j)/2)^{\frac{1}{2}}.$$

Remark If $\max_j \text{Re } \mu_j = -1$ (which is valid if $\mu_j = -1$ for all j), then we have $\rho(G_{\frac{1}{2}}) = 0$.

Case III: $0 < \rho_m \leq \rho \leq \rho_M = \rho(G) < 1$.

In this case $|\lambda_j| < 1$ iff

$$\omega^2(\rho^2 + 1 - 2\rho\cos\theta) + 2\omega(\rho\cos\theta - 1) < 0. \quad (2.5)$$

Assuming first that $\omega < 0$, (2.5) is equivalent to

$$\omega(\rho^2 + 1 - 2\rho\cos\theta) + 2(\rho\cos\theta - 1) > 0. \quad (2.6)$$

Since $\rho^2 + 1 - 2\rho \cos \theta \geq \rho^2 + 1 - 2\rho = (1 - \rho)^2 > 0$ and $1 - \rho \cos \theta \geq 1 - \rho > 0$, from (2.6) we obtain $\omega > 2(1 - \rho \cos \theta) / (\rho^2 + 1 - 2\rho \cos \theta) > 0$, which contradicts to the hypothesis. If now $\omega > 0$, then (2.5) is equivalent to

$$\omega(\rho^2 + 1 - 2\rho \cos \theta) + 2(\rho \cos \theta - 1) < 0, \quad (2.7)$$

which gives $0 < \omega < 2(1 - \rho \cos \theta) / (\rho^2 + 1 - 2\rho \cos \theta) \equiv g(\rho, \theta)$ for all μ_j , or equivalently

$$0 < \omega < \min_{\mu_j} g(\rho, \theta)$$

and the following theorem has been proved.

Theorem 2.1 If the method (1.2) converges ($\rho(G) < 1$), then the method (1.6) converges ($\rho(G_\omega) < 1$) iff $0 < \omega < \min_{\mu_j} \{2(1 - \rho \cos \theta) / (\rho^2 + 1 - 2\rho \cos \theta)\}$.

Remark It can be proved that $g(\rho, \theta) > 1$ for $\rho < 1$.

We now show that $\min_{\rho, \theta} g(\rho, \theta) = 2/(1 + \rho(G))$ for all ρ, θ such that

$$0 < \rho_m \leq \rho \leq \rho_M = \rho(G) < 1 \quad \text{and} \quad 0 \leq \theta < 2\pi.$$

We note that $\partial g / \partial (\cos \theta) = \rho(1 - \rho^2) / (\rho^2 + 1 - 2\rho \cos \theta)^2 > 0$ from which it follows that

$$\min_{\cos \theta} g(\rho, \theta) = g(\rho, \cos \theta = -1) = g(\rho, \theta = \pi) = 2/(1 + \rho)$$

and consequently

$$\min_{\rho, \theta} g(\rho, \theta) = \min_{\rho} (2/(1 + \rho)) = 2/(1 + \rho_M) = 2/(1 + \rho(G)).$$

Since, $2/(1 + \rho(G)) \leq \min_{\mu_j} g(\rho, \theta)$ (the equality holds if for some j we have

$\mu_j = -\rho(G)$), then by virtue of Theorem 2.1 the validity of the following two statements is easily established.

Corollary 2.2 If $\rho(G) < 1$, then $\rho(G_\omega) < 1$ for all $0 < \omega < 2/(1 + \rho(G)) < 2$.

Corollary 2.3 If the matrix G has at least one negative eigenvalue μ , such that $|\mu| = \rho(G) < 1$, then $\rho(G_\omega) < 1$ iff $0 < \omega < 2/(1 + \rho(G))$.

Proof: This follows from Theorem 2.1 since, in this case, we have

$$\min_{\mu_j} g(\rho, \theta) = \min_{\rho, \theta} g(\rho, \theta) = g(\rho(G), \pi) = 2/(1 + \rho(G)).$$

Theorem 2.4 If $\rho(G) < 1$, then $\rho(G_\omega) < 1$ for all $0 < \omega < 2(1 - x_m) / (\rho^2(G) + 1 - 2x_m)$,

where $x_m = \min x$, $x = \operatorname{Re} \mu_j = \rho \cos \theta$.

