

*Research Article*

## **Solvability of Second-Order $m$ -Point Boundary Value Problems with Impulses**

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By Leray-Schauder continuation theorem and the nonlinear alternative of Leray-Schauder type, the existence of a solution for an  $m$ -point boundary value problem with impulses is proved.

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### **1. Introduction**

The main purpose of this paper is to get results on the solvability of the following boundary value problem (BVP):

$$\begin{aligned} x''(t) &= f(t, x(t), x'(t)), \\ \Delta x'(t_k) &= b_k x'(t_k), \quad \Delta x(t_k) = c_k x(t_k), \\ x'(0) &= 0, \quad x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i), \end{aligned} \tag{1.1}$$

where  $\xi_i \in (0, 1)$ ,  $i = 1, 2, \dots, m-2$ ,  $0 < \xi_1 < \xi_2 < \dots < \xi_{m-2} < 1$ ,  $a_i \in R$ ,  $i = 1, 2, \dots, m-2$ ,  $\sum_{i=1}^{m-2} a_i \neq 1$ ,  $0 = t_0 < t_1 < t_2 < \dots < t_T < t_{T+1} = 1$ .

Such problems without impulses effects have been solved before, for example, in [1–3]. But as far as we know the publication on the solvability of  $m$ -point problems with impulses is fewer [4]. Our main goal is to find condition for  $f, b_k, c_k, 1 \leq k \leq T$ , which guarantees the existence of at least one solution of problem (1.1). The proofs are based on the Leray-Schauder continuation theorem [5] and the nonlinear alternative of Leray-Schauder type [6].

## 2 Boundary Value Problems

In order to define the concept of solution for BVP (1.1), we introduce the following spaces of functions:

- (i)  $PC[0,1] = \{u : [0,1] \rightarrow R, u \text{ is continuous at } t \neq t_k, u(t_k^+), u(t_k^-) \text{ exist, and } u(t_k^-) = u(t_k)\};$
- (ii)  $PC^1[0,1] = \{u \in PC[0,1] : u \text{ is continuously differentiable at } t \neq t_k, u'(0^+), u'(t_k^+), u'(t_k^-) \text{ exist and } u'(t_k^-) = u'(t_k)\};$
- (iii)  $PC^2[0,1] = \{u \in PC^1[0,1] : u \text{ is twice continuously differentiable at } t \neq t_k\}.$

Note that  $PC[0,1]$  and  $PC^1[0,1]$  are Banach spaces with the norms

$$\|u\|_\infty = \sup \{ |u(t)| : t \in [0,1] \}, \quad \|u\|_1 = \max \{ \|u\|_\infty, \|u'\|_\infty \}, \quad (1.2)$$

respectively.

**Definition 1.1.** The set  $\mathcal{F}$  is said to be quasiequicontinuous in  $[0,c]$  if for any  $\varepsilon > 0$  there exists  $\delta > 0$  such that if  $x \in \mathcal{F}$ ,  $k \in Z$ ,  $t^*, t^{**} \in (t_{k-1}, t_k] \cap [0,c]$ , and  $|t^* - t^{**}| < \delta$ , then  $|x(t^*) - x(t^{**})| < \varepsilon$ .

**LEMMA 1.2** (compactness criterion [7]). *The set  $\mathcal{F} \subset PC([0,c], R^n)$  is relatively compact if and only if one has the following:*

- (1)  $\mathcal{F}$  is bounded;
- (2)  $\mathcal{F}$  is quasiequicontinuous in  $[0,c]$ .

**LEMMA 1.3** [7]. *Let  $s \in [0, T)$ ,  $c_k \geq 0$ ,  $\alpha_k$ ,  $k = 1, \dots, p$ , are constants and let  $p, q \in PC(J, R)$ ,  $x \in PC^1(J, R)$ . If*

$$\begin{aligned} x'(t) &\leq p(t)x(t) + q(t), \quad t \in [s, T), \quad t \neq t_k, \\ x(t_k^+) &\leq c_k x(t_k) + \alpha_k, \quad t_k \in [s, T), \end{aligned} \quad (1.3)$$

then for  $t \in [s, T]$ ,

$$\begin{aligned} x(t) &\leq x(s^+) \left( \prod_{s < t_k < t} c_k \right) \exp \left( \int_s^t p(u) du \right) \\ &\quad + \int_s^t \left( \prod_{u < t_k < t} c_k \right) \exp \left( \int_u^t p(\tau) d\tau \right) q(u) du \\ &\quad + \sum_{s < t_k < t} \left( \prod_{t_k < t_i < t} c_i \right) \exp \left( \int_{t_k}^t p(\tau) d\tau \right) \alpha_k. \end{aligned} \quad (1.4)$$

The result also holds if the above inequalities are reversed.

