

MAXIMUM NORM ANALYSIS OF AN OVERLAPPING NONMATCHING GRIDS METHOD FOR THE OBSTACLE PROBLEM

M. BOULBRACHENE AND S. SAADI

Received 11 July 2005; Revised 24 September 2005; Accepted 26 September 2005

We provide a maximum norm analysis of an overlapping Schwarz method on nonmatching grids for second-order elliptic obstacle problem. We consider a domain which is the union of two overlapping subdomains where each subdomain has its own independently generated grid. The grid points on the subdomain boundaries need not match the grid points from the other subdomain. Under a discrete maximum principle, we show that the discretization on each subdomain converges quasi-optimally in the L^∞ norm.

Copyright © 2006 M. Boulbrachene and S. Saadi. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

1. Introduction

The Schwarz alternating method can be used to solve elliptic boundary value problems on domains which consists of two or more overlapping subdomains. The solution is approximated by an infinite sequence of functions which results from solving a sequence of elliptic boundary value problems in each of the subdomain.

Extensive analysis of Schwarz alternating method for continuous obstacle problem can be found in [8, 9]. For convergence of discrete Schwarz algorithms of either additive or multiplicative types, see for example, [1, 6, 7, 11].

In this paper, we are interested in the error analysis in the maximum norm for the obstacle problem in the context of overlapping nonmatching grids: we consider a domain Ω which is the union of two overlapping subdomains where each subdomain has its own triangulation. This kind of discretizations is very interesting as they can be applied to solving many practical problems which cannot be handled by global discretizations. They are earning particular attention of computational experts and engineers as they allow the choice of different mesh sizes and different orders of approximate polynomials in different subdomains according to the different properties of the solution and different requirements of the practical problems.

2 Obstacle problem

To prove the main result, we develop an approach which combines a geometrical convergence result due to Lions [9] and a lemma which consists of estimating the error in the L^∞ norm between the continuous and discrete Schwarz iterates. The convergence order is then derived making use of standard finite element L^∞ -error estimate for elliptic variational inequalities.

Quite a few works on maximum error analysis of overlapping nonmatching grid methods are known in the literature (cf., e.g., [2, 3, 10]). However, to the best of our knowledge, this is the first paper that provides an L^∞ -error analysis for overlapping nonmatching grids for variational inequalities.

Now we give an outline of the paper. In Section 2. we state the continuous alternating Schwarz sequences for the obstacle problem, and define their respective finite element counterparts in the context of nonmatching overlapping grids. Section 3. is devoted to the L^∞ -error analysis of the method.

2. The Schwarz method for the obstacle problem

We begin by laying down some definitions and classical results related to elliptic variational inequalities.

2.1. Elliptic obstacle problem. Let Ω be a convex domain in \mathbb{R}^2 with sufficiently smooth boundary $\partial\Omega$. We consider the bilinear form

$$a(u, v) = \int_{\Omega} (\nabla u \cdot \nabla v) dx, \quad (2.1)$$

the linear form

$$(f, v) = \int_{\Omega} f(x) \cdot v(x) dx, \quad (2.2)$$

the right-hand side

$$f \in L^\infty(\Omega), \quad (2.3)$$

the obstacle

$$\psi \in W^{2,\infty}(\Omega) \quad \text{such that } \psi \geq 0 \text{ on } \partial\Omega, \quad (2.4)$$

and the nonempty convex set

$$K_g = \{v \in H^1(\Omega) : v = g \text{ on } \partial\Omega, v \leq \psi \text{ on } \Omega\}, \quad (2.5)$$

where g is a regular function defined on $\partial\Omega$.

We consider the obstacle problem: find $u \in K_g$ such that

$$a(u, v - u) \geq (f, v - u), \quad \forall v \in K_g. \quad (2.6)$$

Let V_h be the space of finite elements consisting of continuous piecewise linear functions. The discrete counterpart of (2.6) consists of finding $u_h \in K_{gh}$ such that

$$a(u_h, v - u_h) \geq (f, v - u_h) \quad \forall v \in K_{gh}, \quad (2.7)$$

where

$$K_{gh} = \{v \in V_h : v = \pi_h g \text{ on } \partial\Omega, v \leq r_h \psi \text{ on } \Omega\} \quad (2.8)$$

π_h is an interpolation operator on $\partial\Omega$, and r_h is the usual finite element restriction operator on Ω .

