

**EXISTENCE THEOREMS FOR A SECOND ORDER  
m-POINT BOUNDARY VALUE PROBLEM AT  
RESONANCE**

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**Abstract**

Let  $f : [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$  be a function satisfying Caratheodory's conditions and  $e(t) \in L^1[0, 1]$ . Let  $\eta \in (0, 1)$ ,  $\xi_i \in (0, 1)$ ,  $a_i \geq 0$ ,  $i = 1, 2, \dots, m-2$ , with  $\sum_{i=1}^{m-2} a_i = 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$  be given. This paper is concerned with the problem of existence of a solution for the following boundary value problems

$$\begin{aligned} x''(t) &= f(t, x(t), x'(t)) + e(t), 0 < t < 1, \\ x'(0) &= 0, x(1) = x(\eta), \\ x''(t) &= f(t, x(t), x'(t)) + e(t), 0 < t < 1, \\ x'(0) &= 0, x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i). \end{aligned}$$

Conditions for the existence of a solution for the above boundary value problems are given using Leray Schauder Continuation theorem.

**Keywords and Phrases:** three-point boundary value problem, m-point boundary value problem, Leray Schauder Continuation theorem, Caratheodory's conditions, Arzela-Ascoli Theorem.

**AMS(MOS) Subject Classification:** 34B10, 34B15, 34G20.

## 1 INTRODUCTION.

Let  $f : [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$  be a function satisfying Caratheodory's conditions,  $e : [0, 1] \rightarrow \mathbb{R}$  be a function in  $L^1[0, 1]$ ,  $a_i \geq 0$ ,  $\xi_i \in (0, 1)$ ,  $i = 1, 2, \dots, m-2$  with  $\sum_{i=1}^{m-2} a_i = 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$  and  $\eta \in (0, 1)$  be given. We study the problem of existence of solutions for the following boundary value problems

$$\begin{aligned} x''(t) &= f(t, x(t), x'(t)) + e(t), 0 < t < 1, \\ x'(0) &= 0, x(1) = x(\eta), \end{aligned} \tag{1}$$

$$\begin{aligned} x''(t) &= f(t, x(t), x'(t)) + e(t), 0 < t < 1, \\ x'(0) &= 0, x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i). \end{aligned} \tag{2}$$

It is well-known, (see, e.g. [1]), that if  $x \in C^1[0, 1]$  satisfies the boundary conditions in (2), with the  $a_i$ 's as above, then there exists an  $\eta \in [\xi_1, \xi_{m-2}]$ , depending on  $x \in C^1[0, 1]$ , such that

$$x(1) = x(\eta). \tag{3}$$

Accordingly, it seems that one can study the problem of existence of a solution for the boundary value problem (2) using the a priori estimates obtained for the three-point boundary value problem (1), as it was done in [2], [3], [4]. But here the m-point boundary value problem (2) happens to be at resonance in the sense that the associated linear homogeneous boundary value problem

$$\begin{aligned} x''(t) &= 0, 0 < t < 1, \\ x'(0) &= 0, x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i), \end{aligned}$$

has  $x(t) = A$ ,  $A \in \mathbb{R}$ , as a non-trivial solution, since  $\sum_{i=1}^{m-2} a_i = 1$ . The result is that  $e(t) \in L^1[0, 1]$  has to be such that  $\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1-\xi_i) e(s) ds + \int_{\xi_i}^1 (1-s) e(s) ds] = 0$ , (in view of the nonlinear Fredholm

alternative), so even though there exists an  $\eta \in [\xi_1, \xi_{m-2}]$  such that  $\int_0^1 (1-\eta) e(s) ds + \int_\eta^1 (1-s) e(s) ds = \sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1-\xi_i) e(s) ds + \int_{\xi_i}^1 (1-s) e(s) ds] = 0$ , since  $\sum_{i=1}^{m-2} a_i = 1$ , this  $\eta$  is not necessarily the same  $\eta$  as in (3). We are, accordingly, forced to study the m-point boundary value problem (2) directly and obtain results about the three-point boundary value problem (1) as a corollary to the results for the m-point boundary value problem. It is interesting to note that while in the nonresonance case we had to study the m-point boundary value problem, using the results for the three-point boundary value problem, it is just the reverse case in the resonance case.