Proof: According to Theorem 2.1, it is sufficient to show that

$$2/(1+\rho(G)) \leq 2(1-x_m)/(\rho^2(G)+1-2x_m) \leq \min_{\mu_j} g(\rho, \theta). \quad (2.8)$$

Evidently, we have $-1 < x_m \leq x < 1$ and $-\rho(G) \leq x_m \leq \rho(G)$. Hence, $\rho^2(G)+1-2x_m \geq \rho^2(G)+1-2\rho(G) = (1-\rho(G))^2 > 0$. Thus, the first inequality in (2.8) is equivalent to

$$(\rho(G)+x_m)(\rho(G)-1) \leq 0. \quad (2.9)$$

Since $1-\rho(G) > 0$ and $\rho(G)+x_m \geq 0$, we conclude that (2.9) holds. To prove the second inequality in (2.8), it is sufficient to show that $2(1-x_m)/(\rho^2(G)+1-2x_m) \leq 2(1-\rho \cos \theta)/(\rho^2+1-2\rho \cos \theta)$ for all $\mu_j = \rho e^{i\theta}$, or equivalently, since $\rho \cos \theta = x$, that

$$\rho^2(1-x_m) - \rho^2(G)(1-x) + x_m - x \leq 0. \quad (2.10)$$

The inequality (2.10) can be written as follows

$$(1-x)(1-\rho^2(G)) \leq (1-x_m)(1-\rho^2).$$

The inequality above holds because of the relationships $0 < 1-x \leq 1-x_m$ and $0 < 1-\rho^2(G) \leq 1-\rho^2$.

Corollary 2.5 If the iteration matrix G of the method (1.2), has eigenvalues μ_j such that, $\operatorname{Re} \mu_j \geq 0$ for all j and $\rho(G) < 1$, then $\rho(G_\omega) < 1$ for all $0 < \omega < 2/(1+\rho^2(G))$.

Case IV: $0 \leq \rho_m \leq \rho \leq \rho_M$ and $\rho_m < 1 < \rho_M = \rho(G)$.

It is also assumed, in this case, that $\mu_j \neq 1$, $j = 1(1)n$. Consider now only those eigenvalues μ_j of G with $1 < \rho \leq \rho_M = \rho(G)$. Then $|\lambda_j| < 1$ iff

$$\omega^2(\rho^2+1-2\rho \cos \theta) + 2\omega(\rho \cos \theta - 1) < 0. \quad (2.11)$$

We distinguish two cases according to whether ω is less or greater than zero.

1. Let $\omega < 0$. Since $\rho^2+1-2\rho \cos \theta \geq (1-\rho)^2 > 0$, by virtue of (2.11) we have $\omega > 2(1-\rho \cos \theta)/(\rho^2+1-2\rho \cos \theta)$. In order that negative values for ω exist, we must have $1-\rho \cos \theta < 0$; Namely, the real parts of the eigenvalues, which we consider, must be > 1 . Since, according to Cases I, II, and III for the other eigenvalues of G with $0 \leq \rho_m \leq \rho < 1$, there is no convergence for $\omega < 0$, we conclude that ω can not take negative values.

2. Now let $\omega > 0$. Then (2.11) gives $\omega < 2(1-\rho \cos \theta)/(\rho^2+1-2\rho \cos \theta)$. In order that positive values for ω exist, we must have $\rho \cos \theta < 1$ or $\operatorname{Re} \mu_j < 1$ for tho-

se eigenvalues μ_j with $\rho > 1$. Considering now all the eigenvalues of G and taking into account the results of Cases I, II, and III, together with the observation that $2(1-\rho\cos\theta)/(\rho^2+1-2\rho\cos\theta) \leq 1$ for $\rho \geq 1$, the theorem below follows.

Theorem 2.6 If $\rho(G) > 1$ and $\operatorname{Re} \mu_j < 1$, $j = 1(1)n$, then $\rho(G_\omega) < 1$ iff $0 < \omega < \min_{\mu_j} g(\rho, \theta)$, where $g(\rho, \theta) = 2(1-\rho\cos\theta)/(\rho^2+1-2\rho\cos\theta)$.

Theorem 2.7 If $\rho(G) > 1$ and $\operatorname{Re} \mu_j \leq 0$, then $\rho(G_\omega) < 1$ for all $0 < \omega < 2/(1+\rho^2(G))$.

Proof: We prove that

$$2/(1+\rho^2(G)) \leq 2(1-\rho\cos\theta)/(\rho^2+1-2\rho\cos\theta) \text{ for all } \mu_j. \quad (2.12)$$

For this, because of the remark in Theorem 2.1, it is sufficient to show

(2.12) for $\rho > 1$ and $\rho\cos\theta \leq 0$. We observe that (2.12) is equivalent to

$$\rho^2 - 1 \leq (1-\rho\cos\theta)(\rho^2(G) - 1),$$

which holds because of $0 < \rho^2 - 1 \leq \rho^2(G) - 1$ and $1 \leq 1-\rho\cos\theta$.

The following Theorem is an immediate result of Case IV.

Theorem 2.8 If G has eigenvalues μ_j with $\rho > 1$, $j = 1(1)n$, then the following statements are valid.

