

## APPLICATION OF UNIFORM ASYMPTOTICS TO THE FIFTH PAINLEVÉ TRANSCENDANT

YOU MIN LU and ZHOU DE SHAO

Received 30 August 2001

We apply the uniform asymptotics method to the fifth Painlevé transcendents, find its asymptotics of the form  $y = -1 + t^{-1/2}A(t)$  as  $t \rightarrow \infty$  along the positive  $t$ -axis, and obtain the corresponding monodromy data.

2000 Mathematics Subject Classification: 34E05.

**1. Introduction.** We study the general fifth Painlevé equation

$$\begin{aligned} \frac{d^2 y}{dt^2} = & \left( \frac{1}{2y} + \frac{1}{y-1} \right) \left( \frac{dy}{dt} \right)^2 - \frac{1}{t} \frac{dy}{dt} \\ & + \frac{(y-1)^2}{t^2} \left( \alpha y + \frac{\beta}{y} \right) + \frac{y y'}{t} + \frac{\delta y(y+1)}{y-1}, \end{aligned} \quad (1.1)$$

where  $\alpha, \beta, \gamma$ , and  $\delta$  are parameters, and its solution of the form

$$\begin{aligned} y(t) &= -1 + 4t^{-1/2}A(t), \\ y'(t) &= -2t^{-3/2}A(t) + 4t^{-1/2}A'(t) = 4t^{-1/2}A'(t) + O(t^{-3/2}), \end{aligned} \quad (1.2)$$

with  $A(t) = O(1)$  as  $t \rightarrow \infty$ .

The fifth Painlevé equation (1.1) can be obtained as the compatibility condition of the following linear systems of equations (see [2, 3]):

$$Y'_z(z) = \begin{pmatrix} \frac{t}{2} + \frac{2v + \theta_0}{2z} - \frac{w}{z-1} & -\frac{u(v + \theta_0)}{z} + \frac{uy(2w - \theta_1)}{2(z-1)} \\ \frac{v}{uz} - \frac{2w + \theta_1}{2uy(z-1)} & -\frac{t}{2} - \frac{2v + \theta_0}{2z} + \frac{w}{z-1} \end{pmatrix} Y(z), \quad (1.3)$$

$$Y'_t(z) = \begin{pmatrix} \frac{1}{2} & \frac{u}{z} \left[ v + \theta_0 - y \left( w - \frac{\theta_1}{2} \right) \right] \\ \frac{1}{uz} \left[ v - \frac{1}{y} \left( w + \frac{\theta_1}{2} \right) \right] & -\frac{1}{2} \end{pmatrix} Y(z), \quad (1.4)$$

where

$$w = v + \frac{1}{2}(\theta_0 + \theta_\infty), \quad (1.5)$$

$$\begin{aligned} t \frac{dy}{dt} &= ty - 2v(y-1)^2 - \frac{1}{2}(y-1)[(\theta_0 - \theta_1 + \theta_\infty)y - (3\theta_0 + \theta_1 + \theta_\infty)], \\ t \frac{du}{dt} &= u \left\{ -2v - \theta_0 + y \left[ v + \frac{1}{2}(\theta_0 - \theta_1 + \theta_\infty) \right] + \frac{1}{y} \left[ v + \frac{1}{2}(\theta_0 + \theta_1 + \theta_\infty) \right] \right\}, \end{aligned} \quad (1.6)$$

with

$$\alpha = \frac{1}{2} \left( \frac{\theta_0 - \theta_1 + \theta_\infty}{2} \right)^2, \quad \beta = -\frac{1}{2} \left( \frac{\theta_0 - \theta_1 - \theta_\infty}{2} \right)^2, \quad \gamma = 1 - \theta_0 - \theta_1, \quad \delta = -\frac{1}{2}. \quad (1.7)$$

The canonical solutions of system (1.3) are defined in [2] by

$$\begin{aligned} -\frac{3\pi}{2} + k\pi &\leq \arg \lambda < -\frac{\pi}{2} + k\pi, \\ Y_k(\lambda) &\sim \hat{Y}_\infty(\lambda) e^{(t\lambda/2 - \log \lambda)\sigma_3}, \end{aligned} \quad (1.8)$$

where  $\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ , and the Stokes multiplier  $G_1$  is defined in [2] by

$$Y_2(\lambda) = Y_1(\lambda)G_1, \quad (1.9)$$

where  $G_1 = \begin{pmatrix} 1 & 0 \\ s & 1 \end{pmatrix}$  and its entry  $s$  is independent of  $t$  and  $\gamma$ .

