

## Research Article

# Liouville Theorems for a Class of Linear Second-Order Operators with Nonnegative Characteristic Form

Alessia Elisabetta Kogoj and Ermanno Lanconelli

Received 1 August 2006; Revised 28 November 2006; Accepted 29 November 2006

Recommended by Vincenzo Vespri

We report on some Liouville-type theorems for a class of linear second-order partial differential equation with nonnegative characteristic form. The theorems we show improve our previous results.

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## 1. Introduction

In this paper, we survey and improve some Liouville-type theorems for a class of hypoelliptic second-order operators, appeared in the series of papers [1–4].

The operators considered in these papers can be written as follows:

$$\mathcal{L} := \sum_{i,j=1}^N \partial_{x_i} (a_{ij}(x) \partial_{x_j}) + \sum_{i=1}^N b_i(x) \partial_{x_i} - \partial_t, \quad (1.1)$$

where the coefficients  $a_{ij}$ ,  $b_i$  are  $t$ -independent and smooth in  $\mathbb{R}^N$ . The matrix  $A = (a_{ij})_{i,j=1,\dots,N}$  is supposed to be symmetric and nonnegative definite at any point of  $\mathbb{R}^N$ .

We will denote by  $z = (x, t)$ ,  $x \in \mathbb{R}^N$ ,  $t \in \mathbb{R}$ , the point of  $\mathbb{R}^{N+1}$ , by  $Y$  the first-order differential operator

$$Y := \sum_{i=1}^N b_i(x) \partial_{x_i} - \partial_t, \quad (1.2)$$

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and by  $\mathcal{L}_0$  the *stationary* counterpart of  $\mathcal{L}$ , that is,

$$\mathcal{L}_0 := \sum_{i,j=1}^N \partial_{x_i} (a_{ij}(x) \partial_{x_j}) + \sum_{i=1}^N b_i(x) \partial_{x_i}. \quad (1.3)$$

We always assume the operator  $Y$  to be divergence free, that is,  $\sum_{i=1}^N \partial_{x_i} b_i(x) = 0$  at any point  $x \in \mathbb{R}^N$ . Moreover, as in [2], we assume the following hypotheses.

(H1)  $\mathcal{L}$  is homogeneous of degree two with respect to the group of dilations  $(d_\lambda)_{\lambda>0}$  given by

$$\begin{aligned} d_\lambda(x, t) &= (D_\lambda(x), \lambda^2 t), \\ D_\lambda(x) &= D_\lambda(x_1, \dots, x_N) = (\lambda^{\sigma_1} x_1, \dots, \lambda^{\sigma_N} x_N), \end{aligned} \quad (1.4)$$

where  $\sigma = (\sigma_1, \dots, \sigma_N)$  is an  $N$ -tuple of natural numbers satisfying  $1 = \sigma_1 \leq \sigma_2 \leq \dots \leq \sigma_N$ . When we say that  $\mathcal{L}$  is  $d_\lambda$ -homogeneous of degree two, we mean that

$$\mathcal{L}(u(d_\lambda(x, t))) = \lambda^2 (\mathcal{L}u)(d_\lambda(x, t)) \quad \forall u \in C^\infty(\mathbb{R}^{N+1}). \quad (1.5)$$

(H2) For every  $(x, t), (y, \tau) \in \mathbb{R}^{N+1}$ ,  $t > \tau$ , there exists an  $\mathcal{L}$ -admissible path  $\eta : [0, T] \rightarrow \mathbb{R}^{N+1}$  such that  $\eta(0) = (x, t)$ ,  $\eta(T) = (y, \tau)$ .

An  $\mathcal{L}$ -admissible path is any continuous path  $\eta$  which is the sum of a finite number of diffusion and drift trajectories.

A *diffusion trajectory* is a curve  $\eta$  satisfying, at any points of its domain, the inequality

$$(\langle \eta'(s), \xi \rangle)^2 \leq \langle \hat{A}(\eta(s)) \xi, \xi \rangle \quad \forall \xi \in \mathbb{R}^N. \quad (1.6)$$

Here  $\langle \cdot, \cdot \rangle$  denotes the inner product in  $\mathbb{R}^{N+1}$  and  $\hat{A}(z) = \hat{A}(x, t) = \hat{A}(x)$  stands for the  $(N+1) \times (N+1)$  matrix

$$\hat{A} = \begin{pmatrix} A & 0 \\ 0 & 0 \end{pmatrix}. \quad (1.7)$$

A *drift trajectory* is a positively oriented integral curve of  $Y$ .

Throughout the paper, we will denote by  $Q$  the homogeneous dimension of  $\mathbb{R}^{N+1}$  with respect to the dilations (1.4), that is,

$$Q = \sigma_1 + \dots + \sigma_N + 2 \quad (1.8)$$

and assume

$$Q \geq 5. \quad (1.9)$$

Then, the  $D_\lambda$ -homogeneous dimension of  $\mathbb{R}^N$  is  $Q - 2 \geq 3$ .

We explicitly remark that the smoothness of the coefficients of  $\mathcal{L}$  and the homogeneity assumption in (H1) imply that the  $a_{ij}$ 's and the  $b_i$ 's are polynomial functions (see [5, Lemma 2]). Moreover, the “oriented” connectivity condition in (H1) implies the

hypoellipticity of  $\mathcal{L}$  and of  $\mathcal{L}_0$  (see [1, Proposition 10.1]). For any  $z = (x, t) \in \mathbb{R}^{N+1}$ , we define the  $d_\lambda$ -homogeneous norm  $|z|$  by

$$|z| = |(x, t)| := (|x|^4 + t^2)^{1/4}, \quad (1.10)$$

where

$$|x| = |(x_1, \dots, x_N)| = \left( \sum_{j=1}^N (x_j^2)^{\sigma/\sigma_j} \right)^{1/2\sigma}, \quad \sigma = \prod_{j=1}^N \sigma_j. \quad (1.11)$$