The lemma below establishes a monotonicity property of the solution of (2.6) with respect to the obstacle and the boundary condition.

LEMMA 2.1. *Let $(\psi, g); (\tilde{\psi}, \tilde{g})$ be a pair of data, and $u = \sigma(\psi, g); \tilde{u} = \sigma(\tilde{\psi}, \tilde{g})$ the corresponding solutions to (2.6). If $\psi \geq \tilde{\psi}$ and $g \geq \tilde{g}$, then $\sigma(\psi, g) \geq \sigma(\tilde{\psi}, \tilde{g})$.*

Proof. Let $v = \min(0, u - \tilde{u})$. In the region where v is negative ($v < 0$), we have

$$u < \tilde{u} \leq \tilde{\psi} \leq \psi \quad (2.9)$$

which means that the obstacle is not active for u . So, for that v , we have

$$a(u, v) = (f, v), \quad (2.10)$$

$$\tilde{u} + v \leq \tilde{\psi} \quad (2.11)$$

so

$$a(\tilde{u}, v) \geq (f, v). \quad (2.12)$$

Subtracting (2.10) and (2.12) from each other, we obtain

$$a(\tilde{u} - u, v) \geq 0. \quad (2.13)$$

But,

$$a(v, v) = a(u - \tilde{u}, v) = -a(\tilde{u} - u, v) \leq 0 \quad (2.14)$$

so

$$v = 0 \quad (2.15)$$

and consequently,

$$u \geq \tilde{u} \quad (2.16)$$

which completes the proof. \square

The proof for the discrete case is similar.

4 Obstacle problem

PROPOSITION 2.2. *Under the notations and conditions of the preceding lemma, we have*

$$\|u - \tilde{u}\|_{L^\infty(\Omega)} \leq \|\psi - \tilde{\psi}\|_{L^\infty(\Omega)} + \|g - \tilde{g}\|_{L^\infty(\partial\Omega)}. \quad (2.17)$$

Proof. Setting

$$\Phi = \|\psi - \tilde{\psi}\|_{L^\infty(\Omega)} + \|g - \tilde{g}\|_{L^\infty(\partial\Omega)} \quad (2.18)$$

we have

$$\begin{aligned} \psi &\leq \tilde{\psi} + \psi - \tilde{\psi} \leq \tilde{\psi} + |\psi - \tilde{\psi}| \leq \tilde{\psi} + \|\psi - \tilde{\psi}\|_{L^\infty(\Omega)} \\ &\leq \tilde{\psi} + \|\psi - \tilde{\psi}\|_{L^\infty(\Omega)} + \|g - \tilde{g}\|_{L^\infty(\partial\Omega)} \end{aligned} \quad (2.19)$$

hence

$$\psi \leq \tilde{\psi} + \Phi. \quad (2.20)$$

On the other hand, we have

$$\begin{aligned} g &\leq \tilde{g} + g - \tilde{g} \leq \tilde{g} + |g - \tilde{g}| \leq \tilde{g} + \|g - \tilde{g}\|_{L^\infty(\partial\Omega)} \\ &\leq \tilde{g} + \|g - \tilde{g}\|_{L^\infty(\partial\Omega)} + \|\psi - \tilde{\psi}\|_{L^\infty(\Omega)} \end{aligned} \quad (2.21)$$

so

$$g \leq \tilde{g} + \Phi. \quad (2.22)$$

Now, making use of Lemma 2.1, we obtain

$$\sigma(\psi, g) \leq \sigma(\tilde{\psi} + \Phi, \tilde{g} + \Phi) = \sigma(\tilde{\psi}, \tilde{g}) + \Phi \quad (2.23)$$

