

CR-HYPERSURFACES OF THE SIX-DIMENSIONAL SPHERE

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ABSTRACT. We proved that there does not exist a proper *CR*-hypersurface of S^6 with parallel second fundamental form. As a result of this we showed that S^6 does not admit a proper *CR*-totally umbilical hypersurface. We also proved that an Einstein proper *CR*-hypersurface of S^6 is an extrinsic sphere.

KEY WORDS AND PHRASES. Nearly Kaehler manifold, *CR*-submanifold, six-dimensional sphere, Einstein hypersurface totally umbilical.

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1. INTRODUCTION.

It is known that of all the Euclidean spheres S^2 and S^6 admit the almost complex structure of which S^2 is complex and S^6 is not. It is also known that S^6 is an almost hermitian manifold which is nearly Kaehler but not Kaehler [4], that is, the almost complex structure is not parallel with respect to the Riemannian connection on S^6 . Among all submanifolds of an almost Hermitian manifold, there are three typical classes; one is the class of holomorphic submanifold, one is the class of totally real submanifolds and the third is the class of *CR*-submanifolds. This last class was introduced by Bejancu [1]. Let (\bar{M}, J, g) be an almost Hermitian manifold with almost Hermitian structure (J, g) and M be a Riemannian submanifold of \bar{M} . The M is called a *CR*-submanifold of \bar{M} if there exists a *CR*-holomorphic distribution D , i.e., $JD = D$ on M such that its orthogonal complement D^\perp is totally real, i.e., $JD^\perp \subset \nu$ where ν is the normal bundle over M in \bar{M} . A *CR*-submanifold is called proper if neither $D = 0$, nor $D^\perp = 0$. The three classes of submanifolds of S^6 , including *CR*-submanifolds, have been studied by several authors [2], [3], [5]. In this paper, we consider *CR*-hypersurfaces of S^6 . We obtain the following results:

THEOREM 1. There does not exist a proper *CR*-hypersurface of S^6 with parallel second fundamental form.

THEOREM 2. S^6 does not admit a proper *CR*-totally umbilical hypersurface.

THEOREM 3. Let M be an Einstein proper *CR*-hypersurface of S^6 , then M is an extrinsic sphere.

PRELIMINARIES. Let (\bar{M}, g) be a Riemannian manifold and M be a Riemannian submanifold of \bar{M} . Let ∇ (resp. $\bar{\nabla}$) be the Riemannian connection on M (resp. \bar{M}) and R (resp. \bar{R}) be the curvature tensor of M (resp. \bar{M}). Denote by h the second fundamental form of M in \bar{M} . Then the Gauss formula and the Weingarten formula are given respectively by

$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y) \quad (1.1)$$

$$\bar{\nabla}_X N = -A_N X + \frac{1}{2} \bar{\nabla}_X N \quad X, Y \in \mathfrak{S}(M) \quad (1.2)$$

where $-A_N X$ (resp. $\frac{1}{2} \bar{\nabla}_X N$) denotes the tantial part (resp. normal part) of $\bar{\nabla}_X N$. The tangential component $A_N X$ is related to the second fundamental form by

$$g(h(X, Y), N) = g(A_N X, Y), \quad X, Y \in \mathfrak{S}(M).$$

The Gauss equation is given by

$$g(R(X, Y)Z, W) = g(\bar{R}(X, Y)Z, W) + g(h(X, W), h(Y, Z)) - g(h(X, Z), h(Y, W)) \quad (1.3)$$

The Codazzi equation is

$$g(\bar{R}(X, Y)Z, N) = g((\bar{\nabla}_X h)(Y, Z) - (\bar{\nabla}_Y h)(X, Z), N) \quad (1.4)$$

where

$$(\bar{\nabla}_X h)(Y, Z) = \frac{1}{2} \bar{\nabla}_X h(Y, Z) - h(\nabla_X Y, Z) - h(Y, \nabla_X Z)$$

If (e_i) $i = 1, 2, \dots, n$ is a frame field for M , then the Ricci curvature S of M is given by

$$S(X, Y) = \sum_{i=1}^n R(e_i, X, Y, e_i).$$

The submanifold M is called an Einstein manifold if $S(X, Y) = cg(X, Y)$ for some constant c and any $X, Y \in \mathfrak{S}(M)$. M is said to be totally umbilical if $h(X, Y) = g(X, Y)H$ where H is the mean curvature vector defined by $H = \frac{1}{n} \text{trace } h$.

