

## A GALERKIN METHOD OF $O(h^2)$ FOR SINGULAR BOUNDARY VALUE PROBLEMS

G. K. BEG and M. A. EL-GEBEILY

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We describe a Galerkin method with special basis functions for a class of singular two-point boundary value problems. The convergence is shown which is of  $O(h^2)$  for a certain subclass of the problems.

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**1. Introduction.** We consider the class of singular two-point boundary value problems:

$$\begin{aligned} -\frac{1}{p}(pu')' + f(x, u) &= 0, \quad 0 < x < 1, \\ (pu')(0^+) &= 0, \quad u(1) = 0. \end{aligned} \quad (1.1)$$

We assume that the real-valued function  $p$  satisfies

$$p \geq 0, \quad p^{-1} \in L^1_{\text{loc}}(0, 1], \quad p^{-1} \notin L^1_{\text{loc}}([0, \alpha)) \quad \text{for any } \alpha > 0, \quad (1.2)$$

$$\int_x^1 p^{-1} \in L^1_p(0, 1), \quad \text{that is,} \quad \int_0^1 \left( \int_x^1 \frac{1}{p(s)} ds \right) p(x) dx < \infty. \quad (1.3)$$

Note that (1.3) is clearly satisfied when  $p$  is an increasing function on  $(0, 1)$ . We also assume that  $f(x, u)$  is continuous in  $u$  such that for any real  $u$ ,  $f(\cdot, u) \in L^\infty_p(0, 1)$ ,

$$q(u, v, x) \equiv \frac{f(x, u) - f(x, v)}{u - v} \geq 0 \quad \text{for } -\infty < u, v < \infty, u \neq v. \quad (1.4)$$

The singular two-point boundary value problems of the form (1.1) occur frequently in many applied problems, for example, in the study of electrohydrodynamics [9], in the theory of thermal explosions [4], in the separation of variables in partial differential equations [11]; see also [1]. There is a considerable literature on the numerical methods for the singular boundary value problems. Special finite difference methods were considered in Chawla et al. [5]. The Galerkin method for singular problems was considered in Ciarlet et al. [6], Eriksson et al. [7], Jespersen [8]. Ciarlet et al. [6] assumed that  $p(x) > 0$  on  $(0, 1)$ ,  $p \in C^1(0, 1)$ , and  $p^{-1} \in L^1(0, 1)$ . In this paper, we address the problem with  $p^{-1} \notin L^1(0, 1)$ , and we assume that  $p \geq 0$ ,  $p^{-1} \in L^1_{\text{loc}}(0, 1)$ ; see (1.2) and (1.3). We investigate a Galerkin method with the same special patch functions considered by Ciarlet et al. [6] and we show that the method is of  $O(h^2)$  when

$p$  is an increasing function on  $(0, 1)$ . The linear case with more general settings was considered in [2] and a nonlinear case was considered in [3]. The special case considered here requires a different approach to establish its order of convergence and to obtain the optimal order of convergence  $h^2$  under an easily checked condition on  $p$ ; namely that  $p$  is increasing on  $[0, 1]$ .

**2. Preliminaries.** Let  $I = (0, 1)$  and  $H = L_p^2(I)$  denote the weighted Hilbert space with the inner product

$$\langle u, v \rangle_H = \int_I u(x)v(x)p(x)dx. \quad (2.1)$$

Also let  $V$  be the Hilbert space consisting of functions  $u \in L_p^2(I)$  which are locally absolutely continuous on  $I$ ,  $u(1) = 0$ , and  $u' \in L_p^2(I)$ . The inner product on the space  $V$  is defined by

$$\langle u, v \rangle_V = \int_I u'(x)v'(x)p(x)dx. \quad (2.2)$$

The variational formulation of the problem (1.1) now follows:

Find  $u \in V$  such that

$$a(u, v) = 0 \quad \forall v \in V, \quad (2.3)$$

where

$$a(u, v) \equiv \langle u, v \rangle_V + \int_0^1 f(x, u(x))v(x)p(x)dx. \quad (2.4)$$

It can be shown [3] that (1.1) and (2.3) have unique absolutely continuous (in  $[0, 1]$ ) solutions and that the weak solution of (2.3) coincides with the strong solution of (1.1).