## 2. Main results

**THEOREM 2.1.** *Let  $f : [0,1] \times R^2 \rightarrow R$  be a continuous function. Assume that there exist  $p(t)$ ,  $q(t)$ , and  $r(t) : [0,1] \rightarrow [0, \infty)$  such that*

$$|f(t, u, v)| \leq p(t)|u| + q(t)|v| + r(t) \quad (2.1)$$

for  $t \in [0, 1]$  and all  $(u, v) \in R^2$ . Then the BVP (1.1) has at least one solution in  $PC^1[0, 1]$  provided

$$Q + B < 1, \quad (2.2)$$

$$\left(1 + \frac{\sum_{i=1}^{m-2} |a_i|}{\left|1 - \sum_{i=1}^{m-2} a_i\right|}\right) \left(\frac{P}{1 - Q - B} + C\right) < 1, \quad (2.3)$$

where  $P = \int_0^1 p(t)dt$ ,  $Q = \int_0^1 q(t)dt$ ,  $B = \sum_{k=1}^T |b_k|$ ,  $C = \sum_{k=1}^T |c_k|$ .

*Proof.* Let  $Y = X = PC^1[0, 1]$ . Define a linear operator  $L : D(L) \subset X \rightarrow Y$  by setting

$$D(L) = \left\{x \in PC^2[0, 1], x'(0) = 0, x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i)\right\}, \quad (2.4)$$

and for  $x \in D(L) : Lx = (x'', \Delta x'(t_k), \Delta x(t_k))$ . We also define a nonlinear mapping  $F : X \rightarrow Y$  by setting

$$(Fx)(t) = (f(t, x(t), x'(t)), b_k x'(t_k), c_k x(t_k)). \quad (2.5)$$

From the assumption on  $f$ , we see that  $F$  is a bounded mapping from  $X$  to  $Y$ . Next, it is easy to see that  $L : D(L) \rightarrow Y$  is one-to-one mapping. Moreover, it follows easily using Lemma 1.2 that  $L^{-1}F : X \rightarrow X$  is a compact mapping.

We note that  $x \in PC^1[0, 1]$  is a solution of (1.1) if and only if  $x$  is a fixed point of the equation

$$x = L^{-1}Fx. \quad (2.6)$$

We apply the Leray-Schauder continuation theorem to obtain the existence of a solution for  $x = L^{-1}Fx$ .

To do this, it suffices to verify that the set of all possible solutions of the family of equations:

$$\begin{aligned} x''(t) &= \lambda f(t, x(t), x'(t)), \\ \Delta x'(t_k^+) &= \lambda b_k x'(t_k), \quad \Delta x(t_k) = \lambda c_k x(t_k), \\ x'(0) &= 0, \quad x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i). \end{aligned} \quad (2.7)$$

Integrate (2.7) from 0 to  $t$  to obtain

$$x'(t) = \lambda \int_0^t f(s, x(s), x'(s)) ds + \lambda \sum_{0 < t_k < t} b_k x'(t_k). \quad (2.8)$$

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By condition (2.1), we have

$$\begin{aligned} |x'(t)| &\leq \int_0^t [p(s)\|x\| + q(s)\|x'\| + r(s)]ds + \sum_{k=1}^T |b_k|\|x'\| \\ &\leq (Q+B)\|x'\| + P\|x\| + R_1, \end{aligned} \quad (2.9)$$

where  $R_1 = \int_0^1 r(t)dt$ . Thus,

$$\|x'\| \leq \frac{1}{1-Q-B} (P\|x\| + R_1). \quad (2.10)$$

Integrate (2.8) from  $t$  to 1 to obtain

$$\begin{aligned} &-x(t) \\ &= \lambda \left\{ \int_0^1 H(t,s)f(s,x(s),x'(s))ds + \int_t^1 \sum_{0 < t_k < s} b_k x'(t_k)ds + \sum_{t < t_k < 1} c_k x(t_k) \right. \\ &\quad \left. + \frac{1}{1 - \sum_{i=1}^{m-2} a_i} \sum_{i=1}^{m-2} a_i \left[ \int_0^1 H(\xi_i, s)f(s, x(s), x'(s))ds + \int_{\xi_i}^1 \sum_{0 < t_k < s} b_k x'(t_k)ds + \sum_{\xi_i < t_k < 1} c_k x(t_k) \right] \right\}, \end{aligned} \quad (2.11)$$

where

$$H(t,s) = \begin{cases} 1-t, & 0 \leq s \leq t \leq 1, \\ 1-s, & 0 \leq t \leq s \leq 1. \end{cases} \quad (2.12)$$