M is called an extrinsic sphere if $\frac{1}{2} \bar{\nabla}_X H = 0$ for any $X \in \mathfrak{S}(M)$. The CR-submanifold M is called a CR-product submanifold if it is locally the Riemannian product of a holomorphic submanifold and a totally real submanifold. Sekigawa [6] proved that in S^6 there does not exist any CR-product submanifolds.

2. PROOF OF THE MAIN RESULTS.

PROOF OF THEOREM 1. Since the second fundamental form is parallel we have $(\nabla_W A)(V) = 0$ or $\nabla_W A V = A \nabla_W V$ for any $V, W \in \mathfrak{S}(M)$. If V is an eigenvector of A with corresponding eigenvalue β , i.e., $AV = \beta V$, then from the equation $\nabla_W(AV) = A \nabla_W V$ we get $\beta \nabla_W V = A \nabla_W V$. This means that $\nabla_W V$ is an eigenvector corresponding to eigenvalue β whenever V is. If T is the eigenspace of β then $\nabla_W T \subset T$.

Since M is a proper CR-hypersurface of S^6 , we can take $\{E_1, JE_1, E_2, JE_2, \xi\}$ as an orthonormal frame field for TM where $E_1, E_2 \in D$ and $\xi \in D^\perp$. Also since the normal bundle is 1-dimensional we assume that the frame $\{E_1, JE_1, E_2, JE_2, \xi\}$ diagonalizes A . So let $AE_1 = \alpha_1 E_1$, $AJE_1 = \bar{\alpha}_1 JE_1$, $AE_2 = \alpha_2 E_2$, $AJE_2 = \bar{\alpha}_2 JE_2$ and $A\xi = \beta\xi$. We consider the two cases for the eigenvalues $\alpha_i, \bar{\alpha}_i, \beta$ $i = 1, 2$.

CASE 1: $\alpha_i \neq \beta$ and $\bar{\alpha}_i \neq \beta$ for all $i = 1, 2$.

In this case we have $g(\nabla_W \xi, E_i) = g(\nabla_W \xi, JE_i) = 0$ for all $W \in \mathfrak{S}(M)$. This gives $\nabla_W \xi \in D^\perp$, i.e., the distribution D^\perp is parallel. Since $\nabla_W \xi \in D$ we get $\nabla_W \xi = 0$. This last equation with $g(\xi, X) = 0$ for $X \in D$ gives $\nabla_W X \in D$, i.e., the distribution D is also parallel. This implies that M is a CR-product, a contradiction, since S^6 does not admit any CR-product submanifold [6].

CASE 2: $\alpha_{i_o} = \beta$ or $\bar{\alpha}_{i_o} = \beta$ for some i_o .

Without loss of generality let us assume that $\alpha_{i_o} = \beta$ for some i_o . Then the space T spanned by $\{E_{i_o}, \xi\}$ is the eigenspace of eigenvalue $\beta = \alpha_{i_o}$. We then have $\nabla_W T \subset T$. In particular