**3. The Galerkin approximation and convergence results.** Let  $\pi : 0 = x_0 < x_1 < \dots < x_{N+1} = 1$  be a mesh on the interval  $[0, 1]$  and, for  $i = 1, 2, \dots, N$ , define the patch functions

$$r_i(x) = \begin{cases} r_i^-(x) & \text{if } x_{i-1} \leq x \leq x_i, \\ r_i^+(x) & \text{if } x_i \leq x \leq x_{i+1}, \\ 0 & \text{otherwise,} \end{cases} \quad (3.1)$$

where

$$\begin{aligned} r_1^-(x) &= 1, \\ r_i^-(x) &= \frac{\int_{x_{i-1}}^x (1/p(s))ds}{\int_{x_{i-1}}^{x_i} (1/p(s))ds}, \quad i = 2, 3, \dots, N, \\ r_i^+(x) &= \frac{\int_x^{x_{i+1}} (1/p(s))ds}{\int_{x_i}^{x_{i+1}} (1/p(s))ds}, \quad i = 1, 2, \dots, N. \end{aligned} \quad (3.2)$$

Define the discrete subspace  $V_N$  of  $V$  by

$$V_N = \text{span} \{r_i\}_{i=1}^N. \quad (3.3)$$

The discrete version of the weak problem (2.3) reads:

Find  $u^G \in V_N$  such that

$$a(u^G, v_N) = 0 \quad \forall v_N \in V_N. \quad (3.4)$$

Note that (3.4) has a unique solution  $u^G \in AC[0, 1]$ . It follows from (2.3) and (3.4) that

$$\langle u - u^G, v_N \rangle_V + \int_0^1 \frac{f(x, u) - f(x, u^G)}{u - u^G} (u - u^G) v_N p = 0. \quad (3.5)$$

Let  $\tilde{q}(x)$  be the unique function (because  $u$  and  $u^G$  are unique) defined by

$$\tilde{q}(x) \equiv \begin{cases} \frac{f(x, u(x)) - f(x, u^G(x))}{u(x) - u^G(x)}, & u(x) \neq u^G(x) \\ 0, & u(x) = u^G(x). \end{cases} \quad (3.6)$$

We assume that  $f$  is such that

$$C_{\tilde{q}} := \int_0^1 \tilde{q}(x) \int_x^1 \frac{ds}{p(s)} p(x) dx < \infty. \quad (3.7)$$

This is the case for example if  $f$  satisfies a Lipschitz condition in its second argument (see (1.3)). We can now state our results on the convergence of the Galerkin solution  $u^G$  to the weak solution  $u$  of (2.3).

**THEOREM 3.1.** *The following relation holds:*

$$\|u^G - u\|_\infty \leq (1 + 4C_{\tilde{q}}) \|f(\cdot, u(\cdot))\|_\infty \ell(\pi_N), \quad (3.8)$$

where  $\ell(\pi_N)$  is given by

$$\ell(\pi_N) = \max_{0 \leq i \leq N} \int_{x_i}^{x_{i+1}} \left( \int_s^{x_{i+1}} \frac{1}{p(t)} dt \right) p(s) ds. \quad (3.9)$$

**COROLLARY 3.2.** *If  $p$  is increasing then the method is  $O(h^2)$  where*

$$h = \max_{0 \leq i \leq N} (x_{i+1} - x_i). \quad (3.10)$$

**REMARK 3.3.** The absolute continuity of the solution  $u$  and the continuity of  $f$  imply that  $\|f(\cdot, u(\cdot))\|_\infty < \infty$  in the above expression for the error.

#### 4. Proof of the results. Let

$$u^G(x) = \sum_{i=1}^N \alpha_i r_i(x) \quad (4.1)$$

be the Galerkin approximation and  $u^I$  be the  $V_N$ -interpolant of the solution  $u$  given by

$$u^I(x) = \sum_{i=1}^N u_i r_i(x), \quad (4.2)$$

where  $u_i = u(x_i)$  and  $r_i$  is given by (3.1),  $i = 1, \dots, N$ . We note here that  $u^I$  is the orthogonal projection of  $u$  with respect to the inner product  $\langle \cdot, \cdot \rangle_V$ :

$$\langle u - u^I, v_N \rangle_V = 0 \quad (4.3)$$

for all  $v_N \in V_N$ . The following relation is also easily checked (using (3.5) and (4.3))

$$\langle u^G - u^I, v_N \rangle_V = \langle \tilde{q}(u - u^G), v_N \rangle_p, \quad (4.4)$$

for all  $v_N \in V_N$ . We have the following lemma.

**LEMMA 4.1.** *The following relation holds:*

$$\|u - u^I\|_\infty \leq \|f(\cdot, u(\cdot))\|_\infty \ell(\pi_N). \quad (4.5)$$

**PROOF.** For any  $x \in [x_i, x_{i+1}]$ ,  $i = 0, 1, \dots, N$

$$u(x) - u^I(x) \leq \int_{x_i}^{x_{i+1}} |g(s)| \left( \int_s^{x_{i+1}} \frac{dt}{p(t)} \right) p(s) ds, \quad (4.6)$$

where  $g(s) = -f(s, u(s))$ . To see this we consider two cases:  $i = 0$  and  $i \geq 1$ .