We obtain conditions for the existence of a solution for the boundary value problem (2), using Mawhin's version of the Leray Schauder Continuation theorem [5] or [6] or [7]. Recently, Gupta, Ntouyas and Tsamatos studied the m-point boundary value problem

$$\begin{aligned} x''(t) &= f(t, x(t), x'(t)) + e(t), \quad 0 < t < 1, \\ x'(0) &= 0, \quad x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i), \end{aligned} \quad (4)$$

with  $\xi_i \in (0,1)$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$ ,  $a_i \in R$ , all  $a_i$  having the same sign, given, and  $\sum_{i=1}^{m-2} a_i \neq 1$ , in [3]. The boundary value problem (2) differs from the boundary value problem (4) in that the associated linear boundary value problem with (2), namely,

$$\begin{aligned} x''(t) &= 0, \quad 0 < t < 1, \\ x'(0) &= 0, \quad x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i), \end{aligned} \quad (5)$$

has  $x(t) = A$ , for  $A \in R$ , as non-trivial solutions, since  $\sum_{i=1}^{m-2} a_i = 1$ , while the corresponding linear boundary value problem associated with (4), namely,

$$\begin{aligned} x''(t) &= 0, \quad 0 < t < 1, \\ x'(0) &= 0, \quad x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i), \end{aligned} \quad (6)$$

with  $\sum_{i=1}^{m-2} a_i \neq 1$ , has  $x(t) \equiv 0$ , as its only solution. It is for this reason we call the boundary value problem (2) to be at resonance. For some recent results on m-point and three-point boundary value problems we refer the reader to [2], [3], [4], [8], [9], [10], (and [11]).

We use the classical spaces  $C[0, 1]$ ,  $C^k[0, 1]$ ,  $L^k[0, 1]$ , and  $L^\infty[0, 1]$  of continuous,  $k$ -times continuously differentiable, measurable real-valued functions whose  $k$ -th power of the absolute value is Lebesgue integrable on  $[0, 1]$ , or measurable functions that are essentially bounded on  $[0, 1]$ . We also use the Sobolev space  $W^{2,k}(0, 1)$ ,  $k = 1, 2$  defined by

$$W^{2,k}(0, 1) = \{x : [0, 1] \rightarrow R \mid x, x' \text{ abs. cont. on } [0, 1] \text{ with } x'' \in L^k[0, 1]\}$$

with its usual norm. We denote the norm in  $L^k[0, 1]$  by  $\| \cdot \|_k$ , and the norm in  $L^\infty[0, 1]$  by  $\| \cdot \|_\infty$ .

## 2 EXISTENCE THEOREMS.

Let  $X, Y$  denote Banach spaces  $X = C^1[0, 1]$  and  $Y = L^1[0, 1]$  with their usual norms. Let  $Y_2$  be the subspace of  $Y$  spanned by the function 1, i.e.

$$Y_2 = \{x(t) \in Y \mid x(t) = A, \text{ a.e. on } [0, 1], A \in R\} \quad (7)$$

and let  $Y_1$  be the subspace of  $Y$  such that  $Y = Y_1 \oplus Y_2$ . Let  $a_i \geq 0$ ,  $\xi_i \in (0, 1)$ ,  $i = 1, 2, \dots, m-2$  with  $\sum_{i=1}^{m-2} a_i = 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$ , be given. We note that for  $x(t) \in Y$  we can write