So

$$\|x\| \leq \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) [(P+C)\|x\| + (Q+B)\|x'\| + R_1]. \quad (2.13)$$

Equations (2.10) and (2.13) imply

$$\|x\| \leq \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \left[ \left( \frac{P}{1-Q-B} + C \right) \|x\| + R_1 \right]. \quad (2.14)$$

It follows from the assumption (2.3) that there is a constant  $M_1$  independent of  $\lambda \in [0, 1]$  such that  $\|x\| \leq M_1$ . Furthermore, by (2.10), there is a constant  $M_2$  such that  $\|x'\| \leq M_2$ . It is now immediate that the set of solutions of the family of equations (2.7) is, a priori, bounded in  $PC^1[0, 1]$  by a constant independent of  $\lambda \in [0, 1]$ . This completes the proof of the theorem.

**THEOREM 2.2.** *Let  $f : [0, 1] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ . Assume that the following conditions hold:*

(H<sub>1</sub>)  $|f(t, u, v)| \leq q(t)w(\max\{|u|, |v|\})$  on  $[0, 1] \times \mathbb{R}^2$  with  $w > 0$  continuous and non-decreasing on  $[0, \infty)$ ,  $q(t) : [0, 1] \rightarrow [0, \infty)$  is continuous;

(H<sub>2</sub>)  $b_k \geq 0$ , and

$$\begin{aligned} C \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) &< 1, \\ \sup_{r \geq 0} \frac{r}{w(r)} > M_3 = \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \left[ 1 - C \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \right]^{-1} Q, \end{aligned} \quad (2.15)$$

where  $Q = \int_0^1 \prod_{0 < t_k < 1} (1 + b_k) q(s) ds$ .

Then (1.1) has at least one solution.

Choose  $\tilde{M} > 0$  such that

$$\frac{\tilde{M}}{w(\tilde{M})} > M_3. \quad (2.16)$$

To show that (1.1) has at least one solution, we consider the operator

$$x = \lambda L^{-1} Fx, \quad \lambda \in [0, 1], \quad (2.17)$$

which is equivalent to (2.7). Let  $x \in PC^1[0, 1]$  be any solution of (2.7), from (H<sub>1</sub>), we have

$$-q(t)w(\|x\|_1) \leq x''(t) \leq q(t)w(\|x\|_1). \quad (2.18)$$

Consider the inequalities

$$\begin{aligned} x''(t) &\leq q(t)w(\|x\|_1), \\ x'(t_k) &= (1 + b_k)x(t_k), \\ x'(0) &= 0, \\ x''(t) &\geq -q(t)w(\|x\|_1), \\ x'(t_k) &= (1 + b_k)x(t_k), \\ x'(0) &= 0. \end{aligned} \quad (2.19)$$

By Lemma 1.3, we have

$$\begin{aligned} x'(t) &\leq w(\|x\|_1) \int_0^t \prod_{0 < t_k < s} (1 + b_k) q(s) ds \\ &\leq Qw(\|x\|_1), \\ x'(t) &\geq -w(\|x\|_1) \int_0^t \prod_{0 < t_k < s} (1 + b_k) q(s) ds \\ &\geq -Qw(\|x\|_1). \end{aligned} \quad (2.20)$$