For  $i = 0$ , that is, for  $x \in [0, x_1]$  we have

$$\begin{aligned} u(x) - u^I(x) &= u(x) - u(x_1) \\ &= \int_x^{x_1} \frac{1}{p(s)} \int_0^s g(t) p(t) dt \\ &= \int_x^{x_1} \frac{ds}{p(s)} \int_0^s g(s) p(s) ds + \int_x^{x_1} g(s) p(s) \int_s^{x_1} \frac{dt}{p(t)} ds \\ &\leq \int_0^x |g(s)| p(s) \int_s^{x_1} \frac{dt}{p(t)} ds + \int_x^{x_1} |g(s)| p(s) \int_s^{x_1} \frac{dt}{p(t)} ds \\ &= \int_0^{x_1} |g(s)| \int_s^{x_1} \frac{dt}{p(t)} p(s) ds. \end{aligned} \quad (4.7)$$

It can be shown, using the fact  $\sum_{i=1}^N r_i(x) = 1$  and integrating by parts, that for  $x \in [x_i, x_{i+1}]$ ,  $i = 1, \dots, N$ ,

$$\begin{aligned}
 u(x) - u^I(x) &= r_i^+(x) \int_{x_i}^x \left( \int_{x_i}^s \frac{dt}{p(t)} \right) g(s) p(s) ds + r_{i+1}^-(x) \int_x^{x_{i+1}} \left( \int_s^{x_{i+1}} \frac{dt}{p(t)} \right) g(s) p(s) ds \\
 &= \frac{\int_x^{x_{i+1}} ds/p(s)}{\int_{x_i}^{x_{i+1}} ds/p(s)} \int_{x_i}^x \left( \int_{x_i}^s dt/p(t) \right) g(s) p(s) ds \\
 &\quad + \frac{\int_{x_i}^x ds/p(s)}{\int_{x_i}^{x_{i+1}} ds/p(s)} \int_x^{x_{i+1}} \int_s^{x_{i+1}} \frac{dt}{p(t)} g(s) p(s) ds \\
 &\leq \left( \int_x^{x_{i+1}} \frac{ds}{p(s)} \right) \int_{x_i}^x |g(s)| p(s) ds + \int_x^{x_{i+1}} \int_s^{x_{i+1}} \frac{dt}{p(t)} |g(s)| p(s) ds \\
 &\leq \int_{x_i}^x |g(s)| p(s) \int_s^{x_{i+1}} \frac{dt}{p(t)} ds + \int_x^{x_{i+1}} \int_s^{x_{i+1}} \frac{dt}{p(t)} |g(s)| p(s) ds \\
 &= \int_{x_i}^{x_{i+1}} |g(s)| \int_s^{x_{i+1}} \frac{dt}{p(t)} p(s) ds
 \end{aligned} \tag{4.8}$$

The result thus follows.  $\square$

**PROOF OF THEOREM 3.1.** In (4.4) taking  $v_N = r_i$  for  $i = 1, \dots, N$ , we obtain

$$\langle u^G - u^I, r_i \rangle_V = \langle \tilde{q}(u - u^G), r_i \rangle_p, \tag{4.9}$$

which can be written as

$$\sum_{j=1}^N [\langle r_j, r_i \rangle_V + \langle \tilde{q} r_j, r_i \rangle_p] (\alpha_j - u_j) = \langle \tilde{q}(u - u^I), r_i \rangle_p. \tag{4.10}$$

This gives the system

$$(\mathbf{A} + \mathbf{Q})\mathbf{e} = \mathbf{d}, \tag{4.11}$$

where  $\mathbf{A} = (a_{ij}) = (\langle r_i, r_j \rangle_V)$  is a symmetric and tridiagonal matrix given by

$$\begin{aligned}
 a_{11} &= \frac{1}{\int_{x_1}^{x_2} (1/p(s)) ds}, \\
 a_{ii} &= \frac{1}{\int_{x_{i-1}}^{x_i} (1/p(s)) ds} + \frac{1}{\int_{x_i}^{x_{i+1}} (1/p(s)) ds}, \quad i = 2, \dots, N, \\
 a_{i,i+1} &= -\frac{1}{\int_{x_i}^{x_{i+1}} (1/p(s)) ds}, \quad i = 1, \dots, N-1,
 \end{aligned} \tag{4.12}$$