$$x(t) = (x(t) - A) + A, \quad (8)$$

with  $A = \frac{2}{\sum_{i=1}^{m-2} a_i (1 - \xi_i^2)} \sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1 - \xi_i) x(s) ds + \int_{\xi_i}^1 (1 - s) x(s) ds]$ , for  $t \in [0, 1]$ . We define the canonical projection operators  $P : Y \rightarrow Y_1$ ,  $Q : Y \rightarrow Y_2$  by

$$\begin{aligned} P(x(t)) &= x(t) - \frac{2}{\sum_{i=1}^{m-2} a_i (1 - \xi_i^2)} [\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1 - \xi_i) x(s) ds + \int_{\xi_i}^1 (1 - s) x(s) ds]], \\ Q(x(t)) &= \frac{2}{\sum_{i=1}^{m-2} a_i (1 - \xi_i^2)} [\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1 - \xi_i) x(s) ds + \int_{\xi_i}^1 (1 - s) x(s) ds]], \end{aligned} \quad (9)$$

for  $x(t) \in Y$ . We note that if  $Q(x(t)) = 0$ , there exists a  $\zeta \in (0, 1)$  such that  $x(\zeta) = 0$ . Clearly,  $Q = I - P$ , where  $I$  denotes the identity mapping on  $Y$ , and the projections  $P$  and  $Q$  are continuous. Now let  $X_2 = X \cap Y_2$ . Clearly  $X_2$  is a closed subspace of  $X$ . Let  $X_1$  be the closed subspace of  $X$  such

that  $X = X_1 \oplus X_2$ . We note that  $P(X) \subset X_1$ ,  $Q(X) \subset X_2$  and the projections  $P|X : X \rightarrow X_1$  and  $Q|X : X \rightarrow X_2$  are continuous. In the following,  $X$ ,  $Y$ ,  $P$ ,  $Q$  will refer to the Banach spaces and the projections as defined and we shall not distinguish between  $P$ ,  $P|X$  (resp.  $Q$ ,  $Q|X$ ) and depend on the context for the proper meaning.

Define a linear operator  $L : D(L) \subset X \rightarrow Y$  by setting

$$D(L) = \{x \in W^{2,1}(0,1) \mid x'(0) = 0, x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i)\}, \quad (10)$$

and for  $x \in D(L)$ ,

$$Lx = x''. \quad (11)$$

Let, now, for  $e \in Y_1$ , i.e.  $e \in L^1[0,1]$  with  $\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1-\xi_i) e(s) ds + \int_{\xi_i}^1 (1-s) e(s) ds] = 0$ ,  $Ke$  denote the unique solution of the boundary value problem

$$\begin{aligned} x''(t) &= e(t), \quad 0 < t < 1, \\ x'(0) &= 0, \quad x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i), \end{aligned}$$

such that  $\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1-\xi_i) x(s) ds + \int_{\xi_i}^1 (1-s) x(s) ds] = 0$ . Indeed, for  $t \in [0,1]$ ,

$$(Ke)(t) = \int_0^t (t-s) e(s) ds + A, \quad (12)$$

where  $A = -\frac{2}{\sum_{i=1}^{m-2} a_i (1-\xi_i^2)} [\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} \int_0^t (1-\xi_i)(t-s) e(s) ds dt + \int_{\xi_i}^1 \int_0^t (1-t)(t-s) e(s) ds dt]]$ . Accordingly the linear mapping  $K : Y_1 \rightarrow X_1$  defined by the equation (12) is a bounded linear mapping and is such that for

$$x \in Y, KPx \in D(L), \text{ and } LKP(x) = P(x).$$

**DEFINITION 1** :- A function  $f : [0,1] \times R^2 \rightarrow R$  satisfies Caratheodory's conditions if (i) for each  $(x,y) \in R^2$ , the function  $t \in [0,1] \rightarrow f(t,x,y) \in R$  is measurable on  $[0,1]$ , (ii) for a.e.  $t \in [0,1]$ , the function  $(x,y) \in R^2 \rightarrow f(t,x,y) \in R$  is continuous on  $R^2$ , and (iii) for each  $r > 0$ , there exists  $\alpha_r(t) \in L^1[0,1]$  such that  $|f(t,x,y)| \leq \alpha_r(t)$  for a.e.  $t \in [0,1]$  and all  $(x,y) \in R^2$  with  $\sqrt{x^2 + y^2} \leq r$ .