$\nabla_{E_{i_o}}\xi = aE_{i_o} + b\xi$ for some functions a and b . Since $g(\nabla_{E_{i_o}}\xi, \xi) = 0$, we get $\nabla_{E_{i_o}}\xi = aE_{i_o}$. Also using the equation $\bar{\nabla}_{E_{i_o}JE_{i_o}} = J\bar{\nabla}_{E_{i_o}E_{i_o}}$ with the help of equations (1.1) and (1.2) and the fact that $h \in JD^\perp$ we get $g(\nabla_{E_{i_o}}E_{i_o}, \xi) = 0$. From which we get $g(\nabla_{E_{i_o}}\xi, E_{i_o}) = 0$, i.e., $\nabla_{E_{i_o}}\xi = 0$. Now using this last equation and the fact that $\nabla_\xi\xi = 0$, we get

$$R(E_{i_o}, \xi)\xi = \nabla_{E_{i_o}}\nabla_\xi\xi - \nabla_\xi\nabla_{E_{i_o}}\xi - \nabla_{[E_{i_o}, \xi]}\xi = \frac{\nabla_\xi}{\xi}E_{i_o}\xi.$$

But $\nabla_\xi E_{i_o} = cE_{i_o} + d\xi = 0$ since $g(\nabla_\xi E_{i_o}, E_{i_o}) = 0$. $g(\nabla_\xi E_{i_o}, \xi) = -g(\nabla_\xi\xi, E_{i_o}) = 0$. So $R(E_{i_o}, \xi)\xi = 0$. However from Gauss equation we obtain $g(R(E_{i_o}, \xi)\xi, E_{i_o}) = c + \beta^2 > 0$ which is a contradiction. This finishes the proof of Theorem 1.

PROOF OF THEOREM 2. Since M is totally umbilical we have $h(X, Y) = g(X, Y)H$ for any $X, Y \in \mathfrak{S}(M)$. Using this in Codazzi equation (1.4) we get $g(R(X, Y)Z, N) = g(g(Y, Z)\bar{\nabla}_XH - g(X, Z)\bar{\nabla}_YH, N)$. Since the ambient space S^6 is of constant curvature we have $g(g(Y, Z)\bar{\nabla}_XH - g(X, Z)\bar{\nabla}_YH, N) = 0$, $X, Y, Z \in \mathfrak{S}(M)$. Now for any $X \in \mathfrak{S}(M)$, choose Y such that $g(Y, X) = 0$ and let $Z = Y$. Then the above equation gives $\bar{\nabla}_XH = 0$, i.e., H is parallel. Using a frame field (E_i) , $1 \leq i \leq 5$ with E_5 in D^\perp and the rest in D , one can write $H = \gamma JE_5$ for some constant γ . Also the equation $h(X, Y) = g(X, Y)H$ gives $h(E_i, E_i) = \gamma JE_5$, and $h(E_i, E_j) = 0$ for $i \neq j$. Note that in this case

$$\begin{aligned} (\bar{\nabla}_{E_i}h)(E_j, E_k) &= \bar{\nabla}_{E_i}h(E_j, E_k) - h(\nabla_{E_i}E_j, E_k) - h(E_j, \nabla_{E_i}E_k) \\ &= E_i g(E_j, E_k)H = 0 \text{ for all } i, j. \end{aligned}$$

where we have used the equation $h(X, Y) = g(X, Y)H$ in the second equality. This means that M has parallel second fundamental form. Then using Theorem 1 we obtain Theorem 2.

PROOF OF THEOREM 3. Let $\{X, Y, JX, JY, Z\}$ be an orthonormal frame for TM where $X, Y \in D$ and $Z \in D^\perp$. Since M is a hypersurface we know that the above frame diagonalizes A . Therefore one can write

$$h(Z, Z) = \alpha JZ, h(X, X) = \beta JZ, h(JX, JX) = \gamma JZ, h(Y, Y) = \delta JZ, h(JY, JY) = \eta JZ$$

and

$$h(Z, X) = h(Z, JX) = h(Z, Y) = h(Z, JY) = h(X, JX) = h(X, Y) = h(X, JY) = h(Y, JY) = 0$$

where $\alpha, \beta, \gamma, \delta, \eta$ are smooth functions on M . Then using Guass equation (1.3) we get

$$S(Z, Z) = R(X, Z, Z, X) + R(JX, Z, Z, JX) + R(Y, Z, Z, Y) + R(JY, Z, Z, JX) = 4c + \alpha(\beta + \gamma + \delta + \eta)$$