Hypotheses (H1) and (H2) imply the existence of a fundamental solution  $\Gamma(z, \zeta)$  of  $\mathcal{L}$  with the following properties (see [2, page 308]):

- (i)  $\Gamma$  is smooth in  $\{(z, \zeta) \in \mathbb{R}^{N+1} \times \mathbb{R}^{N+1} \mid z \neq \zeta\}$ ,
- (ii)  $\Gamma(\cdot, \zeta) \in L_{\text{loc}}^1(\mathbb{R}^{N+1})$  and  $\mathcal{L}\Gamma(\cdot, \zeta) = -\delta_\zeta$  for every  $\zeta \in \mathbb{R}^{N+1}$ ,
- (iii)  $\Gamma(z, \cdot) \in L_{\text{loc}}^1(\mathbb{R}^{N+1})$  and  $\mathcal{L}^*\Gamma(z, \cdot) = -\delta_z$  for every  $z \in \mathbb{R}^{N+1}$ ,
- (iv)  $\limsup_{\zeta \rightarrow z} \Gamma(z, \zeta) = \infty$  for every  $z \in \mathbb{R}^{N+1}$ ,
- (v)  $\Gamma(0, \zeta) \rightarrow 0$  as  $\zeta \rightarrow \infty$ ,  $\Gamma(0, d_\lambda(\zeta)) = \lambda^{-Q+2}\Gamma(0, \zeta)$ ,
- (vi)  $\Gamma((x, t), (\xi, \tau)) \geq 0$ ,  $> 0$  if and only if  $t > \tau$ ,
- (vii)  $\Gamma((x, t), (\xi, \tau)) = \Gamma((x, 0), (\xi, \tau - t))$ .

In (iii)  $\mathcal{L}^*$  denotes the formal adjoint of  $\mathcal{L}$ .

These properties of  $\Gamma$  allow to obtain a mean value formula at  $z = 0$  for the entire solutions to  $\mathcal{L}u = 0$ . We then use this formula to prove a *scaling invariant Harnack inequality* for the *nonnegative* solutions  $\mathcal{L}u = f$  in  $\mathbb{R}^{N+1}$ . Our first Liouville-type theorems will follow from this Harnack inequality. All these results will be showed in Section 2.

In Section 3, we show some *asymptotic* Liouville theorem for nonnegative solution to  $\mathcal{L}u = 0$  in the halfspace  $\mathbb{R}^N \times ] - \infty, 0[$  assuming that  $\mathcal{L}$ , together with (H1) and (H2), is left invariant with respect to some Lie groups in  $\mathbb{R}^{N+1}$ .

Finally, in Section 4 some examples of operators to which our results apply are showed.

## 2. Polynomial Liouville theorems

Throughout this section, we will assume that  $\mathcal{L}$  in (1.1) satisfies hypotheses (H1) and (H2). Let  $\Gamma$  be the fundamental solution of  $\mathcal{L}$  with pole at the origin. With a standard procedure based on the Green identity for  $\mathcal{L}$  and by using the properties of  $\Gamma$  recalled in the introduction, one obtains a mean value formula at  $z = 0$  for the solution to  $\mathcal{L}u = 0$ . Precisely, for every point  $(0, T) \in \mathbb{R}^{N+1}$  and  $r > 0$ , define the  $\mathcal{L}$ -ball centered at  $(0, T)$  and with radius  $r$ , as follows:

$$\Omega_r(0, T) := \left\{ \zeta \in \mathbb{R}^{N+1} : \Gamma((0, T), \zeta) > \left( \frac{1}{r} \right)^{Q-2} \right\}. \quad (2.1)$$

Then, if  $\mathcal{L}u = 0$  in  $\mathbb{R}^{N+1}$ , one has

$$u(0, T) = \left( \frac{1}{r} \right)^{Q-2} \int_{\Omega_r(0, T)} K(T, \zeta) u(\zeta) d\zeta, \quad (2.2)$$

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where

$$K(T, \zeta) = \frac{\langle A(\xi) \nabla_\xi \Gamma, \nabla_\xi \Gamma \rangle}{\Gamma^2}, \quad \zeta = (\xi, \tau), \quad (2.3)$$

and  $\Gamma$  stands for  $\Gamma((0, T), (\xi, \tau))$ . Moreover,  $\langle \cdot, \cdot \rangle$  denotes the inner product in  $\mathbb{R}^N$  and  $\nabla_\xi$  is the gradient operator  $(\partial_{\xi_1}, \dots, \partial_{\xi_N})$ .

Formula (2.2) is just one of the numerous extensions of the classical Gauss mean value theorem for harmonic functions. For a proof of it, we directly refer to [6, Theorem 1.5]. We would like to stress that in this proof one uses our assumption  $\operatorname{div} Y = 0$ .

The kernel  $K(T, \cdot)$  is strictly positive in a dense open subset of  $\Omega_r(0, T)$  for every  $T, r > 0$  (see [2, Lemma 2.3]). This property of  $K(T, \cdot)$ , together with the  $d_\lambda$ -homogeneity of  $\mathcal{L}$ , leads to the following Harnack-type inequality for entire solutions to  $\mathcal{L}u = 0$ .

**THEOREM 2.1.** *Let  $u : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$  be a nonnegative solution to  $\mathcal{L}u = 0$  in  $\mathbb{R}^{N+1}$ . Then, there exist two positive constants  $C = C(\mathcal{L})$  and  $\theta = \theta(\mathcal{L})$  such that*

$$\sup_{C_{0r}} u \leq C u(0, r^2) \quad \forall r > 0, \quad (2.4)$$

where, for  $\rho > 0$ ,  $C_\rho$  denotes the  $d_\lambda$ -symmetric ball

$$C_\rho := \{z \in \mathbb{R}^{N+1} \mid |z| < \rho\}. \quad (2.5)$$

The proof of this theorem is contained in [2, page 310].