or

$$\sigma(\psi, g) - \sigma(\tilde{\psi}, \tilde{g}) \leq \Phi. \quad (2.24)$$

Similarly, interchanging the roles of the couples (ψ, g) and $(\tilde{\psi}, \tilde{g})$, we obtain

$$\sigma(\tilde{\psi}, \tilde{g}) - \sigma(\psi, g) \leq \Phi. \quad (2.25)$$

The proof for the discrete case is similar. □

Remark 2.3. If $\psi = \tilde{\psi}$, then (2.17) becomes

$$\|u - \tilde{u}\|_{L^\infty(\Omega)} \leq \|g - \tilde{g}\|_{L^\infty(\partial\Omega)}. \quad (2.26)$$

THEOREM 2.4 (cf. [5]). *Under conditions (2.3) and (2.4), there exists a constant C independent of h such that*

$$\|u - u_h\|_{L^\infty(\Omega)} \leq Ch^2 |\ln h|^2. \quad (2.27)$$

2.2. The continuous Schwarz sequences. Consider the model obstacle problem: find $u \in K_0$ ($g = 0$) such that

$$a(u, v - u) \geq (f, v - u) \quad \forall v \in K_0. \quad (2.28)$$

We decompose Ω into two overlapping polygonal subdomains Ω_1 and Ω_2 such that

$$\Omega = \Omega_1 \cup \Omega_2 \quad (2.29)$$

and u satisfies the local regularity condition

$$u/\Omega_i \in W^{2,p}(\Omega_i); \quad 2 \leq p < \infty. \quad (2.30)$$

We denote by $\partial\Omega_i$ the boundary of Ω_i , and $\Gamma_i = \partial\Omega_i \cap \Omega_j$. The intersection of $\bar{\Gamma}_i$ and $\bar{\Gamma}_j$; $i \neq j$ is assumed to be empty.

Choosing $u^0 = \psi$, we respectively define the alternating Schwarz sequences (u_1^{n+1}) on Ω_1 such that $u_1^{n+1} \in K$ solves

$$\begin{aligned} a_1(u_1^{n+1}, v - u_1^{n+1}) &\geq (f_1, v - u_1^n) \quad \forall v \in K, \\ u_1^{n+1} &= u_2^n \quad \text{on } \Gamma_1, \quad v = u_2^n \quad \text{on } \Gamma_1 \end{aligned} \quad (2.31)$$

and (u_2^{n+1}) on Ω_2 such that $u_2^{n+1} \in K$ solves

$$\begin{aligned} a_2(u_2^{n+1}, v - u_2^{n+1}) &\geq (f_2, v - u_2^{n+1}) \quad \forall v \in K, \\ u_2^{n+1} &= u_1^{n+1} \quad \text{on } \Gamma_2; \quad v = u_1^{n+1} \quad \text{on } \Gamma_2, \end{aligned} \quad (2.32)$$

where

$$f_i = f/\Omega_i, \quad a_i(u, v) = \int_{\Omega_i} (\nabla u \nabla v) dx. \quad (2.33)$$

The following geometrical convergence is due to Lions [9].

2.3. Geometrical convergence.

THEOREM 2.5 (cf. [9]). *The sequences (u_1^{n+1}) ; (u_2^{n+1}) ; $n \geq 0$ produced by the Schwarz alternating method converge geometrically to the solution u of the obstacle problem (2.28). More precisely, there exist two constants $k_1, k_2 \in (0, 1)$ such that for all $n \geq 0$,*

$$\begin{aligned} \|u_1 - u_1^{n+1}\|_{L^\infty(\Omega_1)} &\leq k_1^n k_2^n \|u^0 - u\|_{L^\infty(\Gamma_1)}, \\ \|u_2 - u_2^{n+1}\|_{L^\infty(\Omega_2)} &\leq k_1^{n+1} k_2^n \|u^0 - u\|_{L^\infty(\Gamma_2)}, \end{aligned} \quad (2.34)$$

where $u_i = u/\Omega_i$, $i = 1, 2$.