Let  $f : [0,1] \times R^2 \rightarrow R$  be a function satisfying Caratheodory's conditions. Let  $N : X \rightarrow Y$  be the non-linear mapping defined by

$$(Nx)(t) = f(t, x(t), x'(t)), \quad t \in [0,1],$$

for  $x(t) \in X$ .

For  $e(t) \in Y_1$ , i.e.  $e(t) \in L^1[0,1]$  with  $\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1-\xi_i) e(s) ds + \int_{\xi_i}^1 (1-s) e(s) ds] = 0$ , the boundary value problem (2) reduces to the functional equation

$$Lx = Nx + e, \quad (13)$$

in  $X$ , with  $e(t) \in Y_1$ , given.

**THEOREM 2** :- Let  $f : [0,1] \times R^2 \rightarrow R$  be a function satisfying Caratheodory's conditions. Assume that there exist functions  $p(t)$ ,  $q(t)$ ,  $r(t)$  in  $L^1(0,1)$  such that

$$|f(t, x_1, x_2)| \leq p(t) |x_1| + q(t) |x_2| + r(t) \quad (14)$$

for a.e.  $t \in [0,1]$  and all  $(x_1, x_2) \in R^2$ . Also let  $a_i \geq 0$ ,  $\xi_i \in (0,1)$ ,  $i = 1, 2, \dots, m-2$  with  $\sum_{i=1}^{m-2} a_i = 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$  be given, and assume that for every  $x(t) \in X$ ,

$$(Qx)(t) \cdot (QNx)(t) \geq 0, \text{ for } t \in [0,1]. \quad (15)$$

Then for  $e(t) \in Y_1$ , i.e.  $e(t) \in L^1[0,1]$  with  $\sum_{i=1}^{m-2} a_i [\int_0^{\xi_i} (1-\xi_i) e(s) ds + \int_{\xi_i}^1 (1-s) e(s) ds] = 0$ , given, the boundary value problem (2) has at least one solution in  $C^1[0,1]$  provided

$$\|p\|_1 + \|q\|_1 < 1. \quad (16)$$

PROOF:- We first note that the bounded linear mapping  $K : Y_1 \rightarrow X_1$  defined by the equation (12) is such that the mapping  $KPN : X \rightarrow X$  maps bounded subsets of  $X$  into relatively compact subsets of  $X$ , in view of Arzela-Ascoli Theorem. Hence  $KPN : X \rightarrow X$  is a compact mapping.

We, next, note that  $x \in C^1[0,1]$  is a solution of the boundary value problem (2) if and only if  $x$  is a solution to the operator equation

$$Lx = Nx + e.$$

Now, to solve the operator equation  $Lx = Nx + e$ , it suffices to solve the system of equations

$$\begin{aligned} Px &= KPNx + e_1, \\ QNx &= 0, \end{aligned} \quad (17)$$

$x \in X$ ,  $e_1 = Ke$  (note that since  $e \in Y_1$ ,  $Pe = e$ ,  $Qe = 0$ ). Indeed, if  $x \in X$  is a solution of (17) then  $x \in D(L)$  and

$$\begin{aligned} LPx &= Lx = LKPNx + Le_1 = PNx + e, \\ QNx &= 0, \end{aligned}$$

which gives on adding that  $Lx = Nx + e$ .