**2. Reduction of the problem.** Generally, if  $(d/dz) \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix} = \begin{pmatrix} A & B \\ C & -A \end{pmatrix} \begin{pmatrix} Y_1 \\ Y_2 \end{pmatrix}$ ,  $\phi = B^{-1/2}Y_1$ , and  $\psi = C^{-1/2}Y_2$ , then

$$\begin{aligned} \frac{d^2\phi}{dz^2} &= \left( A^2 + BC + A' - B'B^{-1}A + \frac{3}{4}B^{-2}B'^2 - \frac{1}{2}B^{-1}B'' \right) \phi, \\ \frac{d^2\psi}{dz^2} &= \left( A^2 + BC - A' + C'C^{-1}A + \frac{3}{4}C^{-2}C'^2 - \frac{1}{2}C^{-1}C'' \right) \psi. \end{aligned} \quad (2.1)$$

We first apply the transformation

$$\hat{Y} = \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} u^{-(1/2)\sigma_3} Y \quad (2.2)$$

to system (1.3) to get

$$\frac{d\hat{Y}}{dz} = \frac{1}{2} \begin{pmatrix} L & N \\ M & -L \end{pmatrix} \hat{Y}, \quad (2.3)$$

where

$$\begin{aligned} L &= \frac{i(2v + \theta_0)}{z} - \frac{i(1/\gamma + \gamma)w + i(1/\gamma - \gamma)(\theta_1/2)}{z-1}, \\ M &= \frac{i(2v + \theta_0) - \theta_0}{z} + \frac{(\gamma - 1/\gamma - 2i)w - (\gamma + 1/\gamma)(\theta_1/2)}{z-1} + it, \\ N &= -\frac{i(2v + \theta_0) + \theta_0}{z} + \frac{(\gamma - 1/\gamma + 2i)w - (\gamma + 1/\gamma)(\theta_1/2)}{z-1} - it. \end{aligned} \quad (2.4)$$

Applying (2.1) to (2.3), we get

$$\begin{aligned}
 \frac{d^2\phi}{dz^2} = & \left\{ \left( \frac{t}{2} + \frac{2v+\theta_0}{2z} - \frac{w}{z-1} \right)^2 + \left[ -\frac{u(v+\theta_0)}{z} + \frac{uy(2w-\theta_1)}{2(z-1)} \right] \left[ \frac{v}{uz} - \frac{2w+\theta_1}{2uy(z-1)} \right] \right. \\
 & - \frac{i(2v+\theta_0)}{2z^2} + \frac{i\left(\frac{1}{y}+y\right)w + i\left(\frac{1}{y}-y\right)\frac{\theta_1}{2}}{2(z-1)^2} \\
 & - \left[ \frac{2iv + (i+1)\theta_0}{z^2} - \frac{\left(y - \frac{1}{y} + 2i\right)w - \left(y + \frac{1}{y}\right)\frac{\theta_1}{2}}{(z-1)^2} \right] \frac{L}{2} \\
 & - \frac{N}{N} \\
 & + \frac{3}{4} \left[ \frac{2iv + (i+1)\theta_0}{z^2} - \frac{\left(y - \frac{1}{y} + 2i\right)w - \left(y + \frac{1}{y}\right)\frac{\theta_1}{2}}{(z-1)^2} \right] \frac{L}{N^2} \\
 & \left. - \frac{-\frac{2iv + (i+1)\theta_0}{z^3} + \left(y - \frac{1}{y} + 2i\right)w - \left(y + \frac{1}{y}\right)\frac{\theta_1}{2}}{N} \right\} \phi.
 \end{aligned} \tag{2.5}$$