From (2.20), we can deduce

$$|x'(t)| \leq Qw(\|x\|_1), \quad (2.21)$$

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and so

$$\|x'\| \leq Qw(\|x\|_1). \quad (2.22)$$

Using  $x(t) = x(1) - \int_t^1 x'(s)ds - \sum_{t < t_k < 1} c_k x(t_k)$  and  $x(1) = \sum_{i=1}^{m-2} a_i x(\xi_i)$ , we have

$$x(t) = -\frac{1}{1 - \sum_{i=1}^{m-2} a_i} \sum_{i=1}^{m-2} a_i \left[ \int_{\xi_i}^1 x'(s)ds + \sum_{\xi_i < t_k < 1} c_k x(t_k) \right] - \int_t^1 x'(s)ds - \sum_{t < t_k < 1} c_k x(t_k), \quad (2.23)$$

which implies

$$|x(t)| \leq \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) (\|x'\| + C\|x\|), \quad (2.24)$$

and so

$$\begin{aligned} \|x\| &\leq \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \left[ 1 - C \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \right]^{-1} \|x'\| \\ &\leq \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \left[ 1 - C \left( 1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|} \right) \right]^{-1} Qw(\|x\|_1). \end{aligned} \quad (2.25)$$

Now, (2.22) together with (2.25) imply  $\|x\|_1 \neq \widetilde{M}$ . Set

$$U = \{u \in PC^1[0,1] : \|u\|_1 < \widetilde{M}\}, \quad K = E = PC^1[0,1], \quad (2.26)$$

then the nonlinear alternative of Leray-Schauder type [6] guarantees that  $L^{-1}F$  has a fixed point, that is, (1.1) has a solution  $x \in PC^1[0,1]$ , which completes the proof.  $\square$

### 3. Examples

*Example 3.1.* Consider the boundary value problem

$$\begin{aligned} x'' &= f(t, x, x'), \quad t \in [0, 1], t \neq \frac{1}{2}, \\ \Delta x'(t_k) &= \frac{1}{6}x'(t_k), \quad \Delta x(t_k) = \frac{1}{4}x(t_k), \quad t_k = \frac{1}{2}, \\ x'(0) &= 0, \quad x(1) = \frac{1}{2}x\left(\frac{1}{3}\right) - \frac{1}{3}x\left(\frac{2}{3}\right), \end{aligned} \quad (3.1)$$

where

$$f(t, u, v) = t^5 u + \frac{1}{2}t^3 v + t^2 [1 + \cos(u^{200} + v^{30})]. \quad (3.2)$$

It is easy to see that

$$|f(t, u, v)| \leq p(t)|u| + q(t)|v| + r(t) \quad (3.3)$$

with  $p(t) = t^5$ ,  $q(t) = (1/2)t^3$ ,  $r(t) = 2t^2$ . Clearly,  $P = 1/6$ ,  $Q = 1/8$ ,  $B = 1/6$ ,  $C = 1/4$ , and

$$Q+B = \frac{7}{24} < 1, \quad \left(1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|}\right) \left(\frac{P}{1-Q-B} + C\right) = \frac{33}{34} < 1. \quad (3.4)$$

By Theorem 2.1, (3.1) has at least one solution.

*Example 3.2.* Consider the boundary value problem

$$\begin{aligned} x'' &= f(t, x, x'), \quad t \in [0, 1], \quad t \neq \frac{1}{2}, \\ \Delta x'(t_k) &= x'(t_k), \quad \Delta x(t_k) = \frac{1}{3}x(t_k), \quad t_k = \frac{1}{2}, \\ x'(0) &= 0, \quad x(1) = \frac{1}{2}x\left(\frac{1}{3}\right) - \frac{1}{2}x\left(\frac{2}{3}\right), \end{aligned} \quad (3.5)$$

where

$$f(t, u, v) = e^{-t}(u^\alpha + v^\beta) + \mu e^{-t} \quad (3.6)$$

with  $\alpha \in [0, 1]$ ,  $\beta \in [0, 1]$ ,  $\mu > 0$ . It is easy to see that

$$|f(t, u, v)| \leq q(t)w(\max\{|u|, |v|\}) \quad (3.7)$$

with  $q(t) = e^{-t}$ ,  $w(s) = s^\alpha + s^\beta + \mu$ . Clearly

$$\begin{aligned} C \left(1 + \frac{\sum_{i=1}^{m-2} |a_i|}{|1 - \sum_{i=1}^{m-2} a_i|}\right) &= \frac{2}{3} < 1, \\ \sup_{r \geq 0} \frac{r}{w(r)} &= \sup_{r \geq 0} \frac{r}{r^\alpha + r^\beta + \mu} = \infty, \end{aligned} \quad (3.8)$$

so  $(H_2)$  is true. Theorem 2.2 shows that (3.5) has at least one solution.

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