2.4. The discretization. For $i = 1, 2$, let τ^{h_i} be a standard regular and quasi-uniform finite element triangulation in Ω_i ; h_i , being the meshsize. We assume that the two triangulations are mutually independent on $\Omega_1 \cap \Omega_2$ in the sense that a triangle belonging to one triangulation does not necessarily belong to the other.

6 Obstacle problem

Let $V_{h_i} = V_{h_i}(\Omega_i)$ be the space of continuous piecewise linear functions on τ^{h_i} which vanish on $\partial\Omega \cap \partial\Omega_i$. For $w \in C(\bar{\Gamma}_i)$ we define

$$V_{h_i}^{(w)} = \{v \in V_{h_i} : v = 0 \text{ on } \partial\Omega_i \cap \partial\Omega; v = \pi_{h_i}(w) \text{ on } \Gamma_i\}, \quad (2.35)$$

where π_{h_i} denotes the interpolation operator on Γ_i .

We also assume that the respective matrices resulting from the discretizations of problems (2.31) and (2.32), are M -matrices. (see [4]).

We now define the discrete counterparts of the continuous Schwarz sequences defined in (2.31) and (2.32), respectively by: $u_{1h}^{n+1} \in V_{h_1}^{(u_{2h}^n)}$ such that

$$\begin{aligned} a_1(u_{1h}^{n+1}, v - u_{1h}^{n+1}) &\geq (f_1, v - u_{1h}^{n+1}) \quad \forall v \in V_{h_1}^{(u_{2h}^n)}, \\ u_{1h}^{n+1} &\leq r_h, \quad v \leq r_h \psi \end{aligned} \quad (2.36)$$

and $u_{2h}^{n+1} \in V_{h_2}^{(u_{1h}^{n+1})}$ such that

$$\begin{aligned} a_2(u_{2h}^{n+1}, v - u_{2h}^{n+1}) &\geq (f_2, v - u_{2h}^{n+1}) \quad \forall v \in V_{h_2}^{(u_{1h}^{n+1})} \\ u_{2h}^{n+1} &\leq r_h, \quad v \leq r_h \psi. \end{aligned} \quad (2.37)$$

Remark 2.6. As the two meshes τ^{h_1} and τ^{h_2} are independent over the overlapping subdomains, it is impossible to formulate a global approximate problem which would be the direct discrete counterpart of problem (2.28).

3. L^∞ -error analysis

This section is devoted to the proof of the main result of the present paper. To that end we begin by introducing two discrete auxiliary sequences and prove a fundamental lemma.

3.1. Definition of two auxiliary sequences. For $\omega_{ih}^0 = u_{ih}^0 = r_h \psi$; $i = 1, 2$, we define the sequences (ω_{ih}^{n+1}) such that $\omega_{1h}^{n+1} \in V_{h_1}^{(u_{2h}^n)}$ solves

$$\begin{aligned} a_1(\omega_{1h}^{n+1}, v - \omega_{1h}^{n+1}) &\geq (f_1, v - \omega_{1h}^{n+1}) \quad \forall v \in V_{h_1}^{(u_{2h}^n)}, \\ \omega_{1h}^{n+1} &\leq r_h \psi, \quad v \leq r_h \psi \end{aligned} \quad (3.1)$$

and (ω_{2h}^{n+1}) such that $\omega_{2h}^{n+1} \in V_{h_2}^{(u_{1h}^{n+1})}$ solves

$$\begin{aligned} a_2(\omega_{2h}^{n+1}, v - \omega_{2h}^{n+1}) &\geq (f_2, v - \omega_{2h}^{n+1}) \quad \forall v \in V_{h_2}^{(u_{1h}^{n+1})}, \\ \omega_{2h}^{n+1} &\leq r_h \psi, \quad v \leq r_h \psi. \end{aligned} \quad (3.2)$$

Note that ω_{ih}^{n+1} is the finite element approximation of u_i^{n+1} defined in (2.31), (2.32).