Now, using (1.6), the following asymptotics can be obtained:

$$\begin{aligned}
 v(t) &= -\frac{1}{8}t - \frac{1}{2}t^{1/2}A'(t) + \frac{1}{2}A^2(t) - 2A(t)A'(t) - \frac{1}{2}\theta_0 - \frac{1}{4}\theta_\infty + O(t^{-1/2}), \\
 u(t) &= Ce^{t/2}(1 + O(t^{-1/2})).
 \end{aligned} \tag{2.6}$$

Substituting (2.6) into (2.5), we get the following second-order equation:

$$\begin{aligned}
 \frac{d^2\phi}{dz^2} &= -t^2 \left\{ -\frac{(2z-1)^2}{16z(z-1)} - t^{-1} \left[ -\frac{(2z-1)\theta_\infty}{4z(z-1)} - \frac{A^2 + 4A'^2}{4z(z-1)} + \frac{i(2z^2 - 2z + 1)}{8z^2(z-1)^2} \right. \right. \\
 &\quad \left. \left. + \frac{i(2z-1)[(it/4)(2z-1) + t^{1/2}Az^2]}{8z^2(z-1)^2[-it^{1/2}A' - t^{1/2}Az - it(z-1/2)^2]} \right] + O(t^{-3/2}) \right\} \phi \\
 &= -t^2 F(z, t) \phi.
 \end{aligned} \tag{2.7}$$

Equation (2.7) has two turning points

$$z_j = \frac{1}{2} \pm t^{-1/2} \sqrt{A^2 + 4A'^2 + i}(1 + o(1)), \quad j = 1, 2 \tag{2.8}$$

which merge to  $1/2$  as  $t \rightarrow \infty$ , and Stokes directions

$$\operatorname{Re} \left( \sqrt{z(z-1)} \right) = 0. \quad (2.9)$$

Now, we define a constant  $\alpha$  by

$$\frac{1}{2} \pi i \alpha^2 = \int_{-\alpha}^{\alpha} (\tau^2 - \alpha^2)^{1/2} d\tau = \int_{z_1}^{z_2} F^{1/2}(z, t) dz \quad (2.10)$$

and a new variable  $\zeta$  by

$$\int_{\alpha}^{\zeta} (\tau^2 - \alpha^2)^{1/2} d\tau = \int_{z_1}^z F^{1/2}(s, t) ds. \quad (2.11)$$

Using [1, Theorem 1], we have the following theorem.

**THEOREM 2.1.** *Given any solution  $\phi$  of (2.7), there exist constants  $c_1$  and  $c_2$  such that, uniformly for  $z$  on the Stokes curve, as  $t \rightarrow \infty$ ,*

$$\left( \frac{\zeta^2 - \alpha^2}{F(z, t)} \right)^{-1/4} \phi(z, t) = \left\{ (c_1 + o(1)) D_{\nu} \left( e^{\pi i/4} \sqrt{2t} \zeta \right) + (c_2 + o(1)) D_{-\nu-1} \left( e^{-\pi i/4} \sqrt{2t} \zeta \right) \right\}, \quad (2.12)$$

where  $\nu = -1/2 + (1/2)it\alpha^2$  and  $D_{\nu}(z)$ ,  $D_{-\nu-1}(z)$  are solutions of the parabolic cylinder equation.

### 3. Monodromy data and asymptotics

**THEOREM 3.1.** *For large  $t$  and  $z$ ,*

$$\begin{aligned} & \frac{1}{2} \zeta^2 - \frac{A^2 + 4A'^2 + i}{2t} \log \zeta + o(t^{-1}) \\ &= \frac{iz}{2} - \frac{i\theta_{\infty}}{2t} \log(4z) + \frac{i}{2t} \log \frac{2it^{1/2}}{2iA' + A} + \frac{1-i}{4} - \frac{\pi\theta_{\infty}}{4t} \\ & \quad - \frac{\pi i \alpha^2}{4} + o(t^{-1}) + O(z^{-1}). \end{aligned} \quad (3.1)$$