1. If $\operatorname{Re} \mu_j > 1$, $j = 1(1)n$, then $\rho(G_\omega) < 1$ iff $\max_{\mu_j} g(\rho, \theta) < \omega < 0$.
2. If $\operatorname{Re} \mu_j < 1$, $j = 1(1)n$, then $\rho(G_\omega) < 1$ iff $0 < \omega < \min_{\mu_j} g(\rho, \theta)$,
where $g(\rho, \theta) = 2(1-\rho\cos\theta)/(\rho^2+1-2\rho\cos\theta)$.

Corollary 2.9 If G has eigenvalues μ_j with $\operatorname{Re} \mu_j > 1$, $j = 1(1)n$, then $\rho(G_\omega) < 1$ for all $2/(1-\rho(G)) < \omega < 0$.

Proof: The conclusion follows, in view of the Theorem 2.8, since we have

$$2(1-\rho\cos\theta)/(\rho^2+1-2\rho\cos\theta) \leq 2/(1-\rho(G)) \text{ for all } \mu_j; \text{ that is, } \max_{\mu_j} g(\rho, \theta) \leq 2/(1-\rho(G)).$$

If the method (1.2) is the Jacobi method (J) with iteration matrix B , then (1.6) is the extrapolation Jacobi method (JOR or EJ) with iteration matrix B_ω (see e.g. [1]). For these methods, by applying the previous results, we have.

Theorem 2.10 If all the eigenvalues of B are real with moduli > 1 , then the JOR method does not converge.

Proof: Since $\text{tr}(B) = 0$, the matrix B must have positive and negative eigenvalues with moduli > 1 . The proof now follows by theorem 2.8.

Theorem 2.11 If the Jacobi method (J) converges ($\rho(B) < 1$), then $\rho(B_\omega) < 1$ for all $0 < \omega < 2/(1+\rho(B)) < 2$.

The previous Theorem is more general than Theorem 1.1 [1, p. 107]. We also note that some of the results of this section are given in [5] in a different way.

In the sequel, we consider the case where the matrix G of the method (1.2) has eigenvalues μ_j with $0 \neq \rho(G) < 1$ and we seek to find values for ω such that

$$\rho(G_\omega) \leq \rho(G).$$

For this, we require $|\lambda_j| \leq |\mu_j|$ to hold for all j , where λ_j are the eigenvalues of G_ω , given by (2.2). Because of (2.1), we conclude that $|\lambda_j| \leq |\mu_j|$ iff

$$F(\omega) = \omega^2(\rho^2 + 1 - 2\rho\cos\theta) + 2\omega(\rho\cos\theta - 1) + 1 - \rho^2 \leq 0. \quad (2.13)$$

Since, $\rho^2 + 1 - 2\rho\cos\theta \geq (1-\rho)^2 > 0$ and the discriminant of $F(\omega)$ given by $D = 4\rho^2(\rho\cos\theta)^2 \geq 0$, it follows that (2.13) holds iff $\min(\omega_1, \omega_2) \leq \omega \leq \max(\omega_1, \omega_2)$, where ω_1, ω_2 are the two roots of $F(\omega)$ given by

$$\omega_1 = 1, \quad \omega_2 = (1 - \rho^2)/(\rho^2 + 1 - 2\rho\cos\theta). \quad (2.14)$$

We note that $\omega_2 > 1$ if $\rho^2 < \rho\cos\theta$, while $\omega_2 < 1$ if $\rho^2 > \rho\cos\theta$. Thus, the following Theorem has been proved.

Theorem 2.12 If G has eigenvalues μ_j with $0 \neq \rho(G) < 1$, then the following statements are valid.

1. If $\rho^2 < \text{Re } \mu_j$ for all j , then $\rho(G_\omega) \leq \rho(G)$ for all $1 \leq \omega \leq \min_{\mu_j} \{(1 - \rho^2)/(\rho^2 + 1 - 2\text{Re } \mu_j)\}$.
2. If $\rho^2 > \text{Re } \mu_j$ for all j , then $\rho(G_\omega) \leq \rho(G)$ for all $\max_{\mu_j} \{(1 - \rho^2)/(\rho^2 + 1 - 2\text{Re } \mu_j)\} \leq \omega \leq 1$.

Remark The restriction $\rho^2 < \text{Re } \mu_j$ implies that $\rho < 1$ and thus $\rho(G) < 1$, while this is not true if $\rho^2 > \text{Re } \mu_j$.

Letting $\mu_j = x + iy$, where $x = \text{Re } \mu_j$ and $y = \text{Im } \mu_j$, we have $\rho^2 = x^2 + y^2$. Then the following lemma, which can be easily shown, gives ranges for x and y such that either $\rho^2 < x$ or $\rho^2 > x$ and $\rho < 1$.

Lemma 2.13

$$1. \rho^2 < x$$

iff $|y| < 1/2$ and $(1-k)/2 < x < (1+k)/2$, where $k = (1-4y^2)^{1/2}$.