Now, (17) is clearly equivalent to the single equation

$$Px + QNx - KPNx = e_1, \quad (18)$$

which has the form of a compact perturbation of the Fredholm operator  $P$  of index zero. We can, therefore, apply the version given in ([5], Theorem 1, Corollary 1) or ([6], Theorem IV.4) or ([7]) of the Leray-Schauder Continuation theorem which ensures the existence of a solution for (18) if the set of all possible solutions of the family of equations

$$Px + (1 - \lambda)Qx + \lambda QNx - \lambda KPNx = \lambda e_1, \quad (19)$$

$\lambda \in (0,1)$ , is a priori bounded, independently of  $\lambda$ . Notice that (19) is then equivalent to the system of equations

$$\begin{aligned} Px &= \lambda KPNx + \lambda e_1, \\ (1 - \lambda)Qx + \lambda QNx &= 0. \end{aligned} \quad (20)$$

Let, now,  $x(t)$  be a solution of (20) for some  $\lambda \in (0,1)$ . We see on multiplying the second equation in (20) and using (15) that  $(1 - \lambda)((Qx)(t))^2 \leq 0$  for every  $t \in [0,1]$ . Hence  $(Qx)(t) = 0$  for every  $t \in [0,1]$  and accordingly there exists a  $\zeta \in (0,1)$  such that  $x(\zeta) = 0$ . Since, now,  $x'(0) = 0$  it follows that  $\|x\|_\infty \leq \|x'\|_\infty \leq \|x''\|_1$ . Also since  $Qx = 0$ , we have  $QNx = 0$ . It follows that  $x \in D(L)$ , i.e.,  $x \in W^{2,1}(0,1)$  with  $x'(0) = 0$ ,  $x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i)$  and  $x''(t) = \lambda f(t, x(t), x'(t)) + \lambda e(t)$ . Accordingly, we get that

$$\begin{aligned} \|x''\|_1 &= \lambda \|f(t, x(t), x'(t)) + e(t)\|_1 \\ &\leq \|p\|_1 \|x\|_\infty + \|q\|_1 \|x'\|_\infty + \|r\|_1 + \|e\|_1 \\ &\leq (\|p\|_1 + \|q\|_1) \|x''\|_1 + \|r\|_1 + \|e\|_1 \end{aligned}$$

It follows from the assumption (16) that there is a constant  $c$ , independent of  $\lambda \in (0,1)$  and  $x(t)$ , such that

$$\|x''\|_1 \leq c.$$

It is now immediate from  $\|x\|_\infty \leq \|x'\|_\infty \leq \|x''\|_1$  that the set of solutions of the family of equations (20) is, a priori, bounded in  $C^1[0,1]$  by a constant, independent of  $\lambda \in (0,1)$ .

This completes the proof of the theorem.//

**REMARK 1:-** We remark that the Theorem 2 remains valid if we replace (15) by the condition

$$(Qx)(t) \cdot (QNx)(t) \leq 0, \text{ for } t \in [0,1]. \quad (21)$$

for every  $x \in X$ .

**REMARK 2:-** We remark that the condition (15) can be replaced by the condition

$$f(t, x_1, x_2) x_1 \geq 0, \quad (22)$$

for almost all  $t \in (0,1)$  and all  $(x_1, x_2) \in R^2$ . Indeed, condition (15) was used to show, in the proof of Theorem 2, that if  $x(t)$  is a solution of (20) for some  $\lambda \in (0,1)$  then there exists a  $\zeta \in (0,1)$  such that  $x(\zeta) = 0$ . We, now, show that (22), implies that if  $x(t)$  is a solution of (20) for some  $\lambda \in (0,1)$  then there exists a  $\zeta \in (0,1)$  such that  $x(\zeta) = 0$ . Indeed, suppose that  $x(t) \neq 0$ , for all  $t \in (0,1)$ . We may, in fact, assume without any loss of generality that  $x(t) > 0$ , for every  $t \in (0,1)$ . It then follows from (22) that  $f(t, x(t), x'(t)) \geq 0$ , for a.e.  $t \in (0,1)$ . Hence  $Qx > 0$  and  $QNx \geq 0$ . Now the second equation in (20) gives that  $(1 - \lambda)(Qx)^2 + \lambda(QNx)(Qx) = 0$ , so that we get  $(Qx)^2 \leq 0$ , a contradiction. Accordingly, there must exist a  $\zeta \in (0,1)$  such that  $x(\zeta) = 0$ .