**PROOF.** Carrying out the integration on the left-hand side of (2.11), we have

$$\frac{1}{2} \zeta^2 - \frac{\alpha^2}{2} \log(2\zeta) - \frac{\alpha^2}{4} + \frac{\alpha^2}{2} \log \alpha + O(\alpha^4 \zeta^{-2}) = \int_{z_1}^z F^{1/2}(s, t) ds. \quad (3.2)$$

Because we are going to calculate the higher-order part of the right-hand side, we will simply ignore the lower-order part in  $F(z, t)$ , and split the right-hand side into two integrals

$$\int_{z_1}^z F^{1/2}(s, t) ds = \left( \int_{z_1}^{z^*} + \int_{z^*}^z \right) F^{1/2}(x, t) dx = I_1 + I_2, \quad (3.3)$$

where  $z^* = 1/2 + Tt^{-1/2}$  and  $T$  is a large parameter to be specified later. Using the substitution

$$x - \frac{1}{2} = st^{-1/2}, \quad (3.4)$$

$I_1$  can be evaluated as follows:

$$\begin{aligned} I_1 &= \frac{1}{t} \int_{\sqrt{A^2+4A'^2}}^T \left( \sqrt{s^2 - (A^2 + 4A'^2 + i)} + o(1) \right) ds \\ &= \frac{T^2}{2t} - \frac{A^2 + 4A'^2 + i}{4t} - \frac{A^2 + 4A'^2 + i}{2t} \log(2T) \\ &\quad + \frac{A^2 + 4A'^2 + i}{4t} \log(A^2 + 4A'^2 + i) + o(t^{-1}). \end{aligned} \quad (3.5)$$

Using the formula

$$\begin{aligned} &\int \frac{2ax + b}{(ax^2 + bx + c)\sqrt{x^2 - \frac{1}{4}}} dx \\ &= 2a \frac{\left( \operatorname{arctanh} \frac{a + 2bx - 2\sqrt{(b^2 - 4ac)}x}{\sqrt{(2b^2 - 2b\sqrt{(b^2 - 4ac)} - 4ac - a^2)}\sqrt{(4x^2 - 1)}} \right)}{\sqrt{(2b^2 - 2b\sqrt{(b^2 - 4ac)} - 4ac - a^2)}} \\ &\quad + 2a \frac{\operatorname{arctanh} \frac{a + 2bx + 2\sqrt{(b^2 - 4ac)}x}{\sqrt{(2b^2 + 2b\sqrt{(b^2 - 4ac)} - 4ac - a^2)}\sqrt{(4x^2 - 1)}}}{\sqrt{(2b^2 + 2b\sqrt{(b^2 - 4ac)} - 4ac - a^2)}}, \end{aligned} \quad (3.6)$$

we find the asymptotic expression of  $I_2$

$$\begin{aligned} I_2 &= \int_{z^*}^z \left\{ -\frac{(2s-1)^2}{16s(s-1)} - t^{-1} \left[ -\frac{(2s-1)\theta_\infty}{4s(s-1)} - \frac{A^2 + 4A'^2}{4s(s-1)} + \frac{i(2s^2 - 2s + 1)}{8s^2(s-1)^2} \right. \right. \\ &\quad \left. \left. - \frac{i(2s-1)[(1/2)it^{1/2}(s-1/2) + As^2]}{8z^2(s-1)^2[iA' + As + it^{1/2}(s-1/2)^2]} \right] \right\}^{1/2} ds \\ &= \int_{z^*}^z \frac{i(2s-1)}{4\sqrt{s(s-1)}} \left\{ 1 + \frac{16s(s-1)}{t(2s-1)^2} \left[ -\frac{(2s-1)\theta_\infty}{4s(s-1)} - \frac{A^2 + 4A'^2}{4s(s-1)} + \frac{i(2s^2 - 2s + 1)}{8s^2(s-1)^2} \right. \right. \\ &\quad \left. \left. + \frac{i(2s-1)[(it/4)(2s-1) + t^{1/2}As^2]}{8s^2(s-1)^2[-it/4 - t^{1/2}A' - t^{1/2}As - its(s-1)]} \right] \right\}^{1/2} ds \end{aligned}$$