Notation 1. From now on, we will adopt the following notations:

$$\begin{aligned} |\cdot|_1 &= \|\cdot\|_{L^\infty(\Gamma_1)}, & |\cdot|_2 &= \|\cdot\|_{L^\infty(\Gamma_2)}, \\ \|\cdot\|_1 &= \|\cdot\|_{L^\infty(\Omega_1)}, & \|\cdot\|_2 &= \|\cdot\|_{L^\infty(\Omega_2)}, \\ \pi_{h_1} &= \pi_{h_2} = \pi_h. \end{aligned} \quad (3.3)$$

The following lemma will play a key role in proving the main result of this paper.

LEMMA 3.1.

$$\begin{aligned} \|u_1^{n+1} - u_{1h}^{n+1}\|_1 &\leq \sum_{p=1}^{n+1} \|u_1^p - \omega_{1h}^p\|_1 + \sum_{p=0}^n \|u_2^p - \omega_{2h}^p\|_2, \\ \|u_2^{n+1} - u_{2h}^{n+1}\|_2 &\leq \sum_{p=0}^{n+1} \|u_2^p - \omega_{2h}^p\|_2 + \sum_{p=1}^{n+1} \|u_1^p - \omega_{1h}^p\|_1. \end{aligned} \quad (3.4)$$

Proof. The proof will be carried out by induction. In order to simplify the notations, we will take $h_1 = h_2 = h$.

Indeed, for $n = 1$, using the discrete version of Remark 2.3, we get

$$\begin{aligned} \|u_1^1 - u_{1h}^1\|_1 &\leq \|u_1^1 - \omega_{1h}^1\|_1 + \|\omega_{1h}^1 - u_{1h}^1\|_1 \leq \|u_1^1 - \omega_{1h}^1\|_1 + |\pi_h u_2^0 - \pi_h u_{2h}^0|_1 \\ &\leq \|u_1^1 - \omega_{1h}^1\|_1 + |u_2^0 - u_{2h}^0|_1 \leq \|u_1^1 - \omega_{1h}^1\|_1 + \|u_2^0 - u_{2h}^0\|_2, \\ \|u_2^1 - u_{2h}^1\|_2 &\leq \|u_2^1 - \omega_{2h}^1\|_2 + \|\omega_{2h}^1 - u_{2h}^1\|_2 \leq \|u_2^1 - \omega_{2h}^1\|_2 + |\pi_h u_1^1 - \pi_h u_{1h}^1|_2 \\ &\leq \|u_2^1 - \omega_{2h}^1\|_2 + |u_1^1 - u_{1h}^1|_2 \leq \|u_2^1 - \omega_{2h}^1\|_2 + \|u_1^1 - u_{1h}^1\|_1 \\ &\leq \|u_2^1 - \omega_{2h}^1\|_2 + \|u_1^1 - \omega_{1h}^1\|_1 + \|u_2^0 - u_{2h}^0\|_2 \end{aligned} \quad (3.5)$$

so

$$\begin{aligned} \|u_1^1 - u_{1h}^1\|_1 &\leq \sum_{p=1}^1 \|u_1^p - \omega_{1h}^p\|_1 + \sum_{p=0}^0 \|u_2^p - \omega_{2h}^p\|_2, \\ \|u_2^1 - u_{2h}^1\|_2 &\leq \sum_{p=0}^1 \|u_2^p - \omega_{2h}^p\|_2 + \sum_{p=1}^1 \|u_1^p - \omega_{1h}^p\|_1. \end{aligned} \quad (3.6)$$