By using inequality (2.4) together with some basic properties of the fundamental solution  $\Gamma$ , one easily gets the following a priori estimates for the positive solution to  $\mathcal{L}u = f$  in  $\mathbb{R}^{N+1}$ .

**COROLLARY 2.2.** *Let  $f$  be a smooth function in  $\mathbb{R}^{N+1}$  and let  $u$  be a nonnegative solution to*

$$\mathcal{L}u = f \quad \text{in } \mathbb{R}^{N+1}. \quad (2.6)$$

*Then there exists a positive constant  $C$  independent of  $u$  and  $f$  such that*

$$u(z) \leq C u \left( 0, \left( \frac{|z|}{\theta} \right)^2 \right) + |z|^2 \sup_{|\zeta| \leq |z|/\theta^2} |f(\zeta)|, \quad (2.7)$$

where  $\theta$  is the constant in Theorem 2.1.

This result allows to use the Liouville-type theorem of Luo [5] to obtain our main result in this section.

**THEOREM 2.3.** *Let  $u : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$  be a smooth function such that*

$$\begin{aligned} \mathcal{L}u &= p \quad \text{in } \mathbb{R}^{N+1}, \\ u &\geq q \quad \text{in } \mathbb{R}^{N+1}, \end{aligned} \quad (2.8)$$

where  $p$  and  $q$  are polynomial function. Assume

$$u(0, t) = O(t^m) \quad \text{as } t \rightarrow \infty. \quad (2.9)$$

Then,  $u$  is a polynomial function.

*Proof.* We split the proof into two steps.

*Step 1.* There exists  $n > 0$  such that

$$u(z) = O(|z|^n) \quad \text{as } z \rightarrow \infty. \quad (2.10)$$

Indeed, letting  $v := u - q$ , we have

$$\begin{aligned} \mathcal{L}v &= p - \mathcal{L}q \quad \text{in } \mathbb{R}^{N+1}, \\ v &\geq 0 \quad \text{in } \mathbb{R}^{N+1}, \end{aligned} \quad (2.11)$$

and  $v(0, t) = u(0, t) - q(0, t) = O(t^{n_1})$  as  $t \rightarrow \infty$ , for a suitable  $n_1 > 0$ . Moreover, since  $p$  and  $\mathcal{L}q$  are polynomial functions,  $(p - \mathcal{L}q)(z) = O(|z|^{m_1})$  as  $z \rightarrow \infty$  for a suitable  $m_1 > 0$ . Then, by the previous corollary, there exists  $m_2 > 0$  such that

$$v(z) = O(|z|^{m_2}) \quad \text{as } z \rightarrow \infty. \quad (2.12)$$

From this estimate, since  $v = u + q$ , and  $q$  is a polynomial function, the assertion (2.10) follows.

*Step 2.* Since  $p$  is a polynomial function and  $\mathcal{L}$  is  $d_\lambda$ -homogeneous, there exists  $m \in \mathbb{N}$  such that

$$\mathcal{L}^{(m)} p \equiv 0, \quad (2.13)$$

where  $\mathcal{L}^{(m)} = \mathcal{L} \circ \dots \circ \mathcal{L}$  is the  $m$ th iterated of  $\mathcal{L}$ . It follows that

$$\mathcal{L}^{(m+1)} u = 0 \quad \text{in } \mathbb{R}^{N+1}. \quad (2.14)$$

Moreover, since  $\mathcal{L}$  is  $d_\lambda$ -homogeneous and hypoelliptic, the same properties hold for  $\mathcal{L}^{(m+1)}$ . On the other hand, by Step 1,  $u(z) = O(z^m)$  as  $z \rightarrow \infty$ , so that  $u$  is a *tempered distribution*. Then, by Luo's paper [5, Theorem 1],  $u$  is a *polynomial function*.  $\square$

*Remark 2.4.* It is well known that hypothesis (2.9) in the previous theorem cannot be removed. Indeed, if  $\mathcal{L} = \Delta - \partial_t$  is the classical heat operator and  $u(x, t) = \exp(x_1 + \dots + x_N + Nt)$ ,  $x = (x_1, \dots, x_N) \in \mathbb{R}^N$  and  $t \in \mathbb{R}$ , we have

$$\mathcal{L}u = 0 \quad \text{in } \mathbb{R}^{N+1}, \quad u \geq 0, \quad (2.15)$$

and  $u$  is *not* a polynomial function.

In the previous theorem, the degree of the polynomial function  $u$  can be estimated in terms of the ones of  $p$  and  $q$ . For this, we need some more notation. If  $\alpha = (\alpha_1, \dots, \alpha_N, \alpha_{N+1})$  is a multi-index with  $(N + 1)$  nonnegative integer components, we let

$$|\alpha|_{d_\lambda} := \sigma_1 \alpha_1 + \dots + \sigma_N \alpha_N + 2\alpha_{N+1}, \quad (2.16)$$

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and, if  $z = (x, t) = (x_1, \dots, x_N, t) \in \mathbb{R}^{N+1}$ ,

$$z^\alpha := x_1^{\alpha_1} \cdots x_N^{\alpha_N} t^{\alpha_{N+1}}. \quad (2.17)$$

As a consequence, we can write every polynomial function  $p$  in  $\mathbb{R}^{N+1}$ , as follows:

$$p(z) = \sum_{|\alpha|_{d_\lambda} \leq m} c_\alpha z^\alpha \quad (2.18)$$

with  $m \in \mathbb{Z}$ ,  $m \geq 0$ , and  $c_\alpha \in \mathbb{R}$  for every multi-index  $\alpha$ . If

$$\sum_{|\alpha|_{d_\lambda} = m} c_\alpha z^\alpha \not\equiv 0 \quad \text{in } \mathbb{R}^{N+1}, \quad (2.19)$$

then we set

$$m = \deg_{d_\lambda} p. \quad (2.20)$$

If  $p$  is independent of  $t$ , that is, if  $p$  is a polynomial function in  $\mathbb{R}^N$ , we denote by

$$\deg_{D_\lambda} p \quad (2.21)$$

the degree of  $p$  with respect to the dilations  $(D_\lambda)_{\lambda>0}$ . Obviously, in this case,  $\deg_{d_\lambda} p = \deg_{D_\lambda} p$ .