$$\begin{aligned}
&= \int_{z^*}^z \left[ \frac{i(2s-1)}{4\sqrt{s(s-1)}} - \frac{i\theta_\infty}{2t\sqrt{s(s-1)}} - \frac{i(A^2+4A'^2+i)}{2t(2s-1)\sqrt{s(s-1)}} \right. \\
&\quad \left. - \frac{2it^{1/2}(s-1/2)+A}{4t\sqrt{(s-1/2)^2-1/4}[iA'+(1/2)A+A(s-1/2)+it^{1/2}(s-1/2)^2]} \right] dz \\
&\quad + O\left(t^{-2} \int_{z^*}^z \frac{|ds|}{|2s-1|^3}\right) + O\left(\frac{1}{z}\right) \\
&= \frac{iz}{2} - \frac{i}{4} - \frac{i\theta_\infty}{2t} \log(4z) - \frac{i\pi(A^2+4A'^2+i)}{4t} + \frac{1}{4} - \frac{T^2}{2t} - \frac{\pi\theta_\infty}{4t} \\
&\quad - \frac{A^2+4A'^2+i}{4t} \log \frac{t}{T^2} + \frac{i}{2t} \log \frac{2it^{1/2}}{2iA'+A+O(t^{-1/4})} + O(z^{-1}) \\
&\quad + O(T^{-2}t^{-1}) + O(T^4t^{-2}).
\end{aligned} \tag{3.7}$$

Using definition (2.10) and setting  $T = -\sqrt{A^2+4A'^2}$  in  $I_1$ , we have the following expression for  $\alpha$ :

$$\alpha^2 = -\frac{A^2+4A'^2+i}{t} + o(t^{-1}). \tag{3.8}$$

Substituting (3.8) into (3.2), setting  $T < t^{1/4}$ , and combining it with (3.5) and (3.7), the theorem is proved.  $\square$

Knowing [4] that

$$D_\nu(z) \sim \begin{cases} z^\nu e^{-(1/4)z^2}, & \text{if } |\arg z| < \frac{3}{4}\pi, \\ z^\nu e^{-(1/4)z^2} - \frac{\sqrt{2\pi}}{\Gamma(-\nu)} e^{i\pi\nu} z^{-\nu-1} e^{(1/4)z^2}, & \text{if } \arg z = \frac{3}{4}\pi, \end{cases} \tag{3.9}$$

and  $\arg(e^{\pi i/4} \sqrt{2t}\zeta) \sim \pi/4$  when  $z \rightarrow -\infty$ , we can choose, as  $z \rightarrow -\infty$ ,

$$\begin{aligned}
\hat{Y}_2^{(11)}(z) &\sim z^{-\theta_\infty/2} e^{tz/2} \\
&\sim 2^{\theta_\infty} t^{1/4} \sqrt{2iA'+A} e^{-(\pi i/4)(1/2+(3it/2)\alpha^2)} e^{(1/4)t+i[t/4-(1/4)(A^2+4A'^2)\log(2t)+\theta_\infty/4]} \\
&\quad \times \zeta^{1/2} D_\nu(e^{\pi i/4} \sqrt{2t}\zeta).
\end{aligned} \tag{3.10}$$

Because  $\arg(e^{\pi i/4} \sqrt{2t}\zeta) \sim 3\pi/4$  when  $z \rightarrow \infty$ , we have the following asymptotics for  $\hat{Y}_2^{(11)}(z)$  as  $z \rightarrow \infty$ :

$$\begin{aligned}
\hat{Y}_2^{(11)}(z) &\sim z^{-\theta_\infty/2} e^{tz/2} \\
&\quad - z^{\theta_\infty/2} e^{-tz/2} \frac{4^{\theta_\infty} \sqrt{\pi}(A^2+2iA'^2)}{\Gamma(1/2-(ti/2)\alpha^2)} e^{(\pi i/4)(2ti\alpha^2-3)+(1/2)t+i[t/2-(1/2)(A+4A'^2)\log(2t)]}.
\end{aligned} \tag{3.11}$$