For $n = 2$, using the discrete version of Remark 2.3, we have

$$\begin{aligned} \|u_1^2 - u_{1h}^2\|_1 &\leq \|u_1^2 - \omega_{1h}^2\|_1 + \|\omega_{1h}^2 - u_{1h}^2\|_1 \leq \|u_1^2 - \omega_{1h}^2\|_1 + |\pi_h u_2^1 - \pi_h u_{2h}^1|_1 \\ &\leq \|u_1^2 - \omega_{1h}^2\|_1 + |u_2^1 - u_{2h}^1|_1 \leq \|u_1^2 - \omega_{1h}^2\|_1 + \|u_2^1 - u_{2h}^1\|_2 \\ &\leq \|u_1^2 - \omega_{1h}^2\|_1 + \|u_2^1 - \omega_{2h}^1\|_2 + \|u_1^1 - \omega_{1h}^1\|_1 + \|u_2^0 - u_{2h}^0\|_2, \\ \|u_2^2 - u_{2h}^2\|_2 &\leq \|u_2^2 - \omega_{2h}^2\|_2 + \|\omega_{2h}^2 - u_{2h}^2\|_2 \leq \|u_2^2 - \omega_{2h}^2\|_2 + |\pi_h u_1^2 - \pi_h u_{1h}^2|_2 \\ &\leq \|u_2^2 - \omega_{2h}^2\|_2 + |u_1^2 - u_{1h}^2|_2 \leq \|u_2^2 - \omega_{2h}^2\|_2 + \|u_1^2 - u_{1h}^2\|_1 \\ &\leq \|u_2^2 - \omega_{2h}^2\|_2 + \|u_1^2 - \omega_{1h}^2\|_1 + \|u_2^1 - \omega_{2h}^1\|_2 + \|u_1^1 - \omega_{1h}^1\|_1 + \|u_2^0 - u_{2h}^0\|_2. \end{aligned} \quad (3.7)$$

8 Obstacle problem

So

$$\begin{aligned} \|u_1^2 - u_{1h}^2\|_1 &\leq \sum_{p=1}^2 \|u_1^p - \omega_{1h}^p\|_1 + \sum_{p=0}^1 \|u_2^p - \omega_{2h}^p\|_2 \\ \|u_2^2 - u_{2h}^2\|_1 &\leq \sum_{p=0}^2 \|u_2^p - \omega_{2h}^p\|_2 + \sum_{p=1}^2 \|u_1^p - \omega_{1h}^p\|_1. \end{aligned} \quad (3.8)$$

Let us now suppose that

$$\|u_2^n - u_{2h}^n\|_2 \leq \sum_{p=0}^n \|u_2^p - \omega_{2h}^p\|_2 + \sum_{p=1}^n \|u_1^p - \omega_{1h}^p\|_1. \quad (3.9)$$

Then, using the discrete version of Remark 2.3 again, we get

$$\begin{aligned} \|u_1^{n+1} - u_{1h}^{n+1}\|_1 &\leq \|u_1^{n+1} - \omega_{1h}^{n+1}\|_1 + \|\omega_{1h}^{n+1} - u_{1h}^{n+1}\|_1 \leq \|u_1^{n+1} - \omega_{1h}^{n+1}\|_1 + \|\pi_h u_2^n - \pi_h u_{2h}^n\|_1 \\ &\leq \|u_1^{n+1} - \omega_{1h}^{n+1}\|_1 + \|u_2^n - u_{2h}^n\|_1 \leq \|u_1^{n+1} - \omega_{1h}^{n+1}\|_1 + \|u_2^n - u_{2h}^n\|_2 \\ &\leq \|u_1^{n+1} - \omega_{1h}^{n+1}\|_1 + \sum_{p=0}^n \|u_2^p - \omega_{2h}^p\|_2 + \sum_{p=1}^n \|u_1^p - \omega_{1h}^p\|_1 \end{aligned} \quad (3.10)$$

and consequently,

$$\|u_1^{n+1} - u_{1h}^{n+1}\|_1 \leq \sum_{p=1}^{n+1} \|u_1^p - \omega_{1h}^p\|_1 + \sum_{p=0}^n \|u_2^p - \omega_{2h}^p\|_2. \quad (3.11)$$