$\mathbf{Q} = (q_{ij}) = (\langle \tilde{q} r_j, r_i \rangle_p)$ ,  $\mathbf{e} = (e_i) = (\alpha_i - u_i)$ , and  $\mathbf{d} = (d_i)$  is given by

$$\begin{aligned} d_1 &= \int_{x_0}^{x_1} h(s)p(s)ds + \frac{\int_{x_1}^{x_2} h(s)p(s) \int_s^{x_2} (dt/p(t))ds}{\int_{x_1}^{x_2} dt/p(t)} \\ d_i &= \frac{\int_{x_{i-1}}^{x_i} h(s)p(s) \int_{x_{i-1}}^s (dt/p(t))ds}{\int_{x_{i-1}}^{x_i} dt/p(t)} + \frac{\int_{x_i}^{x_{i+1}} h(s)p(s) \int_s^{x_{i+1}} (dt/p(t))ds}{\int_{x_i}^{x_{i+1}} dt/p(t)}, \quad i > 1, \end{aligned} \quad (4.13)$$

where  $h(s)$  stands for  $\tilde{q}(s)(u(s) - u^I(s))$ . Now  $\mathbf{A}$  is an  $\mathbf{M}$ -matrix,  $q_{ij} \geq 0$  (see (1.4)),  $q_{ij} < -a_{ij}$  ( $i \neq j$ ) for sufficiently small mesh size and therefore,  $\mathbf{A} + \mathbf{Q}$  is an  $\mathbf{M}$ -matrix with  $(\mathbf{A} + \mathbf{Q})^{-1} \leq \mathbf{A}^{-1}$  (see Ortega [10]). Thus  $|\mathbf{e}| \leq \mathbf{A}^{-1}|\mathbf{d}|$ . The inverse of the matrix  $\mathbf{A}$ , denoted by  $\mathbf{B} = (b_{ij})$ , can be explicitly written as

$$b_{ij} = \begin{cases} \int_{x_j}^1 \frac{ds}{p(s)} & \text{if } i \leq j, \\ \int_{x_i}^1 \frac{ds}{p(s)} & \text{if } i \geq j. \end{cases} \quad (4.14)$$

Therefore,

$$\begin{aligned} |e_i| &\leq \sum_{j=1}^N b_{ij} |d_j| \\ &= \sum_{j=1}^i \int_{x_i}^1 \frac{ds}{p(s)} |d_j| + \sum_{j=i+1}^N \int_{x_j}^1 \frac{ds}{p(s)} |d_j| \\ &\leq \sum_{j=1}^N \int_{x_j}^1 \frac{ds}{p(s)} |d_j|. \end{aligned} \quad (4.15)$$

We see that

$$\begin{aligned} \int_{x_1}^1 \frac{ds}{p(s)} |d_1| &\leq \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} |h(s)| p(s) ds + \int_{x_1}^1 \frac{ds}{p(s)} \frac{\int_{x_1}^{x_2} |h(s)| p(s) \int_s^{x_2} (dt/p(t)) ds}{\int_{x_1}^{x_2} dt/p(t)} \\ &= \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} |h(s)| p(s) ds + \int_{x_1}^{x_2} \frac{ds}{p(s)} \frac{\int_{x_1}^{x_2} |h(s)| p(s) \int_s^{x_2} (dt/p(t)) ds}{\int_{x_1}^{x_2} dt/p(t)} \\ &\quad + \int_{x_2}^1 \frac{ds}{p(s)} \frac{\int_{x_1}^{x_2} |h(s)| p(s) \int_s^{x_2} (dt/p(t)) ds}{\int_{x_1}^{x_2} dt/p(t)} \\ &\leq \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} |h(s)| p(s) ds + \int_{x_1}^{x_2} |h(s)| p(s) \int_s^{x_2} \frac{dt}{p(t)} ds \\ &\quad + \int_{x_2}^1 \frac{ds}{p(s)} \int_{x_1}^{x_2} |h(s)| p(s) ds \\ &= \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} |h(s)| p(s) ds + \int_{x_1}^{x_2} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds \\ &\leq \int_{x_0}^{x_1} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds + \int_{x_1}^{x_2} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds. \end{aligned} \quad (4.16)$$

Also for  $j = 2, \dots, N$ , by a similar approach, we have

$$\begin{aligned} \int_{x_j}^1 \frac{ds}{p(s)} |d_j| &\leq \int_{x_j}^1 \frac{ds}{p(s)} \int_{x_{j-1}}^{x_j} |h(s)| p(s) ds \\ &\quad + \int_{x_j}^1 \frac{ds}{p(s)} \frac{\int_{x_i}^{x_{i+1}} |h(s)| p(s) \int_s^{x_{i+1}} (dt/p(t)) ds}{\int_{x_i}^{x_{i+1}} dt/p(t)} \\ &\leq \int_{x_{j-1}}^{x_j} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds + \int_{x_j}^{x_{j+1}} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds. \end{aligned} \quad (4.17)$$