Similarly

$$S(X, X) = 4c + \beta(\alpha + \gamma + \delta + \eta)$$

$$S(JX, JX) = 4c + \gamma(\alpha + \beta + \delta + \eta)$$

$$S(Y, Y) = 4c + \delta(\alpha + \beta + \gamma + \eta)$$

$$S(JY, JY) = 4c + \eta(\alpha + \beta + \delta + \eta)$$

Since M is Einstein we have

$$S(Z, Z) = S(X, X) = S(JX, JX) = S(Y, Y) = S(JY, JY) = \text{constant}$$

i.e.,

$$\alpha(\beta + \gamma + \delta + \eta) = \beta(\alpha + \gamma + \delta + \eta) = \gamma(\alpha + \beta + \delta + \eta) = \delta(\alpha + \beta + \gamma + \eta) = \eta(\alpha + \beta + \gamma + \delta) = \text{const.}$$

(i)

(ii)

(iii)

(iv)

(v)

We shall show that $\alpha, \beta, \gamma, \delta$ and η are constants. From the above equations we have:

$$\begin{aligned}\alpha(\gamma + \delta + \eta) &= \beta(\gamma + \delta + \eta), & \beta(\alpha + \delta + \eta) &= \gamma(\alpha + \delta + \eta) \\ \gamma(\alpha + \beta + \eta) &= \delta(\alpha + \beta + \eta), & \delta(\alpha + \beta + \gamma) &= \eta(\alpha + \beta + \gamma)\end{aligned}$$

We seek all solutions for this system. One obvious solution is $\alpha = \beta = \gamma = \delta = \eta = \text{const.}$. The other possible solutions are the following cases:

(a) $\gamma + \delta + \eta = \alpha + \delta + \eta = \alpha + \beta + \eta = \alpha + \beta + \gamma = 0$

In this case we have $\alpha = \gamma = \eta = \text{const.}$ and $\delta = \beta$ considering (i) and (iv) with $\delta = \beta$ we get $\delta = \beta = \alpha = \text{const.}$ or $\delta = \beta = -2\alpha = \text{const.}$ So for this case $\alpha, \beta, \gamma, \delta, \eta$ are constants.

(b) $\alpha = \beta, \alpha + \delta + \eta = \alpha + \beta + \eta = \alpha + \beta + \gamma = 0$, i.e., $\alpha = \beta = \delta$ and $\eta = \gamma$. Using (ii) and (v) with $\alpha = \beta = \delta$ we get $\eta = \gamma = \alpha = \text{const.}$ or $\eta = \gamma = -2\alpha = \text{const.}$, i.e., $\alpha, \beta, \gamma, \delta, \eta$ are constants.

(c) $\alpha = \beta = \gamma, \alpha + \beta + \eta = \alpha + \beta + \gamma = 0$, i.e., $\alpha = \beta = \gamma = \eta$. Using (i) and (iv) with this last equation we get $\alpha = \beta = \gamma = \eta = \delta = \text{const.}$ (Note that in case $\alpha = \beta = \gamma = \delta = 0$, then M is totally geodesic and hence $\delta = 0$).

(d) $\alpha = \beta = \gamma = \delta, \alpha + \beta + \gamma = 0$, i.e., $\alpha = \beta = \gamma = \delta = 0$. Following the note in (c) we have $\eta = 0$.

Therefore in all cases $\alpha = \beta = \gamma = \delta = \eta = \text{const.}$ We conclude that $H = \alpha JZ$ where α is constant and thus $\nabla_V^\perp H = 0$ for any $V \in \mathfrak{X}(M)$, i.e., M is an extrinsic sphere.

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