**PROPOSITION 2.5.** *Let  $u, p : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$  be polynomial functions such that*

$$\mathcal{L}u = p \quad \text{in } \mathbb{R}^{N+1}. \quad (2.22)$$

*Assume  $u \geq 0$ . Thus, the following statements hold.*

- (i) *If  $p \equiv 0$ , then  $u = \text{constant}$ .*
- (ii) *If  $p \not\equiv 0$ , then*

$$\deg_{d_\lambda} u = 2 + \deg_{d_\lambda} p. \quad (2.23)$$

This proposition is a consequence of the following lemma.

**LEMMA 2.6.** *Let  $u : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$  be a nonnegative polynomial function  $d_\lambda$ -homogeneous of degree  $m > 0$ . Then  $\mathcal{L}u \not\equiv 0$  in  $\mathbb{R}^{N+1}$ .*

*Proof.* We argue by contradiction and assume  $\mathcal{L}u = 0$ . Since  $u$  is nonnegative and  $d_\lambda$ -homogeneous of strictly positive degree, we have

$$u(0, 0) = 0 = \min_{\mathbb{R}^{N+1}} u. \quad (2.24)$$

Let us now denote by  $\mathcal{P}$  the  $\mathcal{L}$ -propagation set of  $(0, 0)$  in  $\mathbb{R}^{N+1}$ , that is, the set

$$\begin{aligned} \mathcal{P} := \{ & z \in \mathbb{R}^{N+1} : \text{there exists an } \mathcal{L}\text{-admissible path } \eta : [0, T] \longrightarrow \mathbb{R}^{N+1}, \\ & \text{s.t. } \eta(0) = (0, 0), \eta(T) = z \}. \end{aligned} \quad (2.25)$$

From hypotheses (H2), we obtain  $\mathcal{P} = \mathbb{R}^N \times ] - \infty, 0]$  so that, since  $(0,0)$  is a minimum point of  $u$  and the minimum spread all over  $\mathcal{P}$  (see [7]), we have

$$u(z) = u(0,0) = 0 \quad \forall z \in \mathbb{R}^N \times ] - \infty, 0]. \quad (2.26)$$

Then, being  $u$  a polynomial function,  $u \equiv 0$  in  $\mathbb{R}^{N+1}$ . This contradicts the assumption  $\deg_{d_\lambda} u > 0$ , and completes the proof.  $\square$

*Proof of Proposition 2.5.* Obviously, if  $u = \text{constant}$ , we have nothing to prove. If we assume  $m := \deg_{d_\lambda} u > 0$  and prove that

$$m \geq 2, \quad p \not\equiv 0, \quad \deg_{d_\lambda} p = m - 2, \quad (2.27)$$

then it would complete the proof. Let us write  $u$  as follows:

$$u = u_0 + u_1 + \cdots + u_m, \quad (2.28)$$

where  $u_j$  is a polynomial function  $d_\lambda$ -homogeneous of degree  $j$ ,  $j = 0, \dots, m$ , and  $u_m \not\equiv 0$  in  $\mathbb{R}^{N+1}$ .

Then

$$p = \mathcal{L}u = \mathcal{L}u_0 + \mathcal{L}u_1 + \cdots + \mathcal{L}u_m, \quad (2.29)$$

and, since  $\mathcal{L}$  is  $d_\lambda$ -homogeneous of degree two,

$$(\mathcal{L}u_j)(d_\lambda(x)) = \lambda^{j-2} \mathcal{L}u_j(x) \quad (2.30)$$

so that  $\mathcal{L}u_0 = \mathcal{L}u_1 \equiv 0$  and  $\deg_{d_\lambda} \mathcal{L}u_j = j - 2$  if and only if  $\mathcal{L}u_j \not\equiv 0$ .

On the other hand, the hypothesis  $u \geq 0$  implies  $u_m \geq 0$  so that, being  $u_m \not\equiv 0$  and  $d_\lambda$ -homogeneous of degree  $m > 0$ , by Lemma 2.6, we get  $\mathcal{L}u_m \not\equiv 0$ . Hence  $m \geq 2$ . Moreover, by (2.29),  $p = \mathcal{L}u \not\equiv 0$  and

$$\deg_{d_\lambda} p = \deg_{d_\lambda} \mathcal{L}u_m = m - 2. \quad (2.31)$$

$\square$

This proposition allows us to make more precise the conclusion of Theorem 2.3. Indeed, we have the following.

**PROPOSITION 2.7.** *Let  $u, p, q : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$  be polynomial functions such that*

$$\begin{aligned} \mathcal{L}u &= p \quad \text{in } \mathbb{R}^{N+1}, \\ u &\geq q \quad \text{in } \mathbb{R}^{N+1}. \end{aligned} \quad (2.32)$$

*Then*

$$\deg_{d_\lambda} u \leq \max \{2 + \deg_{d_\lambda} p, \deg_{d_\lambda} q\}. \quad (2.33)$$

*In particular, and more precisely, if  $q = 0$ , that is, if  $u \geq 0$ , then*

$$\begin{aligned} \deg_{d_\lambda} u &= 2 + \deg_{d_\lambda} p \quad \text{if } p \not\equiv 0, \\ u &= \text{constant} \quad \text{if } p \equiv 0. \end{aligned} \quad (2.34)$$

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*Proof.* If  $q \equiv 0$ , the assertion is the one of Proposition 2.5. Suppose  $q \not\equiv 0$ . By letting  $v := u - q$ , we have

$$\mathcal{L}v = p - \mathcal{L}q, \quad v \geq 0. \quad (2.35)$$

By Proposition 2.5, we have

$$\deg_{d_\lambda} v \leq 2 + \deg_{d_\lambda} (p - \mathcal{L}q) \leq 2 + \max \{ \deg_{d_\lambda} p, \deg_{d_\lambda} q - 2 \} = \max \{ 2 + \deg_{d_\lambda} p, \deg_{d_\lambda} q \} \quad (2.36)$$

and (2.33) follows.  $\square$

Proposition 2.7, together with Theorem 2.3, extends and improves the Liouville-type theorems contained in [2, 4] (precisely [2, Theorem 1.1] and [4, Theorem 1.2]).