Likewise, using the above estimate, we get

$$\begin{aligned} \|u_2^{n+1} - u_{2h}^{n+1}\|_2 &\leq \|u_2^{n+1} - \omega_{2h}^{n+1}\|_2 + \|\omega_{2h}^{n+1} - u_{2h}^{n+1}\|_2 \leq \|u_2^{n+1} - \omega_{2h}^{n+1}\|_2 \\ &\quad + \|\pi_h u_1^{n+1} - \pi_h u_{1h}^{n+1}\|_2 \leq \|u_2^{n+1} - \omega_{2h}^{n+1}\|_2 + \|u_1^{n+1} - u_{1h}^{n+1}\|_2 \\ &\leq \|u_2^{n+1} - \omega_{2h}^{n+1}\|_2 + \|u_1^{n+1} - u_{1h}^{n+1}\|_1 \leq \|u_2^{n+1} - \omega_{2h}^{n+1}\|_2 \\ &\quad + \sum_{p=1}^{n+1} \|u_1^p - \omega_{1h}^p\|_1 + \sum_{p=0}^n \|u_2^p - \omega_{2h}^p\|_2. \end{aligned} \quad (3.12)$$

Hence,

$$\|u_2^{n+1} - u_{2h}^{n+1}\|_2 \leq \sum_{p=0}^{n+1} \|u_2^p - \omega_{2h}^p\|_2 + \sum_{p=1}^{n+1} \|u_1^p - \omega_{1h}^p\|_1. \quad (3.13)$$

□

3.2. L^∞ -error estimate.

THEOREM 3.2. *Let $h = \max(h_1, h_2)$. Then, there exists a constant C independent of both h and n such that*

$$\|u_i - u_{ih}^{n+1}\|_{L^\infty(\Omega_i)} \leq Ch^2 |\log h|^3; \quad i = 1, 2. \quad (3.14)$$

Proof. Let us give the proof for $i = 1$. The case $i = 2$ is similar.

Indeed, let $\kappa = \max(k_1, k_2)$, then

$$\begin{aligned}
 \|u_1 - u_{1h}^{n+1}\|_1 &\leq \|u_1 - u_{1h}^{n+1}\|_1 + \|u_{1h}^{n+1} - u_{1h}^{n+1}\|_1 \\
 &\leq \kappa^{2n} \|u^0 - u\|_1 + \|u_{1h}^{n+1} - u_{1h}^{n+1}\|_1 \\
 &\leq \kappa^{2n} \|u^0 - u\|_1 + \sum_{p=1}^{n+1} \|u_1^p - \omega_{1h}^p\|_1 + \sum_{p=0}^n \|u_2^p - \omega_{2h}^p\|_2 \\
 &\leq \kappa^{2n} \|u^0 - u\|_1 + 2(n+1)Ch^2 |\log h|^2,
 \end{aligned} \tag{3.15}$$

where we have used Theorem 2.5, Lemma 3.1, and Theorem 2.4, respectively.

Now setting

$$\kappa^{2n} \leq h^2, \tag{3.16}$$

we obtain

$$\|u_1 - u_{1h}^{n+1}\|_1 \leq Ch^2 |\log h|^3, \tag{3.17}$$

which is the desired error estimate. \square

3.3. The equation case. The analysis developed above remains valid for the equation problem ($\psi = \infty$). Consequently, the error estimate (3.14) becomes

$$\|u_i - u_{ih}^{n+1}\|_{L^\infty(\Omega_i)} \leq Ch^2 |\log h|^2; \quad i = 1, 2. \tag{3.18}$$

Remark 3.3. The reduction constant k can be quite close to one if the overlapping region is thin. Therefore, to ensure a good accuracy of the approximation, this region must be large enough.