Substituting these two inequalities in (4.15) we obtain

$$\begin{aligned} |e_i| &\leq \int_{x_0}^{x_N} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds + \int_{x_1}^{x_{N+1}} |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds \\ &\leq 2 \int_0^1 |h(s)| p(s) \int_s^1 \frac{dt}{p(t)} ds \\ &= 2 \int_0^1 |\tilde{q}(s)(u(s) - u^I(s))| p(s) \int_s^1 \frac{dt}{p(t)} ds. \end{aligned} \quad (4.18)$$

Thus using (3.7), we have

$$\max_{1 \leq i \leq N} |\alpha_i - u_i| \leq 2C_{\tilde{q}} \|u - u^I\|_{\infty}. \quad (4.19)$$

It can be shown that

$$\|u^G - u^I\|_{\infty} \leq 2 \max_{1 \leq i \leq N} |\alpha_i - u_i|. \quad (4.20)$$

Therefore,

$$\begin{aligned} \|u - u^G\|_{\infty} &\leq \|u - u^I\|_{\infty} + \|u^G - u^I\|_{\infty} \\ &\leq \|u - u^I\|_{\infty} + 2 \max_{1 \leq i \leq N} |u_i - \alpha_i| \\ &\leq (1 + 4C_{\tilde{q}}) \|u - u^I\|_{\infty}. \end{aligned} \quad (4.21)$$

The result thus follows from Lemma 4.1.  $\square$

**5. Example.** In this section we give examples which are solved by the Galerkin method just described above with equal mesh size  $h$ . We then compare the results with the actual solutions.

**EXAMPLE 5.1.** We consider the boundary value problem

$$-\frac{1}{x}(xu')' + e^u = 0, \quad 0 < x < 1, \quad u'(0) = u(1) = 0. \quad (5.1)$$

The exact solution is known:  $u(x) = 2\ln((1+\beta)/(1+\beta x^2))$ ,  $\beta = -5 + 2\sqrt{6}$ . It is seen that  $\|u^G - u\|_\infty = 0.188845 \times 10^{-2}$  for  $h = 0.1$  and  $\|u^G - u\|_\infty = 0.189 \times 10^{-4}$  for  $h = 0.01$ . According to the [Corollary 3.2](#) the method is  $O(h^2)$  which is reflected in these results.

**EXAMPLE 5.2.** We consider the equation

$$-\frac{1}{x^\alpha}(x^\alpha u')' + \frac{\beta^2 x^{2\beta-2}}{5(4+x^\beta)} e^u = \frac{\beta(\alpha+\beta-1)x^{\beta-2}}{4+x^\beta} \quad (5.2)$$

$$(x^\alpha u')(0^+) = 0, \quad u(1) = 0.$$

The exact solution is  $u = \ln 5 - \ln(4+x^\beta)$ . The following results were obtained:

TABLE 5.1

$\alpha$	$\beta$	$h$	$\ u^G - u\ _\infty$
0.5	2	0.02	$1.0299 \times 10^{-4}$
0.5	2	0.01	$2.6147 \times 10^{-5}$
1.0	2	0.02	$9.9647 \times 10^{-5}$
1.0	2	0.01	$2.4913 \times 10^{-5}$
2.0	6	0.02	$3.4133 \times 10^{-4}$
2.0	6	0.01	$8.6170 \times 10^{-5}$

**REMARK 5.3.** Our method does not differentiate between  $0 < \alpha < 1$  and  $\alpha \geq 1$  as is the case in many articles in the literature.

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G. K. BEG AND M. A. EL-GEBEILY: DEPARTMENT OF MATHEMATICAL SCIENCES, KING FAHD UNIVERSITY OF PETROLEUM AND MINERALS, DHAHRAN 31261, SAUDI ARABIA

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**Edson Denis Leonel**, Departamento de Estatística, Matemática Aplicada e Computação, Instituto de Geociências e Ciências Exatas, Universidade Estadual Paulista, Avenida 24A, 1515 Bela Vista, 13506-700 Rio Claro, SP, Brazil ; [edleonel@rc.unesp.br](mailto:edleonel@rc.unesp.br)

**Alexander Loskutov**, Physics Faculty, Moscow State University, Vorob'evy Gory, Moscow 119992, Russia; [loskutov@chaos.phys.msu.ru](mailto:loskutov@chaos.phys.msu.ru)