From Theorem 2.3 and Proposition 2.7, we straightforwardly get the following polynomial Liouville theorem for the stationary operator  $\mathcal{L}_0$  in (1.3).

**THEOREM 2.8.** *Let  $P, Q : \mathbb{R}^N \rightarrow \mathbb{R}$  be polynomial functions and let  $U : \mathbb{R}^N \rightarrow \mathbb{R}$  be a smooth function such that*

$$\mathcal{L}_0 U = P, \quad U \geq Q, \text{ in } \mathbb{R}^N. \quad (2.37)$$

*Then,  $U$  is a polynomial function and*

$$\deg_{D_\lambda} U \leq \max \{ 2 + \deg_{D_\lambda} P, \deg_{D_\lambda} Q \}. \quad (2.38)$$

*In particular, and more precisely, if  $Q \equiv 0$ , that is, if  $U \geq 0$ , then*

$$\begin{aligned} \deg_{D_\lambda} U &= 2 + \deg_{D_\lambda} P && \text{if } P \not\equiv 0, \\ U &= \text{constant} && \text{if } P \equiv 0. \end{aligned} \quad (2.39)$$

*Proof.* Let us define

$$u(x, t) = U(x), \quad p(x, t) = P(x), \quad q(x, t) = Q(x). \quad (2.40)$$

Then  $p, q$  are polynomial functions in  $\mathbb{R}^{N+1}$  and  $u$  is a smooth solution to the equation

$$\mathcal{L}u = p \quad \text{in } \mathbb{R}^{N+1}, \quad (2.41)$$

such that  $u \geq q$ . Moreover,

$$u(0, t) = U(0) = O(1) \quad \text{as } t \longrightarrow \infty. \quad (2.42)$$

Then, by Theorem 2.3,  $u$  is a polynomial function in  $\mathbb{R}^{N+1}$ . This obviously implies that  $U$  is a polynomial in  $\mathbb{R}^N$ . The second part of the theorem immediately follows from Proposition 2.5.  $\square$



*Remark 2.9.* The class of our stationary operators  $\mathcal{L}_0$  also contains “parabolic”-type operators like, for example, the following “forward-backward” heat operator

$$\mathcal{L}_0 := \partial_{x_1}^2 + x_1 \partial_{x_2} \quad \text{in } \mathbb{R}^2. \quad (2.43)$$

Nevertheless, in Theorem 2.8, we do not require any a priori behavior at infinity, like condition (2.9) in Theorem 2.3.

### 3. Asymptotic Liouville theorems in halfspaces

The operator  $\mathcal{L}$  in our class do not satisfy the *usual* Liouville property. Precisely, if  $u$  is a nonnegative solution to

$$\mathcal{L}u = 0 \quad \text{in } \mathbb{R}^{N+1}, \quad (3.1)$$

then we cannot conclude that  $u \equiv \text{constant}$  without asking an extra condition on the solution  $u$  (see Theorem 2.3 and Remark 2.4).

However, if we also assume that  $\mathcal{L}$  is left translation invariant with respect to the composition law of some Lie group in  $\mathbb{R}^{N+1}$ , then we can show that *every nonnegative solution of (3.1) is constant at  $t = -\infty$* .

To be precise, let us fix the new hypothesis on  $\mathcal{L}$  and give the definition of  $\mathcal{L}$ -parabolic trajectory.

Suppose  $\mathcal{L}$  satisfies (H2) of the introduction and, instead of (H1), the following condition

(H1)\* There exists a homogeneous Lie group in  $\mathbb{R}^{N+1}$ ,

$$\mathbb{L} = (\mathbb{R}^{N+1}, \circ, d_\lambda) \quad (3.2)$$

such that  $\mathcal{L}$  is left translation invariant on  $\mathbb{L}$  and  $d_\lambda$ -homogeneous of degree two.

We assume the composition law  $\circ$  is Euclidean in the time variable, that is,

$$(x, t) \circ (x', t') = (c(x, t, x', t'), t + t'), \quad (3.3)$$

where  $c(x, t, x', t')$  denotes a suitable function of  $(x, t)$  and  $(x', t')$ .

It is a standard matter to prove the existence of a positive constant  $C$  such that

$$|z \circ \zeta| \leq C(|z| + |\zeta|) \quad \forall z, \zeta \in \mathbb{R}^{N+1}. \quad (3.4)$$

Let  $\gamma: [0, \infty[ \rightarrow \mathbb{R}^N$  be a continuous function such that

$$\limsup_{s \rightarrow \infty} \frac{|\gamma(s)|^2}{s} < \infty \quad (3.5)$$

(here  $|\cdot|$  denotes the  $D_\lambda$ -homogeneous norm (1.11)).

Then, the path

$$s \mapsto \eta(s) = (\gamma(s), T - s), \quad T \in \mathbb{R}, \quad (3.6)$$

will be called an  $\mathcal{L}$ -parabolic trajectory.

Obviously, the curve

$$s \mapsto \eta(s) = (\alpha, T - s), \quad \alpha \in \mathbb{R}^N, T \in \mathbb{R} \quad (3.7)$$

is an  $\mathcal{L}$ -parabolic trajectory. It can be proved that every integral curve of the vector fields  $Y$  in (1.2) also is an  $\mathcal{L}$ -parabolic trajectory (see [3, Lemma 3]).