**THEOREM 3** :- Let  $f : [0, 1] \times R^2 \rightarrow R$  be a function as in Theorem 2. Assume that the functions  $p(t)$ ,  $q(t)$ ,  $r(t)$  in (14) are in  $L^2(0,1)$ . Let  $a_i \geq 0$ ,  $\xi_i \in (0,1)$ ,  $i = 1, 2, \dots, m-2$  with  $\sum_{i=1}^{m-2} a_i = 1$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$  be given.

Then for  $e(t) \in L^2[0,1]$  with  $\sum_{i=1}^{m-2} a_i \int_{\xi_i}^1 e(s)ds = 0$ , given, the boundary value problem (2) has at least one solution in  $C^1[0,1]$  provided

$$\frac{2}{\pi} \left( \frac{2}{\pi} \|p\|_2 + \|q\|_2 \right) < 1. \quad (23)$$

PROOF:- The proof is similar to the proof of Theorem 2, except now one uses the inequalities  $\|x\|_2 \leq \frac{2}{\pi} \|x'\|_2 \leq \frac{4}{\pi^2} \|x''\|_2$  for an  $x \in W^{2,2}(0,1)$  with  $x(\zeta) = 0$ , for some  $\zeta \in (0,1)$  and  $x'(0) = 0$  (see, Theorem 256 of [12]) to show that the set of solutions of the family of equations (19) is a priori bounded in  $C^1[0,1]$  by a constant independent of  $\lambda \in (0,1)$ .//

**THEOREM 4** :- Let  $f : [0, 1] \times R^2 \rightarrow R$  be a function as in Theorem 2 (respectively, Theorem 3). Let  $\eta \in (0, 1)$  be given. Then for  $e(t) \in L^1[0,1]$  (respectively,  $e(t) \in L^2[0,1]$ ) with  $\int_0^\eta (1 - \eta)e(s)ds + \int_\eta^1 (1 - s)e(s)ds = 0$ , given, the three-point boundary value problem (1) has at least one solution in  $C^1[0,1]$  provided

$$\|p\|_1 + \|q\|_1 < 1, \quad (24)$$

$$(\text{respectively, } \frac{2}{\pi} \left( \frac{2}{\pi} \|p\|_2 + \|q\|_2 \right) < 1).$$

PROOF:- The theorem follows immediately from Theorem 2 (respectively, Theorem 3) with  $m = 3$  and  $a_1 = 1$ ,  $\xi_1 = \eta$ .//

**THEOREM 5** :- Let  $f : [0, 1] \times R^2 \rightarrow R$  be a function as in Theorem 2 (respectively, Theorem 3). Then for  $e(t) \in L^1[0,1]$  (respectively,  $e(t) \in L^2[0,1]$ ) with  $\int_0^1 (1 - s)e(s)ds = 0$ , given, the boundary value problem

$$\begin{aligned} x''(t) &= f(t, x(t), x'(t)) + e(t), \quad 0 < t < 1, \\ x'(0) &= 0, \quad x(0) = x(1), \end{aligned}$$

has at least one solution in  $C^1[0,1]$  provided

$$\|p\|_1 + \|q\|_1 < 1, \quad (25)$$

$$(\text{respectively, } \frac{2}{\pi} \left( \frac{2}{\pi} \|p\|_2 + \|q\|_2 \right) < 1).$$

PROOF:- The theorem follows immediately from Theorem 2 (respectively, Theorem 3) with  $m = 2$  and  $a_1 = 1$ ,  $\xi_1 = 0$ .//

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Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from "Qualitative Theory of Differential Equations," allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the *Mathematical Problems in Engineering* aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

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