By (1.9) and (2.2), the Stokes multiplier can be defined by  $\hat{Y}_2 = \hat{Y}_1 G_1$ . Therefore, the monodromy data is

$$s = \frac{4^{\theta_\infty} \sqrt{\pi} (A + 2iA')}{\Gamma(1/2 - (ti/2)\alpha^2)} e^{(\pi i/4)(2ti\alpha^2 - 5) + i[t/2 - (1/2)(A + 4A'^2)\log(2t)]}. \quad (3.12)$$

Taking the square of the absolute value of both sides of this equation, we find that  $A^2 + 4A'^2 \sim d^2$  where  $d$  is a constant. Solving (3.12) for  $A + 2iA'$ , we have

$$A + 2iA' = \left( \pm \sqrt{(A^2 + 4A'^2)} + O(t^{-1/2}) \right) e^{i[t/2 - (1/2)(A + 4A'^2)\log(2t) + \theta]}. \quad (3.13)$$

Taking the real part and the imaginary part of (3.13), we obtain the following theorem.

**THEOREM 3.2.** *Equation (1.1) has a solution with the following asymptotics:*

$$\begin{aligned} y(t) &\sim -1 + 4t^{-1/2}(d + O(t^{-1/2})) \cos\left(\frac{t}{2} - \frac{1}{2}d^2 \log(2t) + \theta\right), \\ y'(t) &\sim 2t^{-1/2}(d + O(t^{-1/2})) \sin\left(\frac{t}{2} - \frac{1}{2}d^2 \log(2t) + \theta\right), \quad \text{as } t \rightarrow \infty. \end{aligned} \quad (3.14)$$

## REFERENCES

- [1] A. P. Bassom, P. A. Clarkson, C. K. Law, and J. B. McLeod, *Application of uniform asymptotics to the second Painlevé transcendent*, Arch. Rational Mech. Anal. **143** (1998), no. 3, 241–271.
- [2] A. S. Fokas, U. Muğan, and M. J. Ablowitz, *A method of linearization for Painlevé equations: Painlevé IV, V*, Phys. D **30** (1988), no. 3, 247–283.
- [3] A. R. Its and V. Y. Novokshenov, *The Isomonodromic Deformation Method in the Theory of Painlevé Equations*, Lect. Notes in Math., vol. 1191, Springer-Verlag, Berlin, 1986.
- [4] E. T. Whittaker and G. M. Watson, *Modern Analysis*, 4th ed., Cambridge University Press, Cambridge, 1927.

YOU MIN LU: DEPARTMENT OF MATHEMATICS AND COMPUTER SCIENCE, BLOOMSBURG UNIVERSITY, BLOOMSBURG, PA 17815, USA

ZHOUE SHAO: DEPARTMENT OF MATHEMATICS, MILLERSVILLE UNIVERSITY, MILLERSVILLE, PA 17551-0302, USA

## Special Issue on Modeling Experimental Nonlinear Dynamics and Chaotic Scenarios

### Call for Papers

Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from “Qualitative Theory of Differential Equations,” allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the *Mathematical Problems in Engineering* aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

Authors should follow the Mathematical Problems in Engineering manuscript format described at <http://www.hindawi.com/journals/mpe/>. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/> according to the following timetable:

Manuscript Due	December 1, 2008
First Round of Reviews	March 1, 2009
Publication Date	June 1, 2009

### Guest Editors

**José Roberto Castilho Piqueira**, Telecommunication and Control Engineering Department, Polytechnic School, The University of São Paulo, 05508-970 São Paulo, Brazil; [piqueira@lac.usp.br](mailto:piqueira@lac.usp.br)

**Elbert E. Neher Macau**, Laboratório Associado de Matemática Aplicada e Computação (LAC), Instituto Nacional de Pesquisas Espaciais (INPE), São José dos Campos, 12227-010 São Paulo, Brazil ; [elbert@lac.inpe.br](mailto:elbert@lac.inpe.br)

**Celso Grebogi**, Center for Applied Dynamics Research, King's College, University of Aberdeen, Aberdeen AB24 3UE, UK; [grebogi@abdn.ac.uk](mailto:grebogi@abdn.ac.uk)