Our first asymptotic Liouville theorem is the following one.

**THEOREM 3.1.** *Let  $\mathcal{L}$  satisfy hypotheses (H1)\* and (H2), and let  $u$  be a nonnegative solution to the equation*

$$\mathcal{L}u = 0 \quad (3.8)$$

*in the halfspace*

$$S = \mathbb{R}^N \times ]-\infty, 0[. \quad (3.9)$$

*Then, for every  $\mathcal{L}$ -parabolic trajectory  $\eta$ ,*

$$\lim_{s \rightarrow \infty} u(\eta(s)) = \inf_S u. \quad (3.10)$$

*In particular*

$$\lim_{t \rightarrow -\infty} u(x, t) = \inf_S u \quad \forall x \in \mathbb{R}^N. \quad (3.11)$$

The proof of this theorem relies on a *left translation* and *scaling invariant* Harnack inequality for nonnegative solutions to  $\mathcal{L}u = 0$ .

For every  $z_0 \in \mathbb{R}^{N+1}$  and  $M > 0$ , let us put

$$P_{z_0}(M) := z_0 \circ P(M), \quad (3.12)$$

where

$$P(M) := \{(x, t) \in \mathbb{R}^{N+1} : |x|^2 \leq -Mt\}. \quad (3.13)$$

Then, the following theorem holds.

**THEOREM 3.2** (left and scaling invariant Harnack inequality). *Let  $u$  be a nonnegative solution to*

$$\mathcal{L}u = 0 \quad \text{in } \mathbb{R}^N \times ]-\infty, 0[. \quad (3.14)$$

Then, for every  $z_0 \in \mathbb{R}^N \times ]-\infty, 0[$  and  $M > 0$ , there exists a positive constant  $C = C(M)$ , independent of  $z_0$  and  $u$ , such that

$$\sup_{P_{z_0}(M)} u \leq Cu(z_0). \quad (3.15)$$

*Proof.* It follows from Theorem 2.1 and the left translation invariance of  $\mathcal{L}$ . The details are contained in [3, Proof of Theorem 3].  $\square$

From this theorem we obtain the proof of Theorem 3.1.

*Proof of Theorem 3.1.* We may assume  $\inf_s u = 0$ . Let  $\eta(s) = (\gamma(s), s_0 - s)$ ,  $s_0 \leq 0$ ,  $s \geq s_0$  be an  $\mathcal{L}$ -parabolic trajectory. Then, there exists  $M_0 > 0$  such that

$$|\gamma(s)|^2 \leq M_0 s \quad \forall s \geq s^*, \quad (3.16)$$

where  $s^* > 0$  is big enough. Let us put  $M = 2C(M_0^2 + 1)^{1/4}$  where  $C$  is the positive constant in the triangular inequality (3.4). Let  $\varepsilon > 0$  be arbitrarily fixed and choose  $z_\varepsilon = (x_\varepsilon, t_\varepsilon) \in S$  such that

$$u(z_\varepsilon) < \varepsilon. \quad (3.17)$$

Now, for every  $s \geq s^*$ , we have

$$\begin{aligned} |z_\varepsilon^{-1} \circ \eta(s)| &\leq C(|z_\varepsilon^{-1}| + |\eta(s)|) \\ &\leq C(|z_\varepsilon^{-1}| + (M_0^2 + 1)^{1/4} \sqrt{s}) \\ &= C\sqrt{s - s_0 + t_\varepsilon} \left( \frac{|z_\varepsilon^{-1}|}{\sqrt{s - s_0 + t_\varepsilon}} + (M_0^2 + 1)^{1/4} \sqrt{\frac{s}{s - s_0 + t_\varepsilon}} \right). \end{aligned} \quad (3.18)$$

Then, there exists  $T = T(\varepsilon) > 0$  such that

$$|z_\varepsilon^{-1} \circ \eta(s)| \leq M\sqrt{s - s_0 + t_\varepsilon} \quad \forall s > T. \quad (3.19)$$

This implies that

$$\eta(s) \in z_\varepsilon \circ P(M) \equiv P_{z_\varepsilon}(M) \quad \forall s > T. \quad (3.20)$$

On the other hand, by the Harnack inequality of Theorem 3.2, there exists  $C^* = C^*(M) > 0$  independent of  $z_\varepsilon$  and  $\varepsilon$  such that

$$\sup_{P_{z_\varepsilon}(M)} u \leq C^* u(z_\varepsilon). \quad (3.21)$$

Therefore,

$$u(\eta(s)) \leq C^* \varepsilon \quad \forall s > T. \quad (3.22)$$

Since  $C^*$  is independent of  $\varepsilon$ , this proves the theorem.  $\square$

Theorem 3.1 is contained in [3, Theorem 1]. The idea of our proof is taken from Glagoleva's paper [8], in which classical parabolic operators of Cordes-type are considered. For the heat equation, a stronger version of Theorem 3.1 was proved by Bear [9].

The following theorem improves Theorem 3.1.

**THEOREM 3.3.** *Let  $\mathcal{L}$  and  $u$  as in Theorem 3.1. For every  $M > 0$  and  $t < 0$ , define*

$$M(u, t) = \sup \{u(x, t) : |x|^2 \leq -Mt\}. \quad (3.23)$$

*Then*

$$\lim_{t \rightarrow -\infty} M(u, t) = \inf_S u. \quad (3.24)$$

*Proof.* Let  $\varepsilon$  be arbitrarily fixed and let  $z_\varepsilon = (x_\varepsilon, t_\varepsilon) \in S$  be such that

$$u(z_\varepsilon) < m + \varepsilon, \quad m := \inf_S u. \quad (3.25)$$

Let  $M_0$  be a positive constant that will be chosen later independently of  $\varepsilon$ . Since  $u - m$  is a nonnegative solution to  $\mathcal{L}v = 0$  in  $S$ , the Harnack inequality of Theorem 3.2 implies

$$u(z) - m \leq C_0(u(z_\varepsilon) - m) \quad \forall z \in P_{z_\varepsilon}(M_0), \quad (3.26)$$

where  $C_0 = C_0(M_0)$  is independent of  $\varepsilon$  (and  $u$ ).