2. $\rho^2 > x$ and $\rho < 1$ iff anyone of the following statements holds

$$i) -1 < x < 0 \quad \text{and} \quad |y| < (1-x^2)^{1/2}$$

$$ii) -1 < y < -1/2 \quad \text{or} \quad 1/2 \leq y < 1 \quad \text{and} \quad 0 < x < (1-y^2)^{1/2}$$

$$iii) |y| < 1/2 \quad \text{and} \quad (1+k)/2 < x < (1-y^2)^{1/2} \quad \text{or} \quad 0 < x < (1-k)/2, \quad \text{where} \quad k = (1-4y^2)^{1/2}.$$

As an application of Theorem 2.12, we consider the following examples.

1. Let the matrix G have eigenvalues

$$\mu_1 = \frac{2}{3} + \frac{1}{4}i, \quad \mu_2 = \frac{2}{3} - \frac{1}{4}i, \quad \mu_3 = \frac{1}{2} + \frac{1}{5}i, \quad \mu_4 = \frac{1}{2} - \frac{1}{5}i$$

satisfying $\rho^2 < \operatorname{Re} \mu_j$, $j = 1, 2, 3, 4$.

Therefore

$$\rho(G_\omega) < \rho(G) \quad \text{for all } \omega \in (1, \min_{\mu_j} \{(1-\rho^2)/(\rho^2+1-2\operatorname{Re} \mu_j)\}) \equiv (1, 2.4483).$$

It must be noted that $\rho(G) \approx 0.7120$, while

$$\min_{\omega \in (1, 2.4483)} \rho(G_\omega) = \rho(G_{1.92}) = 0.6.$$

2. Suppose that G has eigenvalues

$$\mu_1 = -\frac{2}{3}, \quad \mu_2 = -\frac{1}{2} + \frac{3}{4}i, \quad \mu_3 = -\frac{1}{2} - \frac{3}{4}i$$

satisfying $\rho^2 > \operatorname{Re} \mu_j$, $\rho < 1$, $j = 1, 2, 3$.

Hence, we have

$$\rho(G_\omega) < \rho(G) \quad \text{for all } \omega \in (\max_{\mu_j} \{(1-\rho^2)/(\rho^2+1-2\operatorname{Re} \mu_j)\}, 1) \equiv (0.2, 1).$$

Moreover, we find that $\rho(G) \approx 0.9014$ and

$$\min_{\omega \in (0.2, 1)} \rho(G_\omega) = \rho(G_{24/45}) \approx 0.4472.$$

3. CONCLUDING REMARKS

From the previous convergence results of section 2, it is clear, that in order to be possible to find ranges for ω such that $\rho(G_\omega) < 1$, either $\operatorname{Re} \mu_j < 1$ or $\operatorname{Re} \mu_j > 1$ must hold for all the eigenvalues μ_j , $j = 1(1)n$ of G . For practical purposes and in a case which is not a special one, the choice

of ω_{opt} is made computationally, since, the range for ω for which $\rho(G_\omega) < 1$ is known.

Finally, we note that the Accelerated Overrelaxation (AOR) method studied in [6], which in turn was an extension of the corresponding one introduced by Hadjidimos [7], is an extrapolation of an obvious extension of the well known Successive Overrelaxation method (SOR) (see e.g. [8], [1]). Also, in a paper of Niethammer [9], an extrapolation of the SOR is studied. Thus, all the theory developed in this paper could be applied to the extrapolation method based on SOR in order to obtain better rates of convergence.

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This subject has been extensively studied in the past years for one-, two-, and three-dimensional space. Additionally, such dynamical systems can exhibit a very important and still unexplained phenomenon, called as the Fermi acceleration phenomenon. Basically, the phenomenon of Fermi acceleration (FA) is a process in which a classical particle can acquire unbounded energy from collisions with a heavy moving wall. This phenomenon was originally proposed by Enrico Fermi in 1949 as a possible explanation of the origin of the large energies of the cosmic particles. His original model was then modified and considered under different approaches and using many versions. Moreover, applications of FA have been of a large broad interest in many different fields of science including plasma physics, astrophysics, atomic physics, optics, and time-dependent billiard problems and they are useful for controlling chaos in Engineering and dynamical systems exhibiting chaos (both conservative and dissipative chaos).

We intend to publish in this special issue papers reporting research on time-dependent billiards. The topic includes both conservative and dissipative dynamics. Papers discussing dynamical properties, statistical and mathematical results, stability investigation of the phase space structure, the phenomenon of Fermi acceleration, conditions for having suppression of Fermi acceleration, and computational and numerical methods for exploring these structures and applications are welcome.

To be acceptable for publication in the special issue of Mathematical Problems in Engineering, papers must make significant, original, and correct contributions to one or more of the topics above mentioned. Mathematical papers regarding the topics above are also welcome.

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