References

- [1] L. Badea, *On the Schwarz alternating method with more than two subdomains for nonlinear monotone problems*, SIAM Journal on Numerical Analysis **28** (1991), no. 1, 179–204.
- [2] M. Boulbrachene, Ph. Cortey-Dumont, and J.-C. Miellou, *Mixing finite elements and finite differences in a subdomain method*, First International Symposium on Domain Decomposition Methods for Partial Differential Equations (Paris, 1987), SIAM, Philadelphia, 1988, pp. 198–216.
- [3] X.-C. Cai, T. P. Mathew, and M. V. Sarkis, *Maximum norm analysis of overlapping nonmatching grid discretizations of elliptic equations*, SIAM Journal on Numerical Analysis **37** (2000), no. 5, 1709–1728.
- [4] P. G. Ciarlet and P.-A. Raviart, *Maximum principle and uniform convergence for the finite element method*, Computer Methods in Applied Mechanics and Engineering **2** (1973), no. 1, 17–31.
- [5] Ph. Cortey-Dumont, *On finite element approximation in the L^∞ -norm of variational inequalities*, Numerische Mathematik **47** (1985), no. 1, 45–57.
- [6] Yu. A. Kuznetsov, P. Neittaanmäki, and P. Tarvainen, *Overlapping domain decomposition methods for the obstacle problem*, Domain Decomposition Methods in Science and Engineering (Como, 1992) (A. Quarteroni, J. Périaux, Yu. A. Kuznetsov, and O. B. Widlund, eds.), Contemp. Math., vol. 157, American Mathematical Society, Rhode Island, 1994, pp. 271–277.

10 Obstacle problem

- [7] ———, *Schwarz methods for obstacle problems with convection-diffusion operators*, Domain Decomposition Methods in Scientific and Engineering Computing (University Park, Pa, 1993) (D. E. Keyes and J. Xu, eds.), Contemp. Math., vol. 180, American Mathematical Society, Rhode Island, 1994, pp. 251–256.
- [8] P.-L. Lions, *On the Schwarz alternating method. I*, First International Symposium on Domain Decomposition Methods for Partial Differential Equations (Paris, 1987), SIAM, Philadelphia, 1988, pp. 1–42.
- [9] ———, *On the Schwarz alternating method. II. Stochastic interpretation and order properties*, Domain Decomposition Methods (Los Angeles, Calif, 1988), SIAM, Philadelphia, 1989, pp. 47–70.
- [10] T. P. Mathew and G. Russo, *Maximum norm stability of difference schemes for parabolic equations on overset nonmatching space-time grids*, Mathematics of Computation **72** (2003), no. 242, 619–656.
- [11] J. Zeng and S. Zhou, *On monotone and geometric convergence of Schwarz methods for two-sided obstacle problems*, SIAM Journal on Numerical Analysis **35** (1998), no. 2, 600–616.

M. Boulbrachene: Department of Mathematics, College of Science, Sultan Qaboos University,
P.O. Box 36, Muscat 123, Oman
E-mail address: boulbrac@squ.edu.om

S. Saadi: Departement de Mathematiques, Faculte des Sciences, Universite Badji Mokhtar,
BP 12 Annaba, Algerie
E-mail address: signor_2000@yahoo.fr

Special Issue on Modeling Experimental Nonlinear Dynamics and Chaotic Scenarios

Call for Papers

Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from “Qualitative Theory of Differential Equations,” allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the *Mathematical Problems in Engineering* aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

Authors should follow the Mathematical Problems in Engineering manuscript format described at <http://www.hindawi.com/journals/mpe/>. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/> according to the following timetable:

| | |
|------------------------|------------------|
| Manuscript Due | December 1, 2008 |
| First Round of Reviews | March 1, 2009 |
| Publication Date | June 1, 2009 |

Guest Editors

José Roberto Castilho Piqueira, Telecommunication and Control Engineering Department, Polytechnic School, The University of São Paulo, 05508-970 São Paulo, Brazil; piqueira@lac.usp.br

Elbert E. Neher Macau, Laboratório Associado de Matemática Aplicada e Computação (LAC), Instituto Nacional de Pesquisas Espaciais (INPE), São José dos Campos, 12227-010 São Paulo, Brazil ; elbert@lac.inpe.br

Celso Grebogi, Center for Applied Dynamics Research, King's College, University of Aberdeen, Aberdeen AB24 3UE, UK; grebogi@abdn.ac.uk