Let  $C$  be the constant in the triangularity inequality (3.4) and choose  $T = T(u, \varepsilon) > 0$  such that

$$T > 2|z_\varepsilon - 1|^2 + 2|t_\varepsilon|. \quad (3.27)$$

Then, if  $z = (x, t) \in S$  with  $t < -T$  and  $|x|^2 < -Mt$ , we have

$$\begin{aligned} |z_\varepsilon^{-1} \circ z| &\leq C(|z_\varepsilon|^{-1} + |z|) \leq C(|z_\varepsilon|^{-1} + (\sqrt{M} + 1)\sqrt{-t}) \\ &= C\sqrt{t_\varepsilon - t} \left( \frac{|z_\varepsilon^{-1}|}{\sqrt{t_\varepsilon - t}} + (\sqrt{M} + 1) \sqrt{\frac{1}{1 - |t_\varepsilon/t|}} \right) \\ &\leq C\sqrt{t_\varepsilon - t} (1 + \sqrt{2}(\sqrt{M} + 1)) =: M_0. \end{aligned} \quad (3.28)$$

Then, by (3.25) and (3.26),

$$m \leq u(z) \leq m + C_0\varepsilon \quad (3.29)$$

for every  $z = (x, t) \in S$  with  $t < -T$  and  $|x|^2 < -Mt$ . Thus

$$m \leq M(u, t) \leq m + C_0\varepsilon \quad \forall t < -T. \quad (3.30)$$

Since  $C_0$  does not depend on  $\varepsilon$ , this completes the proof.  $\square$

#### 4. Some examples

In this section, we show some explicit examples of operators to which our results apply.

*Example 4.1* (heat operators on Carnot groups). Let  $(\mathbb{R}^N, \circ)$  be a Lie group in  $\mathbb{R}^N$ . Assume that  $\mathbb{R}^N$  can be split as follows:

$$\mathbb{R}^N = \mathbb{R}^{N_1} \times \dots \times \mathbb{R}^{N_m} \quad (4.1)$$

and that the dilations

$$\begin{aligned} D_\lambda : \mathbb{R}^N &\longrightarrow \mathbb{R}^N, & D_\lambda(x^{(N_1)}, \dots, x^{(N_m)}) &= (\lambda x^{(N_1)}, \dots, \lambda^m x^{(N_m)}) \\ x^{(N_i)} &\in \mathbb{R}^{N_i}, & i &= 1, \dots, m, \lambda > 0, \end{aligned} \quad (4.2)$$

are automorphisms of  $(\mathbb{R}^N, \circ)$ .

We also assume

$$\text{rankLie}\{X_1, \dots, X_{N_1}\}(x) = N \quad \forall x \in \mathbb{R}^N, \quad (4.3)$$

where the  $X_j$ 's are left invariant on  $(\mathbb{R}^N, \circ)$  and

$$X_j(0) = \frac{\partial}{\partial x_j^{(N_1)}}, \quad j = 1, \dots, N_1. \quad (4.4)$$

Then  $\mathbb{G} = (\mathbb{R}^N, \circ, \delta_\lambda)$  is a *Carnot group* whose *homogeneous dimension*  $Q_0$  is the natural number

$$Q_0 := N_1 + 2N_2 + mN_m. \quad (4.5)$$

The vector fields  $X_1, \dots, X_{N_1}$  are the *generators* of  $\mathbb{G}$ ,

$$\Delta_{\mathbb{G}} := \sum_{j=1}^{N_1} X_j^2 \quad (4.6)$$

is the *canonical sub-Laplacian* on  $\mathbb{G}$  and the parabolic operator

$$\mathcal{L} = \Delta_{\mathbb{G}} - \partial_t \quad \text{in } \mathbb{R}^{N+1} \quad (4.7)$$

is called the *canonical heat operator* on  $\mathbb{G}$ . Obviously  $\mathcal{L}$  can be written as in (3.25). Moreover, if we define

$$\mathbb{L} = (\mathbb{R}^{N+1}, \circ, d_\lambda) \quad (4.8)$$

with  $d_\lambda(x, t) = (D_\lambda x, \lambda^2 t)$  and the composition law  $\circ$  given by

$$(x, t) \circ (x', t') = (x \circ x', t + t'), \quad (4.9)$$

then  $\mathbb{L}$  is a homogeneous group, and the operator  $\mathcal{L}$  in (4.7) satisfies condition (H1)\*. We explicitly remark that the homogeneous dimension of  $\mathbb{L}$  is  $Q := Q_0 + 2$ .

In [1, page 70], it is proved that  $\mathcal{L}$  also satisfies (H2).

*Remark 4.2.* The stationary part of the operator  $\mathcal{L}$  in (4.7) is the sub-Laplacian  $\Delta_{\mathbb{G}}$ . For this kind of operator, the polynomial Liouville theorem in Theorem 2.8 was first proved in [10, Theorem 1.4].

*Example 4.3* (*B-Kolmogorov operators*). Let us split  $\mathbb{R}^N$  as follows:

$$\mathbb{R}^N = \mathbb{R}^p \times \mathbb{R}^r \quad (4.10)$$

and denote by  $x = (x^{(p)}, x^{(r)})$  its points. Let  $B$  be an  $N \times N$  real matrix taking the following block form:

$$B = \begin{pmatrix} 0 & 0 & 0 & \cdots & 0 \\ B_1 & 0 & 0 & \cdots & 0 \\ 0 & B_2 & \cdots & \cdots & \cdots \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & B_k & 0 \end{pmatrix}, \quad (4.11)$$

where  $B_j$  is an  $r_j \times r_{j-1}$  matrix with rank  $r_j$ , and  $r_0 = p \geq r_1 \geq \cdots \geq r_k \geq 1$ ,  $r_0 + r_1 + \cdots + r_k = N$ . Denote

$$E(t) = \exp(-tB) \quad (4.12)$$

and introduce in  $\mathbb{R}^{N+1}$  the following composition law

$$(x, t) \circ (y, \tau) := (y + E(\tau)x, t + \tau). \quad (4.13)$$

The triplet

$$\mathbb{K} = (\mathbb{R}^{N+1}, \circ, d_\lambda) \quad (4.14)$$

is a homogeneous Lie group with respect to the dilations

$$d_\lambda(x, t) = d_\lambda(x^{(p)}, x^{(r_1)}, \dots, x^{(r_k)}, t) = (\lambda x^{(p)}, \lambda^3 x^{(r_1)}, \dots, \lambda^{2k+1} x^{(r_k)}, \lambda^2 t) \quad (4.15)$$

(see [11]). The homogeneous dimension of  $\mathbb{K}$  is

$$Q = p + 3r_1 + \cdots + (2k+1)r_k + 2. \quad (4.16)$$

We call  $\mathbb{K}$  a *B-Kolmogorov-type group*.

Let us now consider the operator

$$\mathcal{H} = \Delta_{\mathbb{R}^p} + \langle Bx, D \rangle - \partial_t, \quad (4.17)$$

where  $\Delta_{\mathbb{R}^p}$  denotes the usual Laplace operator in  $\mathbb{R}^p$ ,  $\langle \cdot, \cdot \rangle$  is the inner product in  $\mathbb{R}^N$ , and  $D = (\partial_{x_1}, \dots, \partial_{x_N})$ . In this case, we have

$$Y = \langle Bx, D \rangle - \partial_t. \quad (4.18)$$

The operator  $\mathcal{H}$  satisfies (H1)\* and (H2), and it is left translation invariant on  $\mathbb{K}$  (see [1, 11]).

*Remark 4.4.* The matrix  $E(t)$  in (4.13) takes the following triangular form:

$$E(t) = \begin{pmatrix} I_p & 0 \\ E_1(t) & I_r \end{pmatrix}, \quad (4.19)$$

where  $I_p$  and  $I_r$  are the identity matrix in  $\mathbb{R}^p$  and  $\mathbb{R}^r$ , respectively. Then, the composition law in  $\mathbb{K}$  has the following structure:

$$(x^{(p)}, x^{(r)}, t) \circ (y^{(p)}, y^{(r)}, \tau) = (x^{(p)} + y^{(p)}, x^{(r)} + y^{(r)} + E_1(\tau)x^{(p)}, t + \tau). \quad (4.20)$$

*Remark 4.5.* The stationary part of  $\mathcal{H}$ ,

$$\mathcal{H}_0 = \Delta_{\mathbb{R}_p} + \langle Bx, D \rangle, \quad (4.21)$$

is contained in the class of degenerate Ornstein-Uhlenbeck operators studied by Priola and Zabczyk [12], where a Liouville theorem for *bounded* solutions is proved.

*Example 4.6* (sub-Kolmogorov operators). Let  $\mathbb{G} = (\mathbb{R}^p \times \mathbb{R}^q, \circ, d_\lambda^{(1)})$  be a Carnot group with first layer  $\mathbb{R}^p$  and let  $\mathbb{K} = (\mathbb{R}^p \times \mathbb{R}^r \times \mathbb{R}, \circ, d_\lambda^{(2)})$  be a Kolmogorov group. Let  $\mathbb{L} = (\mathbb{R}^{N+1}, \circ, d_\lambda)$ ,  $N = p + q + r$ ,

$$\mathbb{L} = \mathbb{G} \triangle \mathbb{K} \quad (4.22)$$

be the link of  $\mathbb{G}$  and  $\mathbb{K}$  (see [13, Section 5.2]).

Then, if  $Y$  is a derivative operator transverse to  $\mathbb{G}$  (see [13, Definition 4.5]), and  $X_1, \dots, X_p$  are the generators of  $\mathbb{G}$ , the operator

$$\mathcal{L} = \sum_{j=1}^p X_j^2 + Y, \quad \text{in } \mathbb{R}^{N+1}, \quad (4.23)$$

satisfies (H1)\* and (H2).

*Example 4.7* (a nontranslations invariant operator). The operator

$$\mathcal{L} = \partial_{x_1}^2 + x_1^{2m+1} \partial_{x_2} - \partial_t \quad \text{in } \mathbb{R}^3 \quad (4.24)$$

$m \in \mathbb{N}$ , satisfies hypotheses (H1) and (H2). The relevant dilation group is given by

$$d_\lambda(x_1, x_2, t) = (\lambda x_1, \lambda^{2m+3} x_2, \lambda^2 t). \quad (4.25)$$

Finally, it is easy to recognize that there is no Lie group structure in  $\mathbb{R}^3$  leaving left translation invariant the operator  $\mathcal{L}$ .

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Alessia Elisabetta Kogoj: Dipartimento di Matematica, Università di Bologna,  
Piazza di Porta San Donato 5, 40126 Bologna, Italy  
Email address: kogoj@dm.unibo.it

Ermanno Lanconelli: Dipartimento di Matematica, Università di Bologna,  
Piazza di Porta San Donato 5, 40126 Bologna, Italy  
Email address: lanconel@dm.unibo.it



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**Shouyang Wang**, Academy of Mathematics and Systems Science, Chinese Academy of Sciences, Beijing 100190, China; [sywang@amss.ac.cn](mailto:sywang@amss.ac.cn)

**K. K. Lai**, Department of Management Sciences, City University of Hong Kong, Tat Chee Avenue, Kowloon, Hong Kong; [mskkklai@cityu.edu.hk](mailto:mskkklai@cityu